Submodular Functions, Optimization, and Applications to Machine Learning — Spring Quarter, Lecture 4 —

http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563\_spring\_2018/

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#### April 4th, 2018



## Cumulative Outstanding Reading

#### • Read chapter 1 from Fujishige's book.

Logistics

## Announcements, Assignments, and Reminders

• Homework 1 out, due Monday, 4/9/2018 11:59pm electronically via our assignment dropbox

(https://canvas.uw.edu/courses/1216339/assignments).

If you have any questions about anything, please ask then via our discussion board

(https://canvas.uw.edu/courses/1216339/discussion\_topics).

Logistic

## Class Road Map - EE563

- L1(3/26): Motivation, Applications, & Basic Definitions,
- L2(3/28): Machine Learning Apps (diversity, complexity, parameter, learning target, surrogate).
- L3(4/2): Info theory exs, more apps, definitions, graph/combinatorial examples
- L4(4/4): Graph and Combinatorial Examples, Matrix Rank, Examples and Properties, visualizations
- L5(4/9):
- L6(4/11):
- L7(4/16):
- L8(4/18):
- L9(4/23):
- L10(4/25):

- L11(4/30):
- L12(5/2):
- L13(5/7):
- L14(5/9):
- L15(5/14):
- L16(5/16):
- L17(5/21):
- L18(5/23):
- L-(5/28): Memorial Day (holiday)
- L19(5/30):
- L21(6/4): Final Presentations maximization.

Last day of instruction, June 1st. Finals Week: June 2-8, 2018.

## Submodular on Hypercube Vertices

• Test submodularity via values on verticies of hypercube.

Example: with |V| = n = 2, this is With |V| = n = 3, a bit harder. easy: 011 01 010 How many inequalities?

## Subadditive Definitions

#### Definition 4.2.1 (subadditive)

A function  $f: 2^V \to \mathbb{R}$  is subadditive if for any  $A, B \subseteq V$ , we have that:

$$f(A) + f(B) \ge f(A \cup B) \tag{4.21}$$

This means that the "whole" is less than the sum of the parts.

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- This means that the "whole" is greater than the sum of the parts.
- In general, submodular and subadditive (and supermodular and superadditive) are different properties.
- Ex: Let 0 < k < |V|, and consider  $f : 2^V \to \mathbb{R}_+$  where:

$$f(A) = \begin{cases} 1 & \text{if } |A| \le k \\ 0 & \text{else} \end{cases}$$
(4.22)

• This function is subadditive but not submodular.

## Modular Definitions

#### Definition 4.2.1 (modular)

A function that is both submodular and supermodular is called modular

If f is a modular function, than for any  $A,B\subseteq V,$  we have

$$f(A) + f(B) = f(A \cap B) + f(A \cup B)$$
 (4.21)

In modular functions, elements do not interact (or cooperate, or compete, or influence each other), and have value based only on singleton values.

#### Proposition 4.2.2

If f is modular, it may be written as

$$f(A) = f(\emptyset) + \sum_{a \in A} \left( f(\{a\}) - f(\emptyset) \right) = c + \sum_{a \in A} f'(a)$$

which has only |V| + 1 parameters.

(4.22)

## Complement function

Given a function  $f: 2^V \to \mathbb{R}$ , we can find a complement function  $\overline{f}: 2^V \to \mathbb{R}$  as  $\overline{f}(A) = f(V \setminus A)$  for any A.

Proposition 4.2.1

 $\bar{f}$  is submodular <u>iff</u> f is submodular.

#### Proof.

$$\bar{f}(A) + \bar{f}(B) \ge \bar{f}(A \cup B) + \bar{f}(A \cap B)$$
(4.26)

follows from

$$f(V \setminus A) + f(V \setminus B) \ge f(V \setminus (A \cup B)) + f(V \setminus (A \cap B))$$
(4.27)

which is true because  $V \setminus (A \cup B) = (V \setminus A) \cap (V \setminus B)$  and  $V \setminus (A \cap B) = (V \setminus A) \cup (V \setminus B)$  (De Morgan's laws for sets).

## Other graph functions that are submodular/supermodular

These come from Narayanan's book 1997. Let G be an undirected graph.

- Let V(X) be the vertices adjacent to some edge in  $X \subseteq E(G)$ , then |V(X)| (the vertex function) is submodular.
- Let E(S) be the edges with both vertices in  $S \subseteq V(G)$ . Then |E(S)| (the interior edge function) is supermodular.
- Let I(S) be the edges with at least one vertex in  $S \subseteq V(G)$ . Then |I(S)| (the incidence function) is submodular.
- Recall  $|\delta(S)|$ , is the set size of edges with exactly one vertex in  $S \subseteq V(G)$  is submodular (cut size function). Thus, we have  $I(S) = E(S) \cup \delta(S)$  and  $E(S) \cap \delta(S) = \emptyset$ , and thus that  $|I(S)| = |E(S)| + |\delta(S)|$ . So we can get a submodular function by summing a submodular and a supermodular function. If you had to guess, is this always the case?
- Consider  $f(A) = |\delta^+(A)| |\delta^+(V \setminus A)|$ . Guess, submodular, supermodular, modular, or neither? Exercise: determine which one and prove it.

## Number of connected components in a graph via edges

- Recall,  $f: 2^V \to \mathbb{R}$  is submodular, then so is  $\overline{f}: 2^V \to \mathbb{R}$  defined as  $\overline{f}(S) = f(V \setminus S)$ .
- Hence, if  $g: 2^V \to \mathbb{R}$  is supermodular, then so is  $\overline{g}: 2^V \to \mathbb{R}$  defined as  $\overline{g}(S) = g(V \setminus S)$ .
- Given a graph G = (V, E), for each A ⊆ E(G), let c(A) denote the number of connected components of the (spanning) subgraph (V(G), A), with c : 2<sup>E</sup> → ℝ<sub>+</sub>.
- c(A) is monotone non-increasing, c(A + a) − c(A) ≤ 0.
   C(φ) ≠ D
   Then c(A) is supermodular, i.e.,

$$c(A+a) - c(A) \le c(B+a) - c(B)$$

with  $A \subseteq B \subseteq E \setminus \{a\}$ .

Intuition: an edge is "more" (no less) able to bridge separate components (and reduce the number of conected components) when edge is added in a smaller context than when added in a larger context.
c
(A) = c(E \ A) is number of connected components in G when we remove A; supermodular monotone non-decreasing but not normalized.

(4.40)

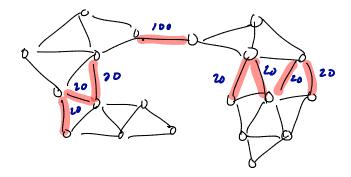
Matrix Rank

### Graph Strength

• So  $\bar{c}(A) = c(E \setminus A)$ , the number of connected components in G when we remove A, is supermodular.

Combinatorial Example

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- Maximizing  $\overline{c}(A)$  would be a goal for a network attacker many connected components means that many points in the network have lost connectivity to many other points (unprotected network).



#### Examples and Properties

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& Combinatorial Examples

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- Let G = (V, E, w) with  $w : E \to \mathbb{R}+$  be a weighted graph with non-negative weights.
- For  $(u, v) = e \in E$ , let w(e) be a measure of the strength of the connection between vertices u and v (strength meaning the difficulty of cutting the edge e).

#### Graph & Combinatorial Examples

Matrix Rank

Examples and Properties

## Graph Strength

• Then w(A) for  $A \subseteq E$  is a modular function

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$$w(A) = \sum_{e \in A} w_e \tag{4.1}$$

so that w(E(G[S])) is the "internal strength" of the vertex set S. Notation S is a set of nodes, G[S] is the vertex-induced subgraph of G induced by vertice S, E(G[S]) are the edges contained within this induced subgraph, and w(E(G[S])) is the weight of these edges.

Graph & Combinatorial Examples

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- A form of graph strength can then be defined as the following:

$$strength(G, w) = \min_{A \subseteq E(G): \bar{c}(A) > 1} \frac{w(A)}{\bar{c}(A) - 1}$$
(4.2)

Graph & Combinatorial Examples

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- Graph strength is like the minimum effort per component. An attacker would use the argument of the min to choose which edges to attack. A network designer would maximize, over G and/or w, the graph strength, strength(G, w).
- Since submodularity, problems have strongly-poly-time solutions.

#### Lemma 4.3.1

Let  $\mathbf{M} \in \mathbb{R}^{n \times n}$  be a symmetric matrix and  $m \in \mathbb{R}^n$  be a vector. Then  $f: 2^V \to \mathbb{R}$  defined as  $\mathfrak{I}_{\mathbf{X}} \in \mathfrak{s}_{\mathbf{Y}}, \mathfrak{I}^* \in \mathbb{R}^n$ 

$$f(X) = m^{\mathsf{T}} \mathbf{1}_X + \frac{1}{2} \mathbf{1}_X^{\mathsf{T}} \mathbf{M} \mathbf{1}_X$$
(4.3)

is submodular  $\underline{i}\underline{f}f$  the off-diagonal elements of M are non-positive.

#### Proof.

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is submodular iff the off-diagonal elements of M are non-positive.

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• Given a complete graph G = (V, E), recall that E(X) is the edge set with both vertices in  $X \subseteq V(G)$ , and that |E(X)| is supermodular.

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- Given a complete graph G = (V, E), recall that E(X) is the edge set with both vertices in  $X \subseteq V(G)$ , and that |E(X)| is supermodular.
- Non-negative modular weights  $w^+ : E \to \mathbb{R}_+$ , w(E(X)) is also supermodular, so w(E(X)) is submodular.

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- f is a modular function  $m^{\intercal} \mathbf{1}_A = m(A)$  added to a weighted submodular function, hence f is submodular.

#### Proof of Lemma 4.3.1 cont.

• Conversely, suppose *f* is submodular.

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- Conversely, suppose f is submodular.
- Then  $\forall u, v \in V$ ,  $f(\{u\}) + f(\{v\}) \ge f(\{u, v\}) + f(\emptyset)$  while  $f(\emptyset) = 0$ .

#### Proof of Lemma 4.3.1 cont.

- Conversely, suppose f is submodular.
- Then  $\forall u, v \in V$ ,  $f(\{u\}) + f(\{v\}) \ge f(\{u, v\}) + f(\emptyset)$  while  $f(\emptyset) = 0$ .
- This requires: v≠v

$$0 \le f(\{u\}) + f(\{v\}) - f(\{u, v\})$$

$$= m(u) + m(v) + m(v) + M$$
(4.4)
(4.5)

$$= m(u) + \frac{1}{2}M_{u,u} + m(v) + \frac{1}{2}M_{v,v}$$
(4.5)

$$-\left(m(u) + m(v) + \frac{1}{2}M_{u,u} + M_{u,v} + \frac{1}{2}M_{v,v}\right)$$
(4.6)  
=  $-M_{u,v}$  (4.7)

So that 
$$\forall u, v \in V$$
,  $M_{u,v} \leq 0$ .



• We are given a finite set U of m elements and a set of subsets  $\mathcal{U} = \{U_1, U_2, \dots, U_n\}$  of n subsets of U, so that  $U_i \subseteq U$  and  $\bigcup_i U_i = U$ .

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Graph & Combinatorial Examples

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- Maximum k cover: The goal in maximum coverage is, given an integer  $k \leq n$ , select k subsets, say  $\{a_1, a_2, \ldots, a_k\}$  with  $a_i \in [n]$  such that  $|\bigcup_{i=1}^k U_{a_i}|$  is maximized.

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- Weighted set cover:  $f(A) = w(\bigcup_{a \in A} U_a)$  where  $w: U \to \mathbb{R}_+$ .

Graph & Combinatorial Example

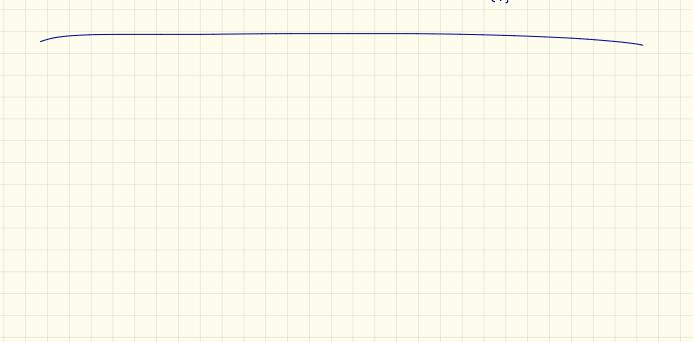
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HVEV, WWEIR W: V -> IR

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 $w: \partial^{V} \rightarrow IR \quad va \quad A \leq v, \quad w(A) = Z w(A)$ 



# Set Cover and Maximum Coverage just Special cases of Submodular Optimization

- We are given a finite set U of m elements and a set of subsets  $\mathcal{U} = \{U_1, U_2, \dots, U_n\}$  of n subsets of U, so that  $U_i \subseteq U$  and  $\bigcup_i U_i = U$ .
- The goal of minimum set cover is to choose the smallest subset  $A \subseteq [n] \triangleq \{1, \ldots, n\}$  such that  $\bigcup_{a \in A} U_a = U$ .
- Maximum k cover: The goal in maximum coverage is, given an integer  $k \leq n$ , select k subsets, say  $\{a_1, a_2, \ldots, a_k\}$  with  $a_i \in [n]$  such that  $|\bigcup_{i=1}^k U_{a_i}|$  is maximized.
- $f: 2^{[n]} \to \mathbb{Z}_+$  where for  $A \subseteq [n]$ ,  $f(A) = |\bigcup_{a \in A} U_a|$  is the set cover function and is submodular.
- Weighted set cover:  $f(A) = w(\bigcup_{a \in A} U_a)$  where  $w : U \to \mathbb{R}_+$ .
- Both Set cover and maximum coverage are well known to be NP-hard, but have a fast greedy approximation algorithm, and hence are instances of submodular optimization.

Graph & Combinatorial Example

#### Vertex and Edge Covers Also instances of submodular optimization

#### Definition 4.3.2 (vertex cover)

A vertex cover (a "vertex-based cover of edges") in graph G = (V, E) is a set  $S \subseteq V(G)$  of vertices such that every edge in G is incident to at least one vertex in S.

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• Let I(S) be the number of edges incident to vertex set S. Then we wish to find the smallest set  $S \subseteq V$  subject to I(S) = |E|.

#### Definition 4.3.3 (edge cover)

A edge cover (an "edge-based cover of vertices") in graph G = (V, E) is a set  $F \subseteq E(G)$  of edges such that every vertex in G is incident to at least one edge in F.

• Let |V|(F) be the number of vertices incident to edge set F. Then we wish to find the smallest set  $F \subseteq E$  subject to |V|(F) = |V|.

#### Graph Cut Problems Also submodular optimization

• Minimum cut: Given a graph G = (V, E), find a set of vertices  $S \subseteq V$  that minimize the cut (set of edges) between S and  $V \setminus S$ .

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Graph & Combinatorial Examples

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Graph & Combinatorial Examples

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- Maximum cut: Given a graph G = (V, E), find a set of vertices  $S \subseteq V$  that maximum cut (set of edges) between S and  $V \setminus S$ .
- Let  $\delta: 2^V \to \mathbb{R}_+$  be the cut function, namely for any given set of nodes  $X \subseteq V$ ,  $|\delta(X)|$  measures the number of edges between nodes X and  $V \setminus X$  i.e.,  $\delta(x) = E(X, V \setminus X)$ .

Graph & Combinatorial Example

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- Weighted versions, where rather than count, we sum the (non-negative) weights of the edges of a cut,  $f(X) = w(\delta(X))$ .

Graph & Combinatorial Example

- Minimum cut: Given a graph G = (V, E), find a set of vertices  $S \subseteq V$  that minimize the cut (set of edges) between S and  $V \setminus S$ .
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- Let  $\delta: 2^V \to \mathbb{R}_+$  be the cut function, namely for any given set of nodes  $X \subseteq V$ ,  $|\delta(X)|$  measures the number of edges between nodes X and  $V \setminus X$  i.e.,  $\delta(x) = E(X, V \setminus X)$ .
- Weighted versions, where rather than count, we sum the (non-negative) weights of the edges of a cut,  $f(X) = w(\delta(X))$ .
- Hence, Minimum cut and Maximum cut are also special cases of submodular optimization.

### Matrix Rank functions

• Let V, with |V| = m be an index set of a set of vectors in  $\mathbb{R}^n$  for some n (unrelated to m).

Matrix Rank

#### Matrix Rank functions

- Let V, with |V| = m be an index set of a set of vectors in  $\mathbb{R}^n$  for some n (unrelated to m).  $\forall v \in V$ ,  $\mathcal{X}_v \in I\mathcal{R}^n$
- For a given set  $\{v, v_1, v_2, \ldots, v_k\}$ , it might or might not be possible to find  $(\alpha_i)_i$  such that:

$$\mathcal{X}_{\mathcal{V}} \in \mathcal{R}^{n}$$
  $x_{v} = \sum_{i=1}^{k} \alpha_{i} x_{v_{i}}$  (4.8)

If not, then  $x_v$  is linearly independent of  $x_{v_1}, \ldots, x_{v_k}$ .

$$P(x_{1g}) = P(x) \cdot P(g)$$

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If not, then  $x_v$  is linearly independent of  $x_{v_1}, \ldots, x_{v_k}$ .

• Let r(S) for  $S \subseteq V$  be the rank of the set of vectors S. Then  $r(\cdot)$  is a submodular function, and in fact is called a matric matroid rank function.



• Given  $n \times m$  matrix  $\mathbf{X} = (x_1, x_2, \dots, x_m)$  with  $x_i \in \mathbb{R}^n$  for all i. There are m length-n column vectors  $\{x_i\}_i$ 

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- Thus, r(V) is the rank of the matrix X.

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Graph & Combinatorial Examples

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Matrix Rank

Examples and Properties

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- Any function where the above inequality is true for all  $A, B \subseteq V$  is called subadditive.

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- Then r(A) + r(B) counts the dimensions spanned by C twice, i.e.,

$$r(A) + r(B) = r(A_r) + 2r(C) + r(B_r).$$
 (4.9)

Matrix Rank

## Rank functions of a matrix

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• But  $r(A \cup B)$  counts the dimensions spanned by C only once.

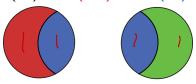
$$r(A \cup B) = r(A_r) + r(C) + r(B_r)$$
 (4.10)

Matrix Rank

Examples and Properties

### Rank functions of a matrix

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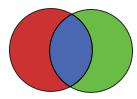
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Examples and Properties

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• Then r(A) + r(B) counts the dimensions spanned by C twice, i.e.,  $r(A) + r(B) = r(A_r) + 2r(C) + r(B_r)$ 

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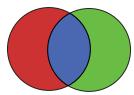
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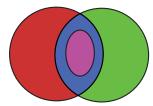


• Thus, we have subadditivity:  $r(A) + r(B) \ge r(A \cup B)$ . Can we add more to the r.h.s. and still have an inequality? Yes.

Combinatorial Examples

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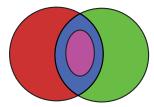
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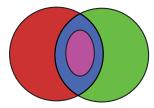


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• Common span (blue) is "more" (no less) than span of common index (magenta).

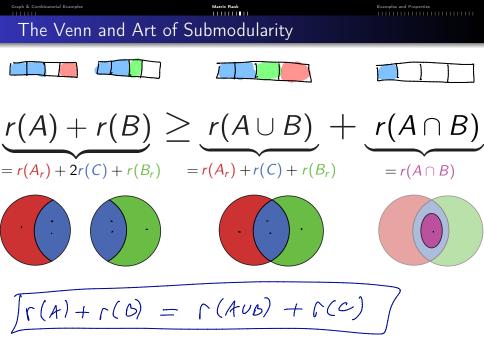
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- More generally, common information (blue) is "more" (no less) than information within common index (magenta).



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Graph & Combinatorial Examples

Combinatorial Examples

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- Then, defining  $f: 2^S \to \mathbb{R}_+$  as follows,

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- We use the term non-decreasing rather than increasing, the latter of which is strict (also so that a constant function isn't "increasing").

## Spanning trees

• Let E be a set of edges of some graph G = (V, E), and let r(S) for  $S \subseteq E$  be the maximum size (in terms of number of edges) spanning forest in the vertex-induced graph, induced by vertices incident to edges S.

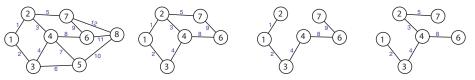
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• Example: Given G = (V, E),  $V = \{1, 2, 3, 4, 5, 6, 7, 8\}$ ,  $E = \{1, 2, \dots, 12\}$ .  $S = \{1, 2, 3, 4, 5, 8, 9\} \subset E$ . Two spanning trees have the same edge count (the rank of S).



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• Then r(S) is submodular, and is another matrix rank function corresponding to the incidence matrix of the graph.

## Summing Submodular Functions

Given E, let  $f_1, f_2: 2^E \to \mathbb{R}$  be two submodular functions. Then

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$$\geq f_1(A \cup B) + f_2(A \cup B) + f_1(A \cap B) + f_2(A \cap B)$$

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I.e., it holds for each component of f in each term in the inequality. In fact, any conic combination (i.e., non-negative linear combination) of submodular functions is submodular, as in  $f(A) = \alpha_1 f_1(A) + \alpha_2 f_2(A)$  for  $\alpha_1, \alpha_2 \ge 0$ .

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That is, the modular component with  $m(A) + m(B) = m(A \cup B) + m(A \cap B)$  never destroys the inequality. Note of course that if m is modular than so is -m.

## Restricting Submodular functions

Given E, let  $f: 2^E \to \mathbb{R}$  be a submodular functions. And let  $S \subseteq E$  be an arbitrary fixed set. Then

$$f': 2^E \to \mathbb{R} \text{ with } f'(A) \triangleq f(A \cap S)$$
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If  $v \notin S$  , then both differences on each size are zero. If  $v \in S$  , then we can consider this

$$f(A'+v) - f(A') \ge f(B'+v) - f(B')$$
(4.26)

with  $A' = A \cap S$  and  $B' = B \cap S$ . Since  $A' \subseteq B'$ , this holds due to submodularity of f.

Prof. Jeff Bilmes

### Summing Restricted Submodular Functions

Given V, let  $f_1, f_2 : 2^V \to \mathbb{R}$  be two submodular functions and let  $S_1, S_2$  be two arbitrary fixed sets. Then  $S_1, S_2 \subseteq V$ .

$$f: 2^V \to \mathbb{R}$$
 with  $f(A) = f_1(A \cap S_1) + f_2(A \cap S_2)$  (4.27)

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is submodular. This follows easily from the preceding two results. Given V, let  $\mathcal{C} = \{C_1, C_2, \ldots, C_k\}$  be a set of subsets of V, and for each  $C \in \mathcal{C}$ , let  $f_C : 2^V \to \mathbb{R}$  be a submodular function. Then

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is submodular. This property is critical for image processing and graphical models. For example, let C be all pairs of the form  $\{\{u, v\} : u, v \in V\}$ , or let it be all pairs corresponding to the edges of some undirected graphical model. We plan to revisit this topic later in the term.

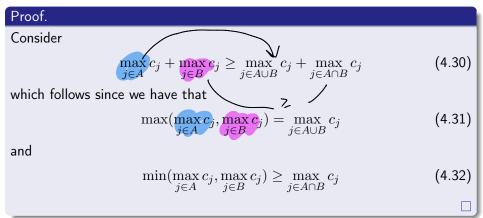
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## Max - normalized

Combinatorial Examples

Given V, let  $c \in \mathbb{R}^V_+$  be a given fixed vector. Then  $f : 2^V \to \mathbb{R}_+$ , where  $f(A) = \max_{j \in A} c_j$ (4.29)

is submodular and normalized (we take  $f(\emptyset) = 0$ ).







Given V, let  $c \in \mathbb{R}^V$  be a given fixed vector (not necessarily non-negative). Then  $f: 2^V \to \mathbb{R}$ , where

$$f(A) = \max_{j \in A} c_j \tag{4.33}$$
  
is submodular, where we take  $f(\emptyset) \leq \min_j c_j$  (so the function is not normalized).

### Proof.

The proof is identical to the normalized case.

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Combinatorial Examples

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nbinatorial Example

#### Examples and Properties

### Facility/Plant Location (uncapacitated) w. plant benefits

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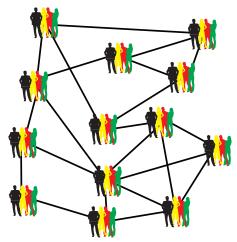
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 (4.34)

• Goal is to find a set A that maximizes f(A) (the benefit) placing a bound on the number of plants A (e.g.,  $|A| \le k$ ).

#### Examples and Properties

# Facility/Plant Location (uncapacitated)

- Core problem in operations research, early motivation for submodularity.
- Goal: as efficiently as possible, place "facilities" (factories) at certain locations to satisfy sites (at all locations) having various demands.



Combinatorial Examples

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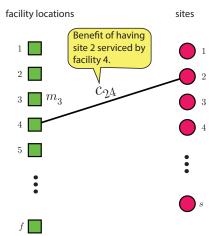


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- Goal: as efficiently as possible, place "facilities" (factories) at certain locations to satisfy sites (at all locations) having various demands.
- We can model this with a weighted bipartite graph G = (F, S, E, c) where F is set of possible factory/plant locations, S is set of sites needing service, E are edges indicating (factory,site) service possibility pairs, and c : E → ℝ<sub>+</sub> is the benefit of a given pair.
- Facility location function has form:

$$f(A) = \sum_{i \in S} \max_{j \in A} c_{ij}.$$
 (4.35)



Combinatorial Examples

# Facility Location

Given V, E , let  $c \in \mathbb{R}^{V \times E}$  be a given  $|V| \times |E|$  matrix. Then

$$f: 2^E \to \mathbb{R}, \text{ where } f(A) = \sum_{i \in V} \max_{j \in A} c_{ij}$$
 (4.36)

### is submodular.

### Proof.

We can write f(A) as  $f(A) = \sum_{i \in V} f_i(A)$  where  $f_i(A) = \max_{j \in A} c_{ij}$  is submodular (max of a *i*<sup>th</sup> row vector), so f can be written as a sum of submodular functions.

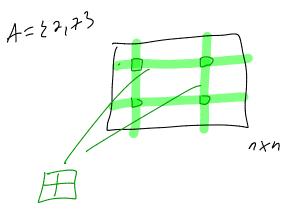
Thus, the facility location function (which only adds a modular function to the above) is submodular.

#### Graph & Combinatorial Examples

Matrix Rank

# Log Determinant

• Let  $\Sigma$  be an  $n \times n$  positive definite matrix. Let  $V = \{1, 2, ..., n\} \equiv [n]$  be an index set, and for  $A \subseteq V$ , let  $\Sigma_A$  be the (square) submatrix of  $\Sigma$  obtained by including only entries in the rows/columns given by A.



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- We have that:

 $f(A) = \log \det(\Sigma_A)$  is submodular. (4.37)

#### Graph & Combinatorial Examples

Matrix Rank

# Log Determinant

- Let  $\Sigma$  be an  $n \times n$  positive definite matrix. Let  $V = \{1, 2, ..., n\} \equiv [n]$  be an index set, and for  $A \subseteq V$ , let  $\Sigma_A$  be the (square) submatrix of  $\Sigma$  obtained by including only entries in the rows/columns given by A.
- We have that:

$$f(A) = \log \det(\mathbf{\Sigma}_A)$$
 is submodular. (4.37)

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### Proof of submodularity of the logdet function.

Suppose  $X \in \mathbf{R}^n$  is multivariate Gaussian random variable, that is

$$x \in p(x) = \frac{1}{\sqrt{|2\pi\Sigma|}} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right)$$
(4.38)

. . .

(4.39)

(4.40)

# Log Determinant

#### ...cont.

Then the (differential) entropy of the r.v. X is given by

$$h(X) = \log \sqrt{|2\pi e \Sigma|} = \log \sqrt{(2\pi e)^n |\Sigma|}$$

and in particular, for a variable subset A,

$$f(A) = h(X_A) = \log \sqrt{(2\pi e)^{|A|} |\boldsymbol{\Sigma}_A|}$$

Entropy is submodular (further conditioning reduces entropy), and moreover

$$f(A) = h(X_A) = m(A) + \frac{1}{2}\log|\Sigma_A|$$
 (4.41)

where m(A) is a modular function.

Note: still submodular in the semi-definite case as well.

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# Summary so far

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- Restrictions:  $f'(A) = f(A \cap S)$
- max:  $f(A) = \max_{j \in A} c_j$  and facility location.
- Log determinant  $f(A) = \log \det(\Sigma_A)$

### Concave over non-negative modular

Let  $m \in \mathbb{R}^E_+$  be a non-negative modular function, and g a concave function over  $\mathbb{R}$ . Define  $f: 2^E \to \mathbb{R}$  as

$$f(A) = g(m(A))$$
 (4.42)

then f is submodular.

### Proof.

Given  $A \subseteq B \subseteq E \setminus v$ , we have  $0 \le a = m(A) \le b = m(B)$ , and  $0 \le c = m(v)$ . For g concave, we have  $g(a + c) - g(a) \ge g(b + c) - g(b)$ , and thus

$$g(m(A) + m(v)) - g(m(A)) \ge g(m(B) + m(v)) - g(m(B))$$
(4.43)

A form of converse is true as well.

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### Theorem 4.5.1

Given a ground set V. The following two are equivalent:

- For all modular functions  $m: 2^V \to \mathbb{R}_+$ , then  $f: 2^V \to \mathbb{R}$  defined as f(A) = g(m(A)) is submodular
- $2 g: \mathbb{R}_+ \to \mathbb{R} \text{ is concave.}$

• If g is non-decreasing concave w. g(0) = 0, then f is polymatroidal.

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- Very large class of functions, including graph cut, bipartite neighborhoods, set cover (Stobbe & Krause 2011), and "feature-based submodular functions" (Wei, Iyer, & Bilmes 2014).
- However, Vondrak showed that a graphic matroid rank function over  $K_4$  (we'll define this after we define matroids) are not members.

### Monotonicity

### Definition 4.5.2

A function  $f : 2^V \to \mathbb{R}$  is monotone nondecreasing (resp. monotone increasing) if for all  $A \subset B$ , we have  $f(A) \leq f(B)$  (resp. f(A) < f(B)).

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#### Definition 4.5.3

A function  $f: 2^V \to \mathbb{R}$  is monotone nonincreasing (resp. monotone decreasing) if for all  $A \subset B$ , we have  $f(A) \ge f(B)$  (resp. f(A) > f(B)).

# Composition of non-decreasing submodular and non-decreasing concave

#### Theorem 4.5.4

Given two functions, one defined on sets

$$f: 2^V \to \mathbb{R} \tag{4.45}$$

and another continuous valued one:

$$g: \mathbb{R} \to \mathbb{R} \tag{4.46}$$

the composition formed as  $h = g \circ f : 2^V \to \mathbb{R}$  (defined as h(S) = g(f(S))) is nondecreasing submodular, if g is non-decreasing concave and f is nondecreasing submodular.

### Monotone difference of two functions

Let f and g both be submodular functions on subsets of V and let  $(f-g)(\cdot)$  be either monotone non-decreasing or monotone non-increasing Then  $h:2^V\to R$  defined by

$$h(A) = \min(f(A), g(A))$$
 (4.47)

is submodular.

### Proof. If h(A) agrees with f on both X and Y (or g on both X and Y), and since $h(X) + h(Y) = f(X) + f(Y) \ge f(X \cup Y) + f(X \cap Y)$ (4.48)

or

$$h(X) + h(Y) = g(X) + g(Y) \ge g(X \cup Y) + g(X \cap Y),$$
(4.49)

the result (Equation 4.47 being submodular) follows since  $\frac{f(X) + f(Y)}{g(X) + g(Y)} \ge \min(f(X \cup Y), g(X \cup Y)) + \min(f(X \cap Y), g(X \cap Y))$ (4.50)

### Monotone difference of two functions

#### ...cont.

Otherwise, w.l.o.g., 
$$h(X) = f(X)$$
 and  $h(Y) = g(Y)$ , giving

$$h(X) + h(Y) = f(X) + g(Y) \ge f(X \cup Y) + f(X \cap Y) + g(Y) - f(Y)$$
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Assume the case where f-g is monotone non-decreasing Hence,  $f(X\cup Y)+g(Y)-f(Y)\geq g(X\cup Y)$  giving

 $h(X) + h(Y) \ge g(X \cup Y) + f(X \cap Y) \ge h(X \cup Y) + h(X \cap Y)$  (4.52)

What is an easy way to prove the case where f - g is monotone non-increasing?

### Saturation via the $\min(\cdot)$ function

Let  $f: 2^V \to \mathbb{R}$  be a monotone increasing or decreasing submodular function and let  $\alpha$  be a constant. Then the function  $h: 2^V \to \mathbb{R}$  defined by

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$$h(A) = \min(\alpha, f(A)) \tag{4.53}$$

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Note also,  $g(a) = \min(k, a)$  for constant k is a non-decreasing concave function, so when f is monotone nondecreasing submodular, we can use the earlier result about composing a monotone concave function with a monotone submodular function to get a version of this.

### More on Min - the saturate trick

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- In general, the minimum of two submodular functions is not submodular (unlike concave functions, closed under min).
- However, when wishing to maximize two monotone non-decreasing submodular functions f, g, we can define function  $h_{\alpha} : 2^V \to \mathbb{R}$  as

$$h_{\alpha}(A) = \frac{1}{2} \left( \min(\alpha, f(A)) + \min(\alpha, g(A)) \right)$$
(4.54)

then  $h_{\alpha}$  is submodular, and  $h_{\alpha}(A) \geq \alpha$  if and only if both  $f(A) \geq \alpha$ and  $g(A) \geq \alpha$ , for constant  $\alpha \in \mathbb{R}$ .

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• This can be useful in many applications. An instance of a <u>submodular</u> <u>surrogate</u> (where we take a non-submodular problem and find a submodular one that can tell us something about it).

### Arbitrary functions: difference between submodular funcs.

#### Theorem 4.5.5

Given an arbitrary set function h, it can be expressed as a difference between two submodular functions (i.e.,  $\forall h \in 2^V \to \mathbb{R}$ ,  $\exists f, g \text{ s.t. } \forall A, h(A) = f(A) - g(A)$  where both f and g are submodular).

#### Proof.

Let h be given and arbitrary, and define:

$$\alpha \stackrel{\Delta}{=} \min_{X,Y:X \not\subseteq Y,Y \not\subseteq X} \left( h(X) + h(Y) - h(X \cup Y) - h(X \cap Y) \right)$$
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If  $\alpha \geq 0$  then h is submodular, so by assumption  $\alpha < 0$ .

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If  $\alpha \ge 0$  then h is submodular, so by assumption  $\alpha < 0$ . Now let f be an arbitrary strict submodular function and define

$$\beta \stackrel{\Delta}{=} \min_{X,Y:X \not\subseteq Y,Y \not\subseteq X} \Big( f(X) + f(Y) - f(X \cup Y) - f(X \cap Y) \Big).$$
(4.56)

Strict means that  $\beta > 0$ .

. . .

### Arbitrary functions as difference between submodular funcs.

#### ...cont.

Define  $h': 2^V \to \mathbb{R}$  as

$$h'(A) = h(A) + \frac{|\alpha|}{\beta} f(A)$$
(4.57)

Then h' is submodular (why?), and  $h = h'(A) - \frac{|\alpha|}{\beta}f(A)$ , a difference between two submodular functions as desired.

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$$f(A \cup \{j\}) - f(A) \stackrel{\Delta}{=} \rho_j(A) \tag{4.58}$$

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$$\stackrel{\Delta}{=} f(\{j\}|A)$$
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#### Graph & Combinatorial Examples

Matrix Rank

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- We'll use f(j|A).
- Submodularity's diminishing returns definition can be stated as saying that f(j|A) is a monotone non-increasing function of A, since  $f(j|A) \ge f(j|B)$  whenever  $A \subseteq B$  (conditioning reduces valuation).

### Gain Notation

It will also be useful to extend this to sets. Let A, B be any two sets. Then

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So when j is any singleton

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Inspired from information theory notation and the notation used for conditional entropy  $H(X_A|X_B) = H(X_A, X_B) - H(X_B)$ .

### Totally normalized functions

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$$\bar{g}(A) = g(A) - \sum_{a \in A} g(a|V \setminus \{a\}) = g(A) - m_g(A)$$
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- Then  $g(A) = \overline{g}(A) + m_g(A)$ .

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natorial Example

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- Given submodular f and g, let  $\overline{f}$  and  $\overline{g}$  be them totally normalized.
- Given arbitrary h = f g where f and g are normalized submodular,

$$h = f - g = \bar{f} + m_f - (\bar{g} + m_g) \tag{4.67}$$

$$=\bar{f}-\bar{g}+(m_f-m_g)$$
(4.68)

$$=\bar{f}-\bar{g}+m_{f-h} \tag{4.69}$$

$$=\bar{f} + m_{f-g}^{+} - (\bar{g} + (-m_{f-g})^{+})$$
(4.70)

where  $m^+$  is the positive part of modular function m. That is,  $m^+(A) = \sum_{a \in A} m(a) \mathbf{1}(m(a) > 0).$ 

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- Any normalized function h (i.e.,  $h(\emptyset) = 0$ ) can be represented as a difference not only between submodular, but between polymatroid (normalized monotone non-decreasing submodular) functions.
- Given submodular f and g, let  $\overline{f}$  and  $\overline{g}$  be them totally normalized.
- Given arbitrary h = f g where f and g are normalized submodular,

$$h = f - g = \bar{f} + m_f - (\bar{g} + m_g)$$
(4.67)

$$=\bar{f}-\bar{g}+(m_f-m_g)$$
(4.68)

$$=ar{f} - ar{g} + m_{f-h}$$
 (4.69)

$$=\bar{f}+m_{f-g}^{+}-(\bar{g}+(-m_{f-g})^{+})$$
(4.70)

where  $m^+$  is the positive part of modular function m. That is,  $m^+(A) = \sum_{a \in A} m(a) \mathbf{1}(m(a) > 0).$ 

- Both  $\bar{f} + m_{f-g}^+$  and  $\bar{g} + (-m_{f-g})^+$  are polymatroid functions!
- Thus, any function can be expressed as a difference between two, not only submodular (DS), but polymatroid functions.