Submodular Functions, Optimization, and Applications to Machine Learning

— Spring Quarter, Lecture 4 —

http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563_spring_2018/

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Cumulative Outstanding Reading

• Read chapter 1 from Fujishige's book.

Announcements, Assignments, and Reminders

- Homework 1 out, due Monday, 4/9/2018 11:59pm electronically via our assignment dropbox (https://canvas.uw.edu/courses/1216339/assignments).
- If you have any questions about anything, please ask then via our discussion board (https://canvas.uw.edu/courses/1216339/discussion_topics).

Class Road Map - EE563

- L1(3/26): Motivation, Applications, & Basic Definitions,
- L2(3/28): Machine Learning Apps (diversity, complexity, parameter, learning target, surrogate).
- L3(4/2): Info theory exs, more apps, definitions, graph/combinatorial examples
- L4(4/4): Graph and Combinatorial Examples, Matrix Rank, Examples and Properties, visualizations
- L5(4/9):
- L6(4/11):
- L7(4/16):
- L8(4/18):
- L9(4/23):
- L10(4/25):

- L11(4/30):
- L12(5/2):
- L13(5/7):
- L14(5/9):
- L15(5/14):
- L16(5/16):
- L17(5/21):
- L18(5/23):
- L-(5/28): Memorial Day (holiday)
- L19(5/30):
- L21(6/4): Final Presentations maximization.

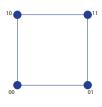
Last day of instruction, June 1st. Finals Week: June 2-8, 2018.

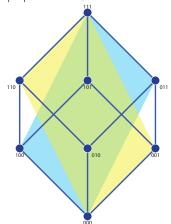
Submodular on Hypercube Vertices

• Test submodularity via values on verticies of hypercube.

Example: with |V|=n=2, this is \quad With |V|=n=3, a bit harder.

easy:





How many inequalities?

Subadditive Definitions

Definition 4.2.1 (subadditive)

A function $f: 2^V \to \mathbb{R}$ is subadditive if for any $A, B \subseteq V$, we have that:

$$f(A) + f(B) \ge f(A \cup B) \tag{4.21}$$

This means that the "whole" is less than the sum of the parts.

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- This means that the "whole" is greater than the sum of the parts.
- In general, submodular and subadditive (and supermodular and superadditive) are different properties.
- Ex: Let 0 < k < |V|, and consider $f: 2^V \to \mathbb{R}_+$ where:

$$f(A) = \begin{cases} 1 & \text{if } |A| \le k \\ 0 & \text{else} \end{cases} \tag{4.22}$$

This function is subadditive but not submodular.

Modular Definitions

Definition 4.2.1 (modular)

A function that is both submodular and supermodular is called modular

If f is a modular function, than for any $A, B \subseteq V$, we have

$$f(A) + f(B) = f(A \cap B) + f(A \cup B)$$
 (4.21)

In modular functions, elements do not interact (or cooperate, or compete, or influence each other), and have value based only on singleton values.

Proposition 4.2.2

If f is modular, it may be written as

$$f(A) = f(\emptyset) + \sum_{a \in A} (f(\{a\}) - f(\emptyset)) = c + \sum_{a \in A} f'(a)$$
 (4.22)

which has only |V| + 1 parameters.

Complement function

Given a function $f: 2^V \to \mathbb{R}$, we can find a complement function $\bar{f}: 2^V \to \mathbb{R}$ as $\bar{f}(A) = f(V \setminus A)$ for any A.

Proposition 4.2.1

 $ar{f}$ is submodular iff f is submodular.

Proof.

$$\bar{f}(A) + \bar{f}(B) \ge \bar{f}(A \cup B) + \bar{f}(A \cap B) \tag{4.26}$$

follows from

$$f(V \setminus A) + f(V \setminus B) \ge f(V \setminus (A \cup B)) + f(V \setminus (A \cap B)) \tag{4.27}$$

which is true because $V \setminus (A \cup B) = (V \setminus A) \cap (V \setminus B)$ and $V \setminus (A \cap B) = (V \setminus A) \cup (V \setminus B)$ (De Morgan's laws for sets).



Other graph functions that are submodular/supermodular

These come from Narayanan's book 1997. Let ${\cal G}$ be an undirected graph.

- Let V(X) be the vertices adjacent to some edge in $X\subseteq E(G)$, then |V(X)| (the <u>vertex function</u>) is submodular.
- Let E(S) be the edges with both vertices in $S \subseteq V(G)$. Then |E(S)| (the <u>interior edge function</u>) is supermodular.
- Let I(S) be the edges with at least one vertex in $S \subseteq V(G)$. Then |I(S)| (the incidence function) is submodular.
- Recall $|\delta(S)|$, is the set size of edges with exactly one vertex in $S\subseteq V(G)$ is submodular (cut size function). Thus, we have $I(S)=E(S)\cup\delta(S)$ and $E(S)\cap\delta(S)=\emptyset$, and thus that $|I(S)|=|E(S)|+|\delta(S)|$. So we can get a submodular function by summing a submodular and a supermodular function. If you had to guess, is this always the case?
- Consider $f(A) = |\delta^+(A)| |\delta^+(V \setminus A)|$. Guess, submodular, supermodular, modular, or neither? Exercise: determine which one and prove it.

Number of connected components in a graph via edges

- Recall, $f:2^V\to\mathbb{R}$ is submodular, then so is $\bar f:2^V\to\mathbb{R}$ defined as $\bar f(S)=f(V\setminus S).$
- Hence, if $g: 2^V \to \mathbb{R}$ is supermodular, then so is $\bar{g}: 2^V \to \mathbb{R}$ defined as $\bar{g}(S) = g(V \setminus S)$.
- Given a graph G=(V,E), for each $A\subseteq E(G)$, let c(A) denote the number of connected components of the (spanning) subgraph (V(G),A), with $c:2^E\to\mathbb{R}_+$.
- ullet c(A) is monotone non-increasing, $c(A+a)-c(A)\leq 0$.
- Then c(A) is supermodular, i.e.,

$$c(A+a)-c(A) \leq c(B+a)-c(B) \tag{4.40}$$
 with $A\subseteq B\subseteq E\setminus \{a\}$.

- Intuition: an edge is "more" (no less) able to bridge separate components (and reduce the number of conected components) when edge is added in a smaller context than when added in a larger context.
- $\bar{c}(A) = c(E \setminus A)$ is number of connected components in G when we remove A; supermodular monotone non-decreasing but not normalized.

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- Let G = (V, E, w) with $w : E \to \mathbb{R}+$ be a weighted graph with non-negative weights.

Graph Strength

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- An attacker wishes to choose a small number of edges (since it is cheap) to shatter the graph into as many components as possible.
- Let G=(V,E,w) with $w:E\to\mathbb{R}+$ be a weighted graph with non-negative weights.
- For $(u,v)=e\in E$, let w(e) be a measure of the strength of the connection between vertices u and v (strength meaning the difficulty of cutting the edge e).

Graph Strength

• Then w(A) for $A \subseteq E$ is a modular function

$$w(A) = \sum_{e \in A} w_e \tag{4.1}$$

so that w(E(G[S])) is the "internal strength" of the vertex set S. Notation: S is a set of nodes, G[S] is the vertex-induced subgraph of G induced by vertices S, E(G[S]) are the edges contained within this induced subgraph, and w(E(G[S])) is the weight of these edges.

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- A form of graph strength can then be defined as the following:

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• Graph strength is like the minimum effort per component. An attacker would use the argument of the min to choose which edges to attack. A network designer would maximize, over G and/or w, the graph strength, strength(G,w).

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- Graph strength is like the minimum effort per component. An attacker would use the argument of the min to choose which edges to attack. A network designer would maximize, over G and/or w, the graph strength, strength(G,w).
- Since submodularity, problems have strongly-poly-time solutions.

Submodularity, Quadratic Structures, and Cuts

Lemma 4.3.1

Let $\mathbf{M} \in \mathbb{R}^{n \times n}$ be a symmetric matrix and $m \in \mathbb{R}^n$ be a vector. Then $f: 2^V \to \mathbb{R}$ defined as

$$f(X) = m^{\mathsf{T}} \mathbf{1}_X + \frac{1}{2} \mathbf{1}_X^{\mathsf{T}} \mathbf{M} \mathbf{1}_X \tag{4.3}$$

is submodular iff the off-diagonal elements of M are non-positive.

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- Given a complete graph G=(V,E), recall that E(X) is the edge set with both vertices in $X\subseteq V(G)$, and that |E(X)| is supermodular.
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- f is a modular function $m^{\mathsf{T}} \mathbf{1}_A = m(A)$ added to a weighted submodular function, hence f is submodular.

Submodularity, Quadratic Structures, and Cuts

Proof of Lemma 4.3.1 cont.

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Proof of Lemma 4.3.1 cont.

- \bullet Conversely, suppose f is submodular.
- Then $\forall u, v \in V$, $f(\{u\}) + f(\{v\}) \ge f(\{u, v\}) + f(\emptyset)$ while $f(\emptyset) = 0$.
- This requires:

$$0 \le f(\{u\}) + f(\{v\}) - f(\{u, v\}) \tag{4.4}$$

$$= m(u) + \frac{1}{2}M_{u,u} + m(v) + \frac{1}{2}M_{v,v}$$
(4.5)

$$-\left(m(u) + m(v) + \frac{1}{2}M_{u,u} + M_{u,v} + \frac{1}{2}M_{v,v}\right) \tag{4.6}$$

$$= -M_{u,v} \tag{4.7}$$

So that $\forall u, v \in V$, $M_{u,v} \leq 0$.



• We are given a finite set U of m elements and a set of subsets $\mathcal{U} = \{U_1, U_2, \dots, U_n\}$ of n subsets of U, so that $U_i \subseteq U$ and $\bigcup_i U_i = U$.

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- Maximum k cover: The goal in maximum coverage is, given an integer $k \leq n$, select k subsets, say $\{a_1, a_2, \ldots, a_k\}$ with $a_i \in [n]$ such that $|\bigcup_{i=1}^k U_{a_i}|$ is maximized.

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- Weighted set cover: $f(A) = w(\bigcup_{a \in A} U_a)$ where $w: U \to \mathbb{R}_+$.
- Both Set cover and maximum coverage are well known to be NP-hard, but have a fast greedy approximation algorithm, and hence are instances of submodular optimization.

Also instances of submodular optimization

Definition 4.3.2 (vertex cover)

A vertex cover (a "vertex-based cover of edges") in graph G=(V,E) is a set $S\subseteq V(G)$ of vertices such that every edge in G is incident to at least one vertex in S.

• Let I(S) be the number of edges incident to vertex set S. Then we wish to find the smallest set $S \subseteq V$ subject to I(S) = |E|.

Definition 4.3.3 (edge cover)

A edge cover (an "edge-based cover of vertices") in graph G=(V,E) is a set $F\subseteq E(G)$ of edges such that every vertex in G is incident to at least one edge in F.

• Let |V|(F) be the number of vertices incident to edge set F. Then we wish to find the smallest set $F \subseteq E$ subject to |V|(F) = |V|.

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Graph Cut Problems Also submodular optimization

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- Let $\delta: 2^V \to \mathbb{R}_+$ be the cut function, namely for any given set of nodes $X \subseteq V$, $|\delta(X)|$ measures the number of edges between nodes X and $V \setminus X$ i.e., $\delta(x) = E(X, V \setminus X)$.

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- Weighted versions, where rather than count, we sum the (non-negative) weights of the edges of a cut, $f(X) = w(\delta(X))$.
- Hence, Minimum cut and Maximum cut are also special cases of submodular optimization.

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- For a given set $\{v, v_1, v_2, \dots, v_k\}$, it might or might not be possible to find $(\alpha_i)_i$ such that:

$$x_v = \sum_{i=1}^k \alpha_i x_{v_i} \tag{4.8}$$

If not, then x_v is linearly independent of x_{v_1}, \ldots, x_{v_k} .

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• Let r(S) for $S \subseteq V$ be the rank of the set of vectors S. Then $r(\cdot)$ is a submodular function, and in fact is called a matric matroid rank function.

• Given $n \times m$ matrix $\mathbf{X} = (x_1, x_2, \dots, x_m)$ with $x_i \in \mathbb{R}^n$ for all i. There are m length-n column vectors $\{x_i\}_i$

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- ullet Thus, r(V) is the rank of the matrix ${f X}$.

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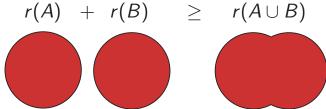
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- Any function where the above inequality is true for all $A, B \subseteq V$ is called subadditive.

 Vectors A and B have a (possibly empty) common span and two (possibly empty) non-common residual spans. ph & Combinatorial Examples Matrix Rank Examples and Properties

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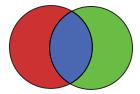
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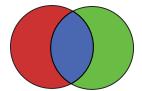
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• Thus, we have subadditivity: $r(A) + r(B) \ge r(A \cup B)$. Can we add more to the r.h.s. and still have an inequality? Yes.

• Note, $r(A \cap B) \leq r(C)$. Why? Vectors indexed by $A \cap B$ (i.e., the common index set) span no more than the dimensions commonly spanned by A and B (namely, those spanned by the professed C).

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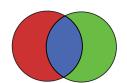
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- More generally, common information (blue) is "more" (no less) than information within common index (magenta).

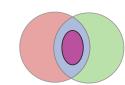
The Venn and Art of Submodularity

$$\underbrace{r(A) + r(B)}_{= r(A_r) + 2r(C) + r(B_r)} \ge \underbrace{r(A \cup B)}_{= r(A_r) + r(C) + r(B_r)} + \underbrace{r(A \cap B)}_{= r(A \cap B)}$$









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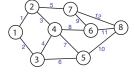
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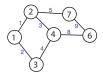
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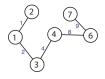
- In general (as we will see) polymatroid rank functions are submodular, normalized $f(\emptyset) = 0$, and monotone non-decreasing $(f(A) \leq f(B))$ whenever $A \subseteq B$).
- We use the term non-decreasing rather than increasing, the latter of which is strict (also so that a constant function isn't "increasing").

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- Example: Given G = (V, E), $V = \{1, 2, 3, 4, 5, 6, 7, 8\}$, $E = \{1, 2, \dots, 12\}$. $S = \{1, 2, 3, 4, 5, 8, 9\} \subset E$. Two spanning trees have the same edge count (the rank of S).

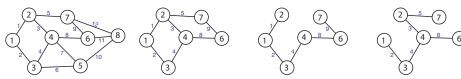








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ullet Then r(S) is submodular, and is another matrix rank function corresponding to the incidence matrix of the graph.

Summing Submodular Functions

Given E, let $f_1, f_2: 2^E \to \mathbb{R}$ be two submodular functions. Then

$$f: 2^E \to \mathbb{R} \text{ with } f(A) = f_1(A) + f_2(A)$$
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$$f(A) + f(B) = f_1(A) + f_2(A) + f_1(B) + f_2(B)$$

$$\geq f_1(A \cup B) + f_2(A \cup B) + f_1(A \cap B) + f_2(A \cap B)$$

$$= f(A \cup B) + f(A \cap B).$$
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 $= f(H \cup D) + f(H \cap D). \tag{1.13}$

I.e., it holds for each component of f in each term in the inequality.

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$$= f(A \cup B) + f(A \cap B). \tag{4.19}$$

I.e., it holds for each component of f in each term in the inequality. In fact, any conic combination (i.e., non-negative linear combination) of submodular functions is submodular, as in $f(A) = \alpha_1 f_1(A) + \alpha_2 f_2(A)$ for $\alpha_1, \alpha_2 \geq 0$.

Summing Submodular and Modular Functions

Given E, let $f_1, m: 2^E \to \mathbb{R}$ be a submodular and a modular function.

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$$f(A) + f(B) = f_1(A) - m(A) + f_1(B) - m(B)$$
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$$= f(A \cup B) + f(A \cap B). \tag{4.23}$$

That is, the modular component with $m(A)+m(B)=m(A\cup B)+m(A\cap B)$ never destroys the inequality. Note of course that if m is modular than so is -m.

Given E, let $f:2^E\to\mathbb{R}$ be a submodular functions. And let $S\subseteq E$ be an arbitrary fixed set. Then

$$f': 2^E \to \mathbb{R} \text{ with } f'(A) \triangleq f(A \cap S)$$
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is submodular.

Restricting Submodular functions

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Given $A \subseteq B \subseteq E \setminus v$, consider

$$f((A+v)\cap S) - f(A\cap S) \ge f((B+v)\cap S) - f(B\cap S) \tag{4.25}$$

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$$f((A+v)\cap S) - f(A\cap S) \ge f((B+v)\cap S) - f(B\cap S) \tag{4.25}$$

If $v \notin S$, then both differences on each size are zero. If $v \in S$, then we can consider this

$$f(A'+v) - f(A') \ge f(B'+v) - f(B') \tag{4.26}$$

with $A' = A \cap S$ and $B' = B \cap S$. Since $A' \subseteq B'$, this holds due to submodularity of f.

Given V, let $f_1, f_2: 2^V \to \mathbb{R}$ be two submodular functions and let S_1, S_2 be two arbitrary fixed sets. Then

$$f: 2^V \to \mathbb{R} \text{ with } f(A) = f_1(A \cap S_1) + f_2(A \cap S_2)$$
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is submodular. This follows easily from the preceding two results. Given V, let $\mathcal{C} = \{C_1, C_2, \ldots, C_k\}$ be a set of subsets of V, and for each $C \in \mathcal{C}$, let $f_C : 2^V \to \mathbb{R}$ be a submodular function. Then

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is submodular. This property is critical for image processing and graphical models. For example, let $\mathcal C$ be all pairs of the form $\{\{u,v\}:u,v\in V\}$, or let it be all pairs corresponding to the edges of some undirected graphical model. We plan to revisit this topic later in the term.

Given V, let $c \in \mathbb{R}_+^V$ be a given fixed vector. Then $f: 2^V \to \mathbb{R}_+$, where

$$f(A) = \max_{i \in A} c_i \tag{4.29}$$

is submodular and normalized (we take $f(\emptyset) = 0$).

Proof.

Consider

$$\max_{j \in A} c_j + \max_{j \in B} c_j \ge \max_{j \in A \cup B} c_j + \max_{j \in A \cap B} c_j \tag{4.30}$$

which follows since we have that

$$\max(\max_{j \in A} c_j, \max_{j \in B} c_j) = \max_{j \in A \cup B} c_j \tag{4.31}$$

and

$$\min(\max_{j \in A} c_j, \max_{j \in B} c_j) \ge \max_{j \in A \cap B} c_j \tag{4.32}$$

Given V, let $c \in \mathbb{R}^V$ be a given fixed vector (not necessarily non-negative). Then $f: 2^V \to \mathbb{R}$, where

$$f(A) = \max_{j \in A} c_j \tag{4.33}$$

is submodular, where we take $f(\emptyset) \leq \min_j c_j$ (so the function is not normalized).

Proof.

The proof is identical to the normalized case.



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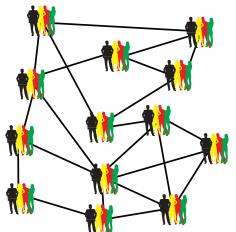
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• Goal is to find a set A that maximizes f(A) (the benefit) placing a bound on the number of plants A (e.g., $|A| \le k$).

oph & Combinatorial Examples Matrix Plank Examples and Properties

Facility/Plant Location (uncapacitated)

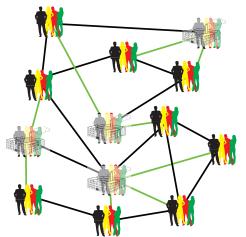
- Core problem in operations research, early motivation for submodularity.
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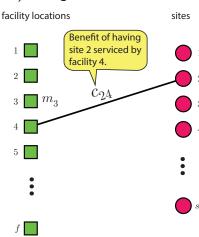
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Facility/Plant Location (uncapacitated)

- Core problem in operations research, early motivation for submodularity.
- Goal: as efficiently as possible, place "facilities" (factories) at certain locations to satisfy sites (at all locations) having various demands.
- We can model this with a weighted bipartite graph G=(F,S,E,c) where F is set of possible factory/plant locations, S is set of sites needing service, E are edges indicating (factory,site) service possiblity pairs, and $c:E\to\mathbb{R}_+$ is the benefit of a given pair.
- Facility location function has form:

$$f(A) = \sum_{i \in S} \max_{j \in A} c_{ij}.$$
 (4.35)



Facility Location

Given V, E, let $c \in \mathbb{R}^{V \times E}$ be a given $|V| \times |E|$ matrix. Then

$$f: 2^E \to \mathbb{R}, \text{ where } f(A) = \sum_{i \in V} \max_{j \in A} c_{ij}$$
 (4.36)

is submodular.

Proof.

We can write f(A) as $f(A) = \sum_{i \in V} f_i(A)$ where $f_i(A) = \max_{j \in A} c_{ij}$ is submodular (max of a i^{th} row vector), so f can be written as a sum of submodular functions.

Thus, the facility location function (which only adds a modular function to the above) is submodular.

• Let Σ be an $n \times n$ positive definite matrix. Let $V = \{1, 2, ..., n\} \equiv [n]$ be an index set, and for $A \subseteq V$, let Σ_A be the (square) submatrix of Σ obtained by including only entries in the rows/columns given by A.

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• The submodularity of the log determinant is crucial for determinantal point processes (DPPs) (defined later in the class).

Proof of submodularity of the logdet function.

Suppose $X \in \mathbf{R}^n$ is multivariate Gaussian random variable, that is

$$x \in p(x) = \frac{1}{\sqrt{|2\pi\Sigma|}} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right)$$
(4.38)

...cont.

Then the (differential) entropy of the r.v. X is given by

$$h(X) = \log \sqrt{|2\pi e \Sigma|} = \log \sqrt{(2\pi e)^n |\Sigma|}$$
 (4.39)

and in particular, for a variable subset A,

$$f(A) = h(X_A) = \log \sqrt{(2\pi e)^{|A|} |\Sigma_A|}$$
 (4.40)

Entropy is submodular (further conditioning reduces entropy), and moreover

$$f(A) = h(X_A) = m(A) + \frac{1}{2}\log|\Sigma_A|$$
 (4.41)

where m(A) is a modular function.

Note: still submodular in the semi-definite case as well.

Summary so far

• Summing: if $\alpha_i \geq 0$ and $f_i : 2^V \to \mathbb{R}$ is submodular, then so is $\sum_i \alpha_i f_i$.

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- max: $f(A) = \max_{i \in A} c_i$ and facility location.

- Summing: if $\alpha_i \geq 0$ and $f_i: 2^V \to \mathbb{R}$ is submodular, then so is $\sum_i \alpha_i f_i$.
- Restrictions: $f'(A) = f(A \cap S)$
- max: $f(A) = \max_{i \in A} c_i$ and facility location.
- Log determinant $f(A) = \log \det(\Sigma_A)$

Let $m\in\mathbb{R}_+^E$ be a non-negative modular function, and g a concave function over $\mathbb{R}.$ Define $f:2^E\to\mathbb{R}$ as

$$f(A) = g(m(A)) \tag{4.42}$$

then f is submodular.

Proof.

Given $A\subseteq B\subseteq E\setminus v$, we have $0\le a=m(A)\le b=m(B)$, and $0\le c=m(v)$. For g concave, we have $g(a+c)-g(a)\ge g(b+c)-g(b)$, and thus

$$g(m(A) + m(v)) - g(m(A)) \ge g(m(B) + m(v)) - g(m(B))$$
 (4.43)



A form of converse is true as well.

Concave composed with non-negative modular

Theorem 4.5.1

Given a ground set V. The following two are equivalent:

- For all modular functions $m: 2^V \to \mathbb{R}_+$, then $f: 2^V \to \mathbb{R}$ defined as f(A) = g(m(A)) is submodular
- $g: \mathbb{R}_+ \to \mathbb{R}$ is concave.
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- Very large class of functions, including graph cut, bipartite neighborhoods, set cover (Stobbe & Krause 2011), and "feature-based submodular functions" (Wei, Iyer, & Bilmes 2014).
- However, Vondrak showed that a graphic matroid rank function over K_4 (we'll define this after we define matroids) are not members.

Monotonicity

Definition 4.5.2

A function $f: 2^V \to \mathbb{R}$ is monotone nondecreasing (resp. monotone increasing) if for all $A \subset B$, we have $f(A) \leq f(B)$ (resp. f(A) < f(B)).

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Definition 4.5.3

A function $f: 2^V \to \mathbb{R}$ is monotone nonincreasing (resp. monotone decreasing) if for all $A \subset B$, we have $f(A) \geq f(B)$ (resp. f(A) > f(B)).

Composition of non-decreasing submodular and non-decreasing concave

Theorem 4.5.4

Given two functions, one defined on sets

$$f: 2^V \to \mathbb{R} \tag{4.45}$$

and another continuous valued one:

$$g: \mathbb{R} \to \mathbb{R} \tag{4.46}$$

the composition formed as $h=g\circ f:2^V\to\mathbb{R}$ (defined as h(S)=g(f(S))) is nondecreasing submodular, if g is non-decreasing concave and f is nondecreasing submodular.

Let f and g both be submodular functions on subsets of V and let $(f-g)(\cdot)$ be either monotone non-decreasing or monotone non-increasing Then $h:2^V\to R$ defined by

$$h(A) = \min(f(A), g(A)) \tag{4.47}$$

is submodular.

Proof.

If h(A) agrees with f on both X and Y (or g on both X and Y), and since

$$h(X) + h(Y) = f(X) + f(Y) \ge f(X \cup Y) + f(X \cap Y)$$
 (4.48)

or

$$h(X) + h(Y) = g(X) + g(Y) \ge g(X \cup Y) + g(X \cap Y),$$
 (4.49)

the result (Equation 4.47 being submodular) follows since

$$\frac{f(X) + f(Y)}{g(X) + g(Y)} \ge \min(f(X \cup Y), g(X \cup Y)) + \min(f(X \cap Y), g(X \cap Y))$$

(4.50)

Monotone difference of two functions

...cont.

Otherwise, w.l.o.g., h(X) = f(X) and h(Y) = g(Y), giving

$$h(X) + h(Y) = f(X) + g(Y) \ge f(X \cup Y) + f(X \cap Y) + g(Y) - f(Y) \tag{4.51}$$

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Otherwise, w.l.o.g., h(X) = f(X) and h(Y) = g(Y), giving

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(4.51)

Assume the case where f-g is monotone non-decreasing Hence, $f(X \cup Y) + g(Y) - f(Y) \ge g(X \cup Y)$ giving

$$h(X) + h(Y) \ge g(X \cup Y) + f(X \cap Y) \ge h(X \cup Y) + h(X \cap Y)$$
 (4.52)

What is an easy way to prove the case where f-g is monotone non-increasing?



Saturation via the $\min(\cdot)$ function

Let $f:2^V\to\mathbb{R}$ be a monotone increasing or decreasing submodular function and let α be a constant. Then the function $h:2^V\to\mathbb{R}$ defined by

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is submodular.

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For constant k, we have that (f - k) is non-decreasing (or non-increasing) so this follows from the previous result.

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Note also, $g(a)=\min(k,a)$ for constant k is a non-decreasing concave function, so when f is monotone nondecreasing submodular, we can use the earlier result about composing a monotone concave function with a monotone submodular function to get a version of this.

More on Min - the saturate trick

• In general, the minimum of two submodular functions is not submodular (unlike concave functions, closed under min).

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- In general, the minimum of two submodular functions is not submodular (unlike concave functions, closed under min).
- However, when wishing to maximize two monotone non-decreasing submodular functions f,g, we can define function $h_{\alpha}:2^{V}\to\mathbb{R}$ as

$$h_{\alpha}(A) = \frac{1}{2} \left(\min(\alpha, f(A)) + \min(\alpha, g(A)) \right)$$
 (4.54)

then h_{α} is submodular, and $h_{\alpha}(A) \geq \alpha$ if and only if both $f(A) \geq \alpha$ and $g(A) \geq \alpha$, for constant $\alpha \in \mathbb{R}$.

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This can be useful in many applications. An instance of a <u>submodular</u> <u>surrogate</u> (where we take a non-submodular problem and find a submodular one that can tell us something about it).

Arbitrary functions: difference between submodular funcs.

Theorem 4.5.5

Given an arbitrary set function h, it can be expressed as a difference between two submodular functions (i.e., $\forall h \in 2^V \to \mathbb{R}$, $\exists f, g \text{ s.t. } \forall A, h(A) = f(A) - g(A)$ where both f and g are submodular).

Proof.

Let h be given and arbitrary, and define:

$$\alpha \stackrel{\Delta}{=} \min_{X,Y:X \not\subseteq Y,Y \not\subseteq X} \left(h(X) + h(Y) - h(X \cup Y) - h(X \cap Y) \right) \tag{4.55}$$

If $\alpha \geq 0$ then h is submodular, so by assumption $\alpha < 0$.

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If $\alpha \geq 0$ then h is submodular, so by assumption $\alpha < 0$. Now let f be an arbitrary strict submodular function and define

$$\beta \stackrel{\triangle}{=} \min_{X,Y:X \subseteq Y,Y \subseteq X} \Big(f(X) + f(Y) - f(X \cup Y) - f(X \cap Y) \Big). \tag{4.56}$$

Strict means that $\beta > 0$.

Arbitrary functions as difference between submodular funcs.

...cont.

Define $h': 2^V \to \mathbb{R}$ as

$$h'(A) = h(A) + \frac{|\alpha|}{\beta} f(A)$$
(4.57)

Then h' is submodular (why?), and $h = h'(A) - \frac{|\alpha|}{\beta} f(A)$, a difference between two submodular functions as desired.



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- This is called the gain and is used so often, there are equally as many ways to notate this. I.e., you might see:

$$f(A \cup \{j\}) - f(A) \stackrel{\Delta}{=} \rho_j(A) \tag{4.58}$$

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- We'll use f(j|A).
- Submodularity's diminishing returns definition can be stated as saying that f(j|A) is a monotone non-increasing function of A, since $f(j|A) \ge f(j|B)$ whenever $A \subseteq B$ (conditioning reduces valuation).

Gain Notation

It will also be useful to extend this to sets.

Let A, B be any two sets. Then

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Inspired from information theory notation and the notation used for conditional entropy $H(X_A|X_B) = H(X_A, X_B) - H(X_B)$.

atorial Examples Matrix Rank Examples and Properties

Totally normalized functions

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where $m_g(A) \triangleq \sum_{a \in A} g(a|V \setminus \{a\})$ is a modular function.

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- Then $g(A) = \bar{g}(A) + m_q(A)$.

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where m^+ is the positive part of modular function m. That is, $m^+(A) = \sum_{a \in A} m(a) \mathbf{1}(m(a) > 0)$.

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- Both $\bar{f} + \overline{m_{f-q}^+}$ and $\bar{g} + (-m_{f-q})^+$ are polymatroid functions!
- Thus, any function can be expressed as a difference between two, not only submodular (DS), but polymatroid functions.