Submodular Functions, Optimization, and Applications to Machine Learning

— Spring Quarter, Lecture 19 —

http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563_spring_2018/

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Announcements, Assignments, and Reminders

- Take home final exam (like long homework). Due Friday, June 8th, 4:00pm via our assignment dropbox (https://canvas.uw.edu/courses/1216339/assignments).
- Get started now. At least read through everything and ask any questions you might have.
- As always, if you have any questions about anything, please ask then
 via our discussion board
 (https://canvas.uw.edu/courses/1216339/discussion_topics).
 Can meet at odd hours via zoom (send message on canvas to schedule
 time to chat).

Class Road Map - EE563

- L1(3/26): Motivation, Applications, & Basic Definitions.
- L2(3/28): Machine Learning Apps (diversity, complexity, parameter, learning target, surrogate).
- L3(4/2): Info theory exs, more apps, definitions, graph/combinatorial examples
- L4(4/4): Graph and Combinatorial Examples, Matrix Rank, Examples and Properties, visualizations
- L5(4/9): More Examples/Properties/ Other Submodular Defs., Independence,
- L6(4/11): Matroids, Matroid Examples, Matroid Rank, Partition/Laminar
 Matroids
- L7(4/16): Laminar Matroids, System of Distinct Reps, Transversals, Transversal Matroid, Matroid Representation, Dual Matroids
- L8(4/18): Dual Matroids, Other Matroid Properties, Combinatorial Geometries, Matroids and Greedy.
- L9(4/23): Polyhedra, Matroid Polytopes, Matroids → Polymatroids
- L10(4/29): Matroids → Polymatroids, Polymatroids, Polymatroids and Greedy,

- L11(4/30): Polymatroids, Polymatroids and Greedy
- L12(5/2): Polymatroids and Greedy, Extreme Points, Cardinality Constrained Maximization
- L13(5/7): Constrained Submodular Maximization
- L14(5/9): Submodular Max w. Other Constraints, Cont. Extensions, Lovasz Extension
- L15(5/14): Cont. Extensions, Lovasz Extension, Choquet Integration, Properties
- L16(5/16): More Lovasz extension, Choquet, defs/props, examples, multiliear extension
- L17(5/21): Finish L.E., Multilinear Extension, Submodular Max/polyhedral approaches, Most Violated inequality, Still More on Matroids, Closure/Sat
- L-(5/28): Memorial Day (holiday)
- L18(5/30): Closure/Sat, Fund. Circuit/Dep
- L19(6/6): Fund. Circuit/Dep, Min-Norm-Point Definitions, Review & Support for Min-Norm, Proof that min-norm gives optimal, Computing Min-Norm Vector for B_f maximization.

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- dep function & fundamental circuit of a matroid

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- e-containing x-tight sets: For $x \in P_f$, $\mathcal{D}(x,e) = \{A : e \in A \subseteq E, x(A) = f(A)\} \subseteq \mathcal{D}(x)$.

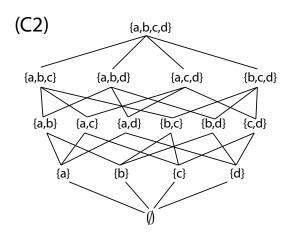
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- Minimal e-containing x-tight set/polymatroidal fundamental circuit/: For $x \in P_f$,

$$dep(x,e) = \begin{cases} \bigcap \{A : e \in A \subseteq E, x(A) = f(A)\} & \text{if } e \in \text{sat}(x) \\ \emptyset & \text{else} \end{cases}$$
$$= \{e' : \exists \alpha > 0, \text{ s.t. } x + \alpha(\mathbf{1}_e - \mathbf{1}_{e'}) \in P_f \}$$

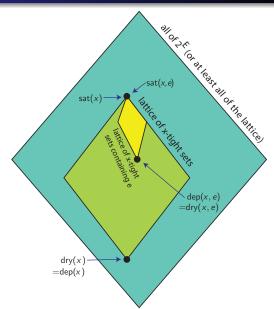
dep and sat in a lattice

- Given some $x \in P_f$,
- The picture on the right summarizes the relationships between the lattices and sublattices.
- Note, $dep(x, e) \supseteq dep(x) = \bigcap \{A : x(A) = f(A)\}.$
- In fact, sat(x, e) = sat(x). Why?
- Example lattice on 4 elements.



dep and sat in a lattice

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- We saw that SFM can be used to solve most violated inequality problems for a given $x \in P_f$ and, in general, SFM can solve the question "Is $x \in P_f$ " by seeing if x violates any inequality (if the most violated one is negative, solution to SFM, then $x \in P_f$).
- Unconstrained SFM, $\min_{A\subseteq V} f(A)$ solves many other problems as well in combinatorial optimization, machine learning, and other fields.
- We next study an algorithm, the "Fujishige-Wolfe Algorithm", or what
 is known as the "Minimum Norm Point" algorithm, which is an active
 set method to do this, and one that in practice works about as well as
 anything else people (so far) have tried for general purpose SFM.
- Note special case SFM can be much faster.

Min-Norm Point: Definition

Consider the optimization:

$$minimize ||x||_2^2 (19.1a)$$

subject to
$$x \in B_f$$
 (19.1b)

where B_f is the base polytope of submodular f, and $||x||_2^2 = \sum_{e \in E} x(e)^2$ is the squared 2-norm. Let x^* be the optimal solution.

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 Note, x* is the unique optimal solution since we have a strictly convex objective over a set of convex constraints.

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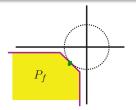
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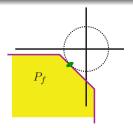
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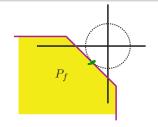
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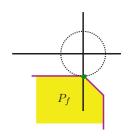
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- x^* is called the minimum norm point of the base polytope.

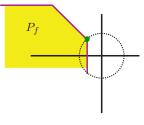
Min-Norm Point: Examples

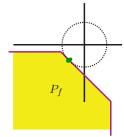








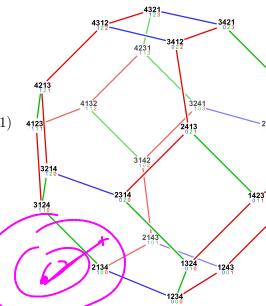




 Consider submodular function $f: 2^V \to \mathbb{R}$ with n = |V| = 4, and for $X \subseteq V$, concave q,

$$f(X) = g(|X|) = \sum_{i=1}^{|X|} (n-i+1)$$
 4123
$$= |X| \left(n - \frac{|X|-1}{2}\right)$$
 3

• Then B_f is a 3D polytope, and in this particular case gives us a permutahedron with 24 distinct extreme points, on the right (from wikipedia).



Fund. Circuit/Dep

Min-Norm Point and Submodular Function Minimization

• Given optimal solution x^* to $[\min ||x||_2^2$ s.t. $x \in B_f]$, and consider:

$$y^* = x^* \land 0 = (\min(x^*(e), 0) | e \in E), \tag{19.2}$$

$$A_{-} = \{e : x^{*}(e) < 0\}, \tag{19.3}$$

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• Thus, we immediately have that:

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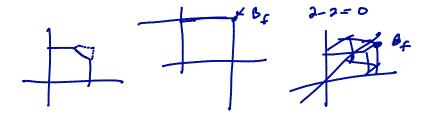
- It turns out, these quantities will solve the submodular function minimization problem, as we now show.
- The proof is nice since it uses the tools we've been recently developing.

More about the base B_f

Theorem 19.5.1

Fund. Circuit/Dep

Let f be a polymatroid function and suppose that E can be partitioned into (E_1,E_2,\ldots,E_k) such that $f(A)=\sum_{i=1}^k f(A\cap E_i)$ for all $A\subseteq E$, and k is maximum. Then the base polytope $B_f = \{x \in P_f : x(E) = f(E)\}$ (the *E*-tight subset of P_f) has dimension |E| - k.



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• In fact, every $x \in P_f$ is dominated by $x \leq y \in B_f$.

Theorem 19.5.2

If $x \in P_f$ and T is tight for x (meaning x(T) = f(T)), then there exists $y \in B_f$ with $x \le y$ and y(e) = x(e) for $e \in T$.



$$\chi(\iota_i) = \chi(\iota_i) = +(\iota_i)$$
 $T = \{e_i\}$
 $\chi(\iota_i) = \chi(\iota_i)$

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• In fact, every $x \in P_f$ is dominated by $x \leq y \in B_f$.

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If $x \in P_f$ and T is tight for x (meaning x(T) = f(T)), then there exists $y \in B_f$ with $x \leq y$ and y(e) = x(e) for $e \in T$.

We leave the proof as an exercise.

Review from Lecture 12

Fund. Circuit/Dep

The following slide repeats Theorem 12.3.2 from lecture 12 and is one of the most important theorems in submodular theory.

A polymatroid function's polyhedron is a polymatroid.

Theorem 19.5.1

Fund. Circuit/Dep

Let f be a submodular function defined on subsets of E. For any $x \in \mathbb{R}^E$, we have:

$$\operatorname{rank}(x) = \max\left(y(E) : y \le x, y \in \underline{P_f}\right) = \min\left(x(A) + f(E \setminus A) : A \subseteq E\right) \tag{19.1}$$

Essentially the same theorem as Theorem 10.4.1, but note P_f rather than

 P_f^+ . Taking x=0 we get:

Corollary 19.5.2

Let f be a submodular function defined on subsets of E. We have:

$$rank(0) = \max(y(E) : y \le 0, y \in P_f) = \min(f(A) : A \subseteq E)$$
 (19.2)

Modified max-min theorem

• Min-max theorem (Thm 12.3.2) restated for x = 0.

$$\max\{y(E)|y \in P_f, y \le 0\} = \min\{f(X)|X \subseteq V\}$$
 (19.7)

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Theorem 19.5.3 (Edmonds-1970)

$$\min\left\{f(X)|X\subseteq E\right\} = \max\left\{x^{-}(E)|x\in B_f\right\} \tag{19.8}$$

where $x^{-}(e) = \min \{x(e), 0\}$ for $e \in E$.

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Theorem 19.5.3 (Edmonds-1970)

$$\sqrt{\min\{f(X)|X\subseteq E\}} = \max\{x^{-}(E)|x\in B_f\}$$
where $x^{-}(e) = \min\{x(e), 0\}$ for $e\in E$.

Proof via the Lovász ext.

$$\min \{ f(X) | X \subseteq E \} = \min_{w \in [0,1]^E} \tilde{f}(w) = \min_{w \in [0,1]^E} \max_{x \in P_f} w^{\mathsf{T}} x \tag{19.9}$$

$$= \min_{w \in [0,1]^E} \max_{x \in B_f} w^{\mathsf{T}} x \tag{19.10}$$

$$w \in [0,1]^E \xrightarrow{x \in B_f}$$

$$= \max_{x \in B_f} \min_{w \in [0,1]^E} w^{\mathsf{T}} x \tag{19.11}$$

$$= \max_{x \in B_f} x^-(E)$$
 (19.12)

Alternate proof of modified max-min theorem

We start directly from Theorem 12.3.2.

$$\max(y(E): y \le 0, y \in P_f) = \min(f(A): A \subseteq E)$$
(19.16)

Given $y \in \mathbb{R}^E$, define $y^- \in \mathbb{R}^E$ with $y^-(e) = \min\{y(e), 0\}$ for $e \in E$.

$$\max(y(E): y \le 0, y \in P_f) = \max(y^-(E): y \le 0, y \in P_f)$$
 (19.17)

$$= \max \left(y^{-}(E) : y \in P_f \right) \tag{19.18}$$

$$= \max (y^{-}(E) : y \in B_f)$$
 (19.19)

The first equality follows since $y \leq 0$. The second equality (together with the first) shown on following slide. The third equality follows since for any $x \in P_f$ there exists a $y \in B_f$ with $x \leq y$ (follows from Theorem 19.5.2).

Alternate proof of modified max-min theorem

Consider the following two problems:

$$\max \sum_{e \in E} y(e) \qquad (19.20a) \qquad \max \sum_{e \in E} \min(y(e), x(e)) \qquad (19.21a)$$
s.t. $y \le x \qquad (19.20b) \qquad \text{s.t. } y \in P \qquad (19.21b)$

- Solutions identical cost. Let y_1^* be l.h.s. OPT and y_2^* be r.h.s. OPT.
- Consider y_1^* as r.h.s. solution and suppose it is worse than r.h.s. OPT:

$$\sum_{e \in E} \min(y_1^*(e), x(e)) < \sum_{e \in E} \min(y_2^*(e), x(e))$$
(19.22)

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 (19.20a)
$$\max \sum_{e \in E} \min(y(e), x(e))$$
 (19.21a)
$$y \in P$$
 (19.20c)
$$\text{s.t. } y \in P$$
 (19.21b)

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(19.22)

• Hence, $\exists e' \text{ s.t. } y_1^*(e') < \min(y_2^*(e'), x(e'))$. Recall $y_1^*, y_2^* \in P$.

Alternate proof of modified max-min theorem

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- ullet Solutions identical cost. Let y_1^* be l.h.s. OPT and y_2^* be r.h.s. OPT.
- ullet Consider y_1^* as r.h.s. solution and suppose it is worse than r.h.s. OPT:

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(19.22)

- $\bullet \ \ \text{Hence, } \exists e' \ \text{s.t.} \ \ y_1^*(e') < \min(y_2^*(e'), x(e')). \ \ \text{Recall} \ \ y_1^*, y_2^* \in P.$
- This implies $\sum_{e\neq e'} y_1^*(e) + y_1^*(e') < \sum_{e\neq e'} y_1^*(e) + \min(y_2^*(e'), x(e'))$, better feasible solution to l.h.s., contradicting y_1^* 's optimality for l.h.s.

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$$\max \sum_{e \in E} y(e)$$
 (19.20a)
$$\max \sum_{e \in E} \min(y(e), x(e))$$
 (19.21a)
$$y \in P$$
 (19.20c)
$$\sup_{e \in E} \sum_{e \in E} \min(y(e), x(e))$$
 (19.21b)

- ullet Solutions identical cost. Let y_1^* be l.h.s. OPT and y_2^* be r.h.s. OPT.
- Similarly, consider y_2^* as l.h.s. solution, suppose worse than l.h.s. OPT

$$\sum_{e \in F} y_2^*(e) < \sum_{e \in F} y_1^*(e) \tag{19.22}$$

Alternate proof of modified max-min theorem

Consider the following two problems:

$$\max \sum_{e \in E} y(e)$$
 (19.20a)
$$\max \sum_{e \in E} \min(y(e), x(e))$$
 (19.21a)
$$y \in P$$
 (19.20c)
$$\sup_{e \in E} \sum_{e \in E} \min(y(e), x(e))$$
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$$\sum_{e \in E} y_2^*(e) < \sum_{e \in E} y_1^*(e) \tag{19.22}$$

• Then $\exists e'$ such that $y_2^*(e') < y_1^*(e') \le x(e')$.

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Consider the following two problems:

$$\max \sum_{e \in E} y(e)$$
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 (19.21a)
$$y \in P$$
 (19.20c)
$$\text{s.t. } y \in P$$
 (19.21b)

- Solutions identical cost. Let y_1^* be l.h.s. OPT and y_2^* be r.h.s. OPT.
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- Then $\exists e'$ such that $y_2^*(e') < y_1^*(e') \le x(e')$.
- This implies that replacing $y_2^*(e')$'s value with $y_1^*(e')$ is still feasible for r.h.s. but better, contradicting y_2^* 's optimality.

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- Solutions identical cost. Let y_1^* be l.h.s. OPT and y_2^* be r.h.s. OPT.
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- Then $\exists e'$ such that $y_2^*(e') < y_1^*(e') \le x(e')$.
- This implies that replacing $y_2^*(e')$'s value with $y_1^*(e')$ is still feasible for r.h.s. but better, contradicting y_2^* 's optimality.
- Hence, from previous slide, taking x = 0, $\max(y(E) : y \le 0, y \in P_f) =$ $\max(y^{-}(E):y\in P_f) = \max(y^{-}(E):y\in B_f)$

$\min\left\{w^{\intercal}x:x\in B_f\right\}$

Fund. Circuit/Dep

 \bullet Recall that the greedy algorithm solves, for $w \in \mathbb{R}_+^E$

$$\max\{w^{\mathsf{T}}x|x\in P_f\} = \max\{w^{\mathsf{T}}x|x\in B_f\}$$
 (19.23)

since for all $x \in P_f$, there exists $y \ge x$ with $y \in B_f$.

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since for all $x \in P_f$, there exists $y \ge x$ with $y \in B_f$.

• For arbitrary $w \in \mathbb{R}^E$, greedy algorithm will also solve:

$$\max\left\{w^{\mathsf{T}}x|x\in B_f\right\} \tag{19.24}$$

$\min \{ w^{\intercal} x : x \in B_f \}$

• Recall that the greedy algorithm solves, for $w \in \mathbb{R}^E_+$

$$\max\{w^{\mathsf{T}}x|x\in P_f\} = \max\{w^{\mathsf{T}}x|x\in B_f\}$$
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since for all $x \in P_f$, there exists $y \ge x$ with $y \in B_f$.

• For arbitrary $w \in \mathbb{R}^E$, greedy algorithm will also solve:

$$\max \left\{ w^{\mathsf{T}} x | x \in B_f \right\}$$

$$\underset{\left(w_1\right) = +(w_1)}{\max \left\{ w^{\mathsf{T}} x | x \in B_f \right\}}$$

$$\underset{\left(w_1\right) = +(w_1)}{\max \left\{ -w^{\mathsf{T}} x | x \in B_f \right\}}$$

$$\underset{\left(w_1\right) = +(w_1)}{\min \left\{ w^{\mathsf{T}} x | x \in B_f \right\}}$$

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$$\min \{w^{\mathsf{T}}x|x \in B_f\} = \max \{-w^{\mathsf{T}}x|x \in B_f\}$$
 (19.25) edy algorithm-using ordering (e_1, e_2, \dots, e_m) such that

$$w(e_1) \le w(e_2) \le \dots \le w(e_m) \tag{19.26}$$

will solve l.h.s. of Equation (19.25).

Greedy solves $\max \{w \mid x \mid x \in B_f\}$ for arbitrary $w \in \mathbb{R}^E$

Let f(A) be arbitrary submodular function, and f(A) = f'(A) - m(A)where f' is polymatroidal, and $w \in \mathbb{R}^E$.

$$\max \{w^{\mathsf{T}}x | x \in B_f\} = \max \{w^{\mathsf{T}}x | x(A) \leq f(A) \, \forall A, x(E) = f(E)\}$$

$$= \max \{w^{\mathsf{T}}x | x(A) \leq f'(A) - m(A) \, \forall A, x(E) = f'(E) - m(E)\}$$

$$= \max \{w^{\mathsf{T}}x | x(A) + m(A) \leq f'(A) \, \forall A, x(E) + m(E) = f'(E)\}$$

$$= \max \{w^{\mathsf{T}}x + w^{\mathsf{T}}m |$$

$$x(A) + m(A) \leq f'(A) \, \forall A, x(E) + m(E) = f'(E)\} - w^{\mathsf{T}}m$$

$$= \max \{w^{\mathsf{T}}y | y \in B_{f'}\} - w^{\mathsf{T}}m$$

$$= w^{\mathsf{T}}y^* - w^{\mathsf{T}}m = w^{\mathsf{T}}(y^* - m)$$

$$= w^{\mathsf{T}}y^* - w^{\mathsf{T}}m = w^{\mathsf{T}}(y^* - m)$$

where y = x + m, so that $x^* = y^* - m$.

So y^* uses greedy algorithm with positive orthant $B_{f'}$. To show, we use Theorem 11.4.1 in Lecture 11, but we don't require y > 0, and don't stop when w goes negative to ensure $y^* \in B_{f'}$. Then when we subtract off m from y^* , we get solution to the original problem.

Min-Norm Point and Submodular Function Minimization

• Given optimal solution x^* to $[\min ||x||_2^2$ s.t. $x \in B_f$], and consider:

$$y^* = x^* \land 0 = (\min(x^*(e), 0) | e \in E), \tag{19.2}$$

$$A_{-} = \{e : x^{*}(e) < 0\}, \tag{19.3}$$

$$A_0 = \{e : x^*(e) \le 0\}. \tag{19.4}$$

Thus, we immediately have that:

$$A_{-} \subseteq A_0 \tag{19.5}$$

and that

$$x^*(A_-) = x^*(A_0) = y^*(A_-) = y^*(A_0)$$
(19.6)

- It turns out, these quantities will solve the submodular function minimization problem, as we now show.
- The proof is nice since it uses the tools we've been recently developing.

Theorem 19.6.1

Let x^* , y^* , A_- , and A_0 be as given. Then y^* is a maximizer of the l.h.s. of Eqn. (19.7). Moreover, A_- is the unique minimal minimizer of f and A_0 is the unique maximal minimizer of f.

Proof.

Fund. Circuit/Dep

• First note, since $x^* \in B_f$, we have $x^*(E) = f(E)$, meaning $\operatorname{sat}(x^*) = E$. Thus, we may consider any $e \in E$ within $\operatorname{dep}(x^*, e)$.



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Let x^* , y^* , A_- , and A_0 be as given. Then y^* is a maximizer of the l.h.s. of Eqn. (19.7). Moreover, A_{-} is the unique minimal minimizer of f and A_{0} is the unique maximal minimizer of f.

Proof.

- First note, since $x^* \in B_f$, we have $x^*(E) = f(E)$, meaning $\operatorname{sat}(x^*) = E$. Thus, we may consider any $e \in E$ within $dep(x^*, e)$.
- Consider any pair (e, e') with $e \in A_-$ and $e' \in dep(x^*, e)$. Then $x^*(e) < 0$, and $\exists \alpha > 0$ s.t. $x^* + \alpha \mathbf{1}_e - \alpha \mathbf{1}_{e'} \in P_f$.

Theorem 19.6.1

Let x^* , y^* , A_- , and A_0 be as given. Then y^* is a maximizer of the l.h.s. of Eqn. (19.7). Moreover, A_- is the unique minimal minimizer of f and A_0 is the unique maximal minimizer of f.

Proof.

- First note, since $x^* \in B_f$, we have $x^*(E) = f(E)$, meaning $\operatorname{sat}(x^*) = E$. Thus, we may consider any $e \in E$ within $\operatorname{dep}(x^*, e)$.
- Consider any pair (e,e') with $e\in A_-$ and $e'\in \operatorname{dep}(x^*,e)$. Then $x^*(e)<0$, and $\exists \alpha>0$ s.t. $x^*+\alpha \mathbf{1}_e-\alpha \mathbf{1}_{e'}\in P_f$.
- We have $x^*(E)=f(E)$ and x^* is minimum in I2 sense. We have $(x^*+\alpha \mathbf{1}_e-\alpha \mathbf{1}_{e'})\in P_f$, and in fact

$$(x^* + \alpha \mathbf{1}_e - \alpha \mathbf{1}_{e'})(E) = x^*(E) + \alpha - \alpha = f(E)$$
so $x^* + \alpha \mathbf{1}_e - \alpha \mathbf{1}_{e'} \in B_f$ also. (19.27)

Min-Norm Point and SFM

• Then
$$(x^* + \alpha \mathbf{1}_e - \alpha \mathbf{1}_{e'})(E)$$

= $x^*(E \setminus \{e, e'\}) + \underbrace{(x^*(e) + \alpha)}_{x^*_{\mathsf{new}}(e)} + \underbrace{(x^*(e') - \alpha)}_{x^*_{\mathsf{new}}(e')} = f(E).$

Min-Norm Point and SFM

- Then $(x^* + \alpha \mathbf{1}_e \alpha \mathbf{1}_{e'})(E)$ $= x^*(E \setminus \{e, e'\}) + \underbrace{(x^*(e) + \alpha)}_{x^*_{\mathsf{new}}(e)} + \underbrace{(x^*(e') - \alpha)}_{x^*_{\mathsf{new}}(e')} = f(E).$
- Minimality of $x^* \in B_f$ in 12 sense requires that, with such an $\alpha > 0$,

$$\left(x^*(e)\right)^2 + \left(x^*(e')\right)^2 < \left(x^*_{\mathsf{new}}(e)\right)^2 + \left(x^*_{\mathsf{new}}(e')\right)^2$$

... proof of Thm. 19.6.1 cont.

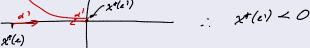
- Then $(x^* + \alpha \mathbf{1}_e \alpha \mathbf{1}_{e'})(E)$ $= x^*(E \setminus \{e, e'\}) + (x^*(e) + \alpha) + (x^*(e') - \alpha) = f(E).$
- Minimality of $x^* \in B_f$ in l2 sense requires that, with such an $\alpha > 0$, $(x^*(e))^2 + (x^*(e'))^2 < (x^*_{\mathsf{new}}(e))^2 + (x^*_{\mathsf{new}}(e'))^2$
- Given that $e \in A_-$, $x^*(e) < 0$. Thus, if $x^*(e') > 0$, we would have $(x^*(e) + \alpha')^2 + (x^*(e') - \alpha')^2 < (x^*(e))^2 + (x^*(e'))^2$, for some $0 < \alpha' \le \alpha$, contradicting the optimality of x^* .



: x7/e) = 0

Min-Norm Point and SFM

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- If $x^*(e') = 0$, we would have $(x^*(e) + \alpha)^2 + (\alpha')^2 < (x^*(e))^2$, for any $0 < \alpha' < |x^*(e)|$ by convexity, again contradicting optimality of x^* .



- Then $(x^* + \alpha \mathbf{1}_e \alpha \mathbf{1}_{e'})(E)$ $= x^*(E \setminus \{e, e'\}) + (x^*(e) + \alpha) + (x^*(e') - \alpha) = f(E).$ $x_{-}^*(e)$ $x_{-}^*(e')$
- Minimality of $x^* \in B_f$ in I2 sense requires that, with such an $\alpha > 0$, $(x^*(e))^2 + (x^*(e'))^2 < (x^*_{\mathsf{new}}(e))^2 + (x^*_{\mathsf{new}}(e'))^2$
- Given that $e \in A_-$, $x^*(e) < 0$. Thus, if $x^*(e') > 0$, we would have $(x^*(e) + \alpha')^2 + (x^*(e') - \alpha')^2 < (x^*(e))^2 + (x^*(e'))^2$, for some $0 < \alpha' \le \alpha$, contradicting the optimality of x^* .
- If $x^*(e') = 0$, we would have $(x^*(e) + \alpha)^2 + (\alpha')^2 < (x^*(e))^2$, for any $0 < \alpha' < |x^*(e)|$ by convexity, again contradicting optimality of x^* .
- Thus, we must have $x^*(e') < 0$ (strict negativity).

... proof of Thm. 19.6.1 cont.

• Thus, for a pair (e, e') with $e' \in dep(x^*, e)$ and $e \in A_-$, we have x(e') < 0 and hence $e' \in A_-$.

Min-Norm Point and SFM

- Thus, for a pair (e,e') with $e' \in dep(x^*,e)$ and $e \in A_-$, we have x(e') < 0 and hence $e' \in A_-$.
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Min-Norm Point and SFM

- Thus, for a pair (e, e') with $e' \in dep(x^*, e)$ and $e \in A_-$, we have x(e') < 0 and hence $e' \in A_-$.
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- A very similar argument can show that, $\forall e \in A_0$, we have $dep(x^*,e) \subseteq A_0$.

Min-Norm Point and SFM

- Thus, for a pair (e, e') with $e' \in dep(x^*, e)$ and $e \in A_-$, we have x(e') < 0 and hence $e' \in A_-$.
- Hence, $\forall e \in A_-$, we have $dep(x^*, e) \subseteq A_-$.
- A very similar argument can show that, $\forall e \in A_0$, we have $dep(x^*,e) \subseteq A_0$.
- Also, recall that $e \in dep(x^*, e)$.

...proof of Thm. 19.6.1 cont.

ullet Therefore, we have $\cup_{e\in A_-} \operatorname{dep}(x^*,e) = A_-$ and $\cup_{e\in A_0} \operatorname{dep}(x^*,e) = A_0$

- Therefore, we have $\bigcup_{e \in A_-} \operatorname{dep}(x^*, e) = A_-$ and $\bigcup_{e \in A_0} \operatorname{dep}(x^*, e) = A_0$
- le., $\{\operatorname{dep}(x^*,e)\}_{e\in A_-}$ is cover for A_- , as is $\{\operatorname{dep}(x^*,e)\}_{e\in A_0}$ for A_0 .

Min-Norm Point and SFM

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- \bullet dep (x^*,e) is minimal tight set containing e, meaning $x^*(\operatorname{dep}(x^*,e)) = f(\operatorname{dep}(x^*,e))$, and since tight sets are closed under union, we have that A_{-} and A_{0} are also tight, meaning:

Min-Norm Point and SFM

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$$x^*(A_-) = f(A_-) \tag{19.28}$$

Min-Norm Point and SFM

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$$x^*(A_-) = f(A_-) (19.28)$$

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$$x^*(A_0) = f(A_0) (19.29)$$

$$x^*(A_-) = x^*(A_0) = y^*(E) = y^*(A_0) + \underbrace{y^*(E \setminus A_0)}$$
 (19.30)

Min-Norm Point and SFM

... proof of Thm. 19.6.1 cont.

- Therefore, we have $\bigcup_{e \in A_-} \operatorname{dep}(x^*, e) = A_-$ and $\bigcup_{e \in A_0} \operatorname{dep}(x^*, e) = A_0$
- le., $\{\operatorname{dep}(x^*,e)\}_{e\in A}$ is cover for A_- , as is $\{\operatorname{dep}(x^*,e)\}_{e\in A_0}$ for A_0 .
- $dep(x^*, e)$ is minimal tight set containing e, meaning $x^*(\operatorname{dep}(x^*,e)) = f(\operatorname{dep}(x^*,e))$, and since tight sets are closed under union, we have that A_{-} and A_{0} are also tight, meaning:

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... proof of Thm. 19.6.1 cont.

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and therefore, all together we have

$$f(A_{-}) = f(A_{0}) = x^{*}(A_{-}) = x^{*}(A_{0}) = y^{*}(E)$$
 (19.31)

Min-Norm Point and SFM

... proof of Thm. 19.6.1 cont.

- Therefore, we have $\bigcup_{e \in A_-} \operatorname{dep}(x^*, e) = A_-$ and $\bigcup_{e \in A_0} \operatorname{dep}(x^*, e) = A_0$
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- $dep(x^*, e)$ is minimal tight set containing e, meaning $x^*(\operatorname{dep}(x^*,e)) = f(\operatorname{dep}(x^*,e))$, and since tight sets are closed under union, we have that A_{-} and A_{0} are also tight, meaning:

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$$x^*(A_-) = x^*(A_0) = y^*(E) = y^*(A_0) + \underbrace{y^*(E \setminus A_0)}_{}$$
 (19.30)

and therefore, all together we have

$$f(A_{-}) = f(A_{0}) = x^{*}(A_{-}) = x^{*}(A_{0}) = y^{*}(E)$$
(19.31)

• Hence, $f(A_{-}) = f(A_{0})$, meaning A_{-} and A_{0} have the same valuation, but we have not yet shown they are the minimizers of the submodular function, nor that they are, resp. the maximal and minimal minimizers.

Min-Norm Point and SFM

... proof of Thm. 19.6.1 cont.

• Now, y^* is feasible for the l.h.s. of Eqn. (19.7) (recall, which is $\max\{y(E)|y \in P_f, y \le 0\} = \min\{f(X)|X \subseteq V\}.$

Min-Norm Point and SFM

... proof of Thm. 19.6.1 cont.

• Now, y^* is feasible for the l.h.s. of Eqn. (19.7) (recall, which is $\max\{y(E)|y\in P_f,y\leq 0\}=\min\{f(X)|X\subseteq V\}$). This follows since, we have $y^* = x^* \wedge 0 \leq 0$, and since $x^* \in B_f \subset P_f$, and $y^* \leq x^*$ and P_f is down-closed, we have that $y^* \in P_f$.

Min-Norm Point and SFM

- Now, y^* is feasible for the l.h.s. of Eqn. (19.7) (recall, which is $\max\{y(E)|y\in P_f,y\leq 0\}=\min\{f(X)|X\subseteq V\}$). This follows since, we have $y^* = x^* \land 0 \le 0$, and since $x^* \in B_f \subset P_f$, and $y^* \le x^*$ and P_f is down-closed, we have that $y^* \in P_f$.
- Also, for any $y \in P_f$ with $y \leq 0$ and for any $X \subseteq E$, we have y(E) < y(X) < f(X).

Min-Norm Point and SFM

- Now, y^* is feasible for the l.h.s. of Eqn. (19.7) (recall, which is $\max\{y(E)|y\in P_f,y\leq 0\}=\min\{f(X)|X\subseteq V\}$). This follows since, we have $y^* = x^* \land 0 \le 0$, and since $x^* \in B_f \subset P_f$, and $y^* \le x^*$ and P_f is down-closed, we have that $y^* \in P_f$.
- Also, for any $y \in P_f$ with $y \leq 0$ and for any $X \subseteq E$, we have y(E) < y(X) < f(X).
- Hence, we have found a feasible for l.h.s. of Eqn. (19.7), $y^* \leq 0$, $y^* \in P_f$, so $y^*(E) \leq f(X)$ for all X.

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- Considering Eqn. (19.28), we have found sets A_{-} and A_{0} with tightness in Eqn. (19.7), meaning $y^*(E) = f(A_-) = f(A_0)$.

$$f(A_{-})=f(A_{0})=mh(f(x)|x\leq v)$$

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Min-Norm Point Definitions Review & Support for Min-Norm Proof that min-norm gives optimal Computing Min-Norm Vector for

Min-Norm Point and SFM

...proof of Thm. 19.6.1 cont.

 \bullet We next show that, not only are they minimizers, but A_- is the unique minimal and A_0 is the unique maximal minimizer of f



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• Hence, A_{-} must be the unique minimal minimizer of f, and A_{0} is the unique maximal minimizer of f.



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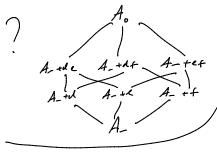
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- This is currently the best practical algorithm for general purpose submodular function minimization.
- But its underlying lower-bound strong poly complexity is unknown.

• Recall, that the set of minimizers of f forms a lattice.

Min-norm point and other minimizers of f

- ullet Recall, that the set of minimizers of f forms a lattice.
- Q: If we take any A with $A_- \subset A \subset A_0$, is A also a minimizer? No



$$A_{1} = \{a_{1}, c_{1}\}$$
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Theorem 19.6.2

Fund. Circuit/Dep

Let $A \subseteq E$ be any minimizer of submodular f, and let x^* be the minimum-norm point. Then A can be expressed in the form:

$$A = A_{-} \cup \bigcup_{a \in A_{m}} \operatorname{dep}(x^{*}, a)$$
 (19.34)

for some set $A_m \subseteq A_0 \setminus A_-$. Conversely, for any set $A_m \subseteq A_0 \setminus A_-$, then $A \triangleq A_- \cup \bigcup_{a \in A_-} \operatorname{dep}(x^*, a)$ is a minimizer.

proof of Thm. 19.6.2.

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- Hence, for any $a \in A$, $dep(x^*, a) \subseteq A$.
- This means that $\bigcup_{a \in A} \operatorname{dep}(x^*, a) = A$.
- Since $A_- \subseteq A \subseteq A_0$, then $\exists A_m \subseteq A \setminus A_-$ such that

$$A = \bigcup_{a \in A_{-}} \operatorname{dep}(x^{*}, a) \cup \bigcup_{a \in A_{m}} \operatorname{dep}(x^{*}, a) = A_{-} \cup \bigcup_{a \in A_{m}} \operatorname{dep}(x^{*}, a)$$

proof of Thm. 19.6.2.

Fund. Circuit/Dep

• Conversely, consider any set $A_m \subseteq A_0 \setminus A_-$, and define A as

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 Then since A is a union of tight sets, A is also a tight set, and we have $f(A) = x^*(A).$



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Therefore, we can generate the entire lattice of minimizers of f starting from A_{-} and A_{0} given access to $dep(x^{*}, e)$.

On a unique minimizer f

• Note that if f(e|A) > 0, $\forall A \subseteq E$ and $e \in E \setminus A$, then we have $A_{-}=A_{0}$ (there is one unique minimizer).

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- On the other hand, if $A_- = A_0$, it does not imply f(e|A) > 0 for all $A \subseteq E \setminus \{e\}.$
- If $A_- = A_0$ then certainly $f(e|A_0) > 0$ for $e \in E \setminus A_0$ and $-f(e|A_0 \setminus \{e\}) > 0$ for all $e \in A_0$.

Fund. Circuit/Dep

Duality: convex minimization of L.E. and min-norm alg.

• Let f be a submodular function with \tilde{f} it's Lovász extension. Then the following two problems are duals (Bach-2013):

$$\begin{array}{ll}
\text{minimize } \tilde{f}(w) + \frac{1}{2} \|w\|_2^2 \\
w \in \mathbb{R}^V
\end{array} (19.36) \qquad \begin{array}{ll}
\text{maximize} & -\|x\|_2^2 \\
\text{subject to} & x \in B_f
\end{array} (19.37a)$$

where $B_f = P_f \cap \{x \in \mathbb{R}^V : x(V) = f(V)\}$ is the base polytope of submodular function f, and $||x||_2^2 = \sum_{e \in V} x(e)^2$ is squared 2-norm.

- Equation (19.36) is related to proximal methods to minimize the Lovász extension (see Parikh&Boyd, "Proximal Algorithms" 2013).
- Equation (19.37b) is solved by the minimum-norm point algorithm (Wolfe-1976, Fujishige-1984, Fujishige-2005, Fujishige-2011) is (as we will see) essentially an active-set procedure for quadratic programming, and uses Edmonds's greedy algorithm to make it efficient.
- Unknown strongly poly worst-case running time, although in practice it usually performs quite well (see below).

• Given points set $P = \{p_1, p_2, \dots, p_k\}$ with $p_i \in \mathbb{R}^V$, let $\operatorname{conv} P$ be the convex hull of P, i.e.,

$$\operatorname{conv} P \triangleq \left\{ \sum_{i=1}^{k} \lambda_i p_i : \sum_{i} \lambda_i = 1, \ \lambda_i \ge 0, i \in [k] \right\}.$$
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• For a set of points $Q = \{q_1, q_2, \dots, q_k\}$, with $q_i \in \mathbb{R}^V$, we define aff Q to be the affine hull of Q, i.e.:

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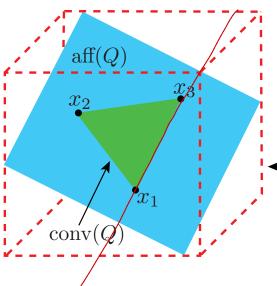
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ullet A set of points Q is affinely independent if no point in Q belows to the affine hull of the remaining points.

Convex vs. Affine hull, geometry



$$\forall i, x_i \in \mathbb{R}^3$$

$$Q = \{x_1, x_2, x_3\}$$

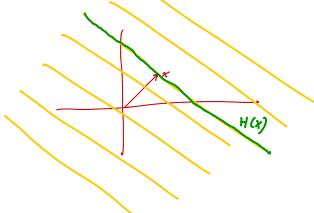
$$x_1, x_2, x_3 \text{ coplanar}$$

 $\overline{\operatorname{span}}(Q)$

H(x): Orthogonal x-containing hyperplane

• Define H(x) as the hyperplane that is orthogonal to the line from 0 to x, while also containing x, i.e.

$$H(x) \triangleq \left\{ y \in \mathbb{R}^V \mid x^{\mathsf{T}} y = \|x\|_2^2 \right\} \tag{19.40}$$

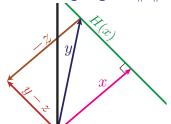


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Any set $\{y \in \mathbb{R}^V | x^\intercal y = c\}$ is orthogonal to the line from 0 to x. This follows since, for constant z, $\{y:(y-z)^{\mathsf{T}}x=0\}=$ $\{y: y^{\mathsf{T}}x = z^{\mathsf{T}}x\}$ is hyperplane orthogonal to x translated by z. Take $c = z^{T}x$ for result, and z = x, giving $c = ||x||^2$, to contain x.

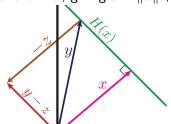


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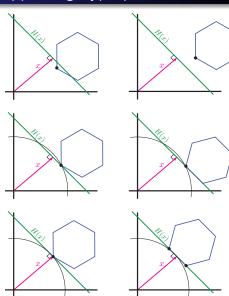
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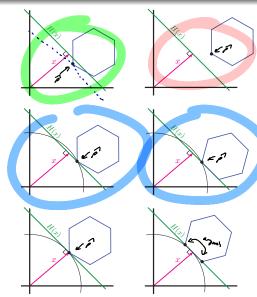


 $\bullet \ H(x) = \Big\{ y \in \mathbb{R}^V | x^\intercal y = \|x\|_2^2 \Big\},$ any $z \in H(x)$ has $x^\intercal z = x^\intercal x.$

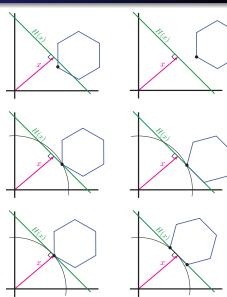


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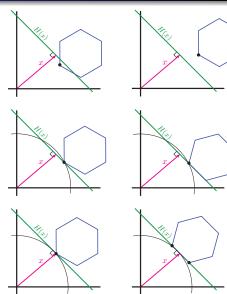
 \bullet Consider $\operatorname{conv} P$ polytope for points $P = \{p_1, p_2, ...\}$, and $\hat{p} \in \operatorname{argmin}_{p \in P} x^{\mathsf{T}} p$. TL: $x^{\mathsf{T}}\hat{p} < x^{\mathsf{T}}x; \mathsf{TR}: x^{\mathsf{T}}\hat{p} > x^{\mathsf{T}}x;$ middle row: $x^{\mathsf{T}}p = x^{\mathsf{T}}x$.



- $\bullet \ H(x) = \Big\{ y \in \mathbb{R}^V | x^\intercal y = \|x\|_2^2 \Big\},$ any $z \in H(x)$ has $x^\intercal z = x^\intercal x.$
- Consider conv P polytope for points $P = \{p_1, p_2, \ldots\}$, and $\hat{p} \in \operatorname{argmin}_{p \in P} x^{\mathsf{T}} p$. TL: $x^{\mathsf{T}} p < x^{\mathsf{T}} x$; TR: $x^{\mathsf{T}} p > x^{\mathsf{T}} x$; middle row: $x^{\mathsf{T}} p = x^{\mathsf{T}} x$.
- Bottom Row: In Algo, x is chosen so that if $x^{\mathsf{T}}\hat{p} = x^{\mathsf{T}}x$ then H(x) separates P from the origin, and x is the min 2-norm point. Notice that $x^{\mathsf{T}}p \geq x^{\mathsf{T}}x$ for all $p \in P$.



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- Middle/bottom row: H(x) is a supporting hyperplane of $\operatorname{conv} P$ (contained, touching).



Notation

Fund. Circuit/Dep

• The line between x and y: given two points $x, y \in \mathbb{R}^V$, let $(x,y) \triangleq \{\lambda x + (x,y) = \lambda \in [0,1]\}. \text{ Hence, } [x,y] = \operatorname{conv}\{x,y\}.$

Notation

- The line between x and y: given two points $x, y \in \mathbb{R}^V$, let $[x,y] \triangleq \{\lambda x + (1-\lambda y) : \lambda \in [0,1]\}$. Hence, $[x,y] = \operatorname{conv}\{x,y\}$.
- Note, if we wish to minimize the 2-norm of a vector $||x||_2$, we can equivalently minimize its square $||x||_2^2 = \sum_i x_i^2$, and vice verse.

Frank-Wolfe vs. Fujishige-Wolfe

An algorithm we will <u>not</u> use for the min-norm is M. Frank & P. Wolfe "An algorithm for quadratic programming", 1956, or conditional gradient descent for constrained convex minimization given convex function $f: \mathcal{D} \to \mathbb{R}$.

```
Input : Convex f: \mathcal{D} \to \mathbb{R}, x_0 \in \overline{\mathcal{D}}

Output: x^* \in \mathcal{D}, the minimizer of f.

1 k \leftarrow 0 and start with x_0 \in \mathcal{D};

2 Let s_k solve \min \langle s, \nabla f(x_k) \rangle s.t. s \in \mathcal{D};

3 Let \lambda_k \in [0,1] minimize f(\lambda s_k + (1-\lambda)x_k);

4 x_{k+1} \leftarrow \lambda_k s_k + (1-\lambda_k)x_k, k \leftarrow k+1;

5 Goto line 1 if ||x_{k+1} - x_k|| > \tau;

6 x^* \leftarrow x_{k+1}
```

- Above could minimize Lovász extension, primal approach to SFM.
- For finding the min-norm point, we will be using the P. Wolfe, "Finding the Nearest Point in a Polytope", 1976 which is the same Wolfe but different algorithm and different year.

 Wolfe-1976 ("Finding the Nearest Point in a Polytope") developed an algorithm to compute the minimum norm point of a polytope, specified as a set of vertices (again, not same as Frank-Wolfe'1956).

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$$\min_{x \in \text{conv } P} \|x\|_2 \tag{19.41}$$

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- Seems to still be (among) the fastest general purpose SFM algo.
- Algorithm maintains a set of points $Q \subseteq P$, which is always assuredly affinely independent. Q

Min-Norm Point Definitions Review & Support for Min-Norm Proof that min-norm gives optimal Computing Min-Norm

Fujishige-Wolfe Min-Norm Algorithm

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- One of the most expensive parts of Wolfe's original 1976 algorithm is solving linear optimization problem over the polytope, doable by examining all the extreme points in the polytope.
- If number of extreme points is exponential, hard to do in general.
- Number of extreme points of submodular base polytope is exponentially large, but linear optimization over the base polytope B_f doable $O(n \log n)$ time via Edmonds's greedy algorithm.

Pseudocode of Fujishige-Wolfe Min-Norm (MN) algorithm Input : $P = \{p_1, \dots, p_m\}, p_i \in \mathbb{R}^n, i = 1, \dots, m$.

```
Output: x^*: the minimum-norm-point in conv P.
 1 x^* \leftarrow p_{i^*} where p_{i^*} \in \operatorname{argmin}_{p \in P} ||p||_2 /* or choose it arbitrarily */;
 2 Q \leftarrow \{x^*\};
 3 while 1 do
                                                                                        /* major loop */
         if x^* = 0 or H(x^*) separates P from origin then
             return : x^*
        else
             Choose \hat{x} \in P on the near (closer to 0) side of H(x^*);
          Q = Q \cup \{\hat{x}\};
         while 1 do
                                                                                         /* minor loop */
 8
             x_0 \longleftarrow \operatorname{argmin}_{x \in \operatorname{aff} Q} \|x\|_2;
             if x_0 \in \operatorname{conv} Q then
10
                  x^* \longleftarrow x_0;
11
                  break:
12
13
             else
                  y \leftarrow \operatorname{argmin}_{x \in \operatorname{conv} Q \cap [x^*, x_0]} \|x - x_0\|_2;
14
                  Delete from Q points not on the face of conv Q where y lies;
15
16
```

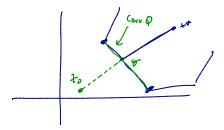
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- Algorithm maintains an invariant, namely that:

$$\underline{x^* \in \operatorname{conv} Q} \subseteq \operatorname{conv} P, \tag{19.42}$$

must hold at every possible assignment of x^* (Lines 1, 11, and 16):

- **1** True after Line 1 since $Q = \{x^*\}$,
- **2** True after Line 11 since $x_0 \in \text{conv } Q$,
- 3 and true after Line 16 since $y \in \text{conv } Q$ even after deleting points.



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- Note also for any $x^* \in \operatorname{conv} Q \subseteq \operatorname{conv} P$, we have

$$\min_{x \in \text{aff } Q} \|x\|_2 \le \min_{x \in \text{conv } Q} \|x\|_2 \le \|x^*\|_2 \tag{19.43}$$

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 6, Line
 9, Line
 10, Line
 14, and Line
 15.

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- Note, the input, P, consists of m points. In the case of the base polytope, $P=B_f$ could be exponential in n=|V|.
- There are six places that might be seemingly tricky or expensive: Line 4, Line 6, Line 9, Line 10, Line 14, and Line 15.
- We will consider each in turn, but first we do a geometric example.

Pseudocode of Fujishige-Wolfe Min-Norm (MN) algorithm Input : $P = \{p_1, \dots, p_m\}, p_i \in \mathbb{R}^n, i = 1, \dots, m.$

```
Output: x^*: the minimum-norm-point in conv P.
```

1 $x^* \leftarrow p_{i^*}$ where $p_{i^*} \in \operatorname{argmin}_{p \in P} ||p||_2$ /* or choose it arbitrarily */;

 $Q \leftarrow \{x^*\}$: 3 while 1 do /* major loop */

if $x^* = 0$ or $H(x^*)$ separates P from origin then

return : x^* Solved by Edmond's greedy procedure. else

Choose $\hat{x} \in P$ on the near (closer to 0) side of $H(x^*)$;

while 1 do $x_0 \leftarrow \operatorname{argmin}_{x \in \operatorname{aff} Q} \|x\|_2;$

if $x_0 \in \operatorname{conv} Q$ then

 $x^* \leftarrow\!\!\!\!- x_0$;

11 break:

 $Q = Q \cup \{\hat{x}\};$

6

7

8

10

14

else 13

Doable since we're representing points 12 as convex combinations of points within Q

 $y \leftarrow \operatorname{argmin}_{x \in \operatorname{conv} Q \cap [x^*, x_0]} \|x - x_0\|_2;$

Solved via linear

equation solver.

Linear equation solver represents

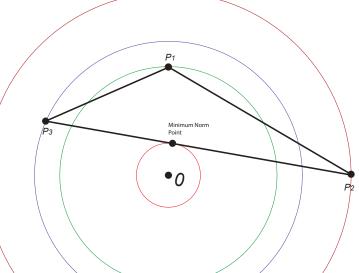
 x_0 as affine coefs, so this just checks >= 0.

/* minor loop */

Delete from Q points not on the face of conv Q where y lies; 15 $x^* \leftarrow y$; 16

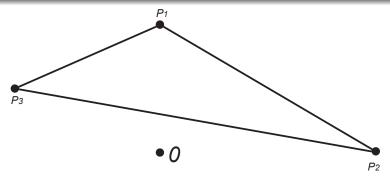
- In the following series of images, permanent (non-changing) named points on the polytope will be indicated by capital letters (i.e., P_1 , P_2 , P_3 , R, S, T) while variables in the algorithm that are changing will use lower case letters (i.e., x^* , x_0 , \hat{x} , y).
- Also, example is in 2D, so polytope given can't be a real base B_f for any f. Example meant to show only the geometry of the algorithm.

Polytope, and circles concentric at 0.

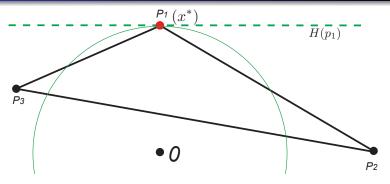


Min-Norm Point Definitions Review & Support for Min-Norm Proof that min-norm gives optimal Computing Min-Norm Vector for B f

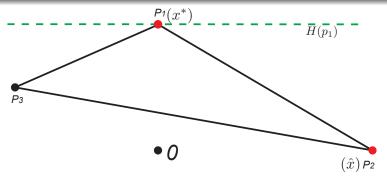
Fujishige-Wolfe Min-Norm algorithm: Geometric Example



The initial polytope consisting of the convex hull of three points p_1, p_2, p_3 , and the origin 0.



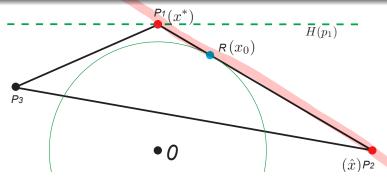
 p_1 is the extreme point closest to 0 and so we choose it first, although we can choose any arbitrary extreme point as the initial point. We set $x^* \leftarrow p_1$ in Line 1, and $Q \leftarrow \{p_1\}$ in Line 2. $H(x^*) = H(p_1)$ (green dashed line) is not a supporting hyperplane of $\operatorname{conv}(P)$ in Line 4, so we move on to the else condition in Line 5.



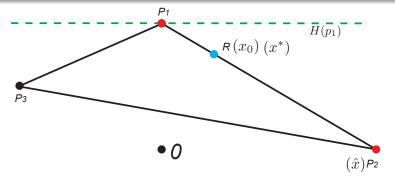
We need to add some extreme point \hat{x} on the "near" side of $H(\mathbf{p}_1)$ in Line 6, we choose $\hat{x} = \mathbf{p}_2$. In Line 7, we set $Q \leftarrow Q \cup \{p_2\}$, so $Q = \{p_1, p_2\}$.

Fund: Circuit/Dep Min-Norm Point Definitions Review & Support for Min-Norm Proof that min-norm gives optimal Computing Min-Norm Vector for B_f

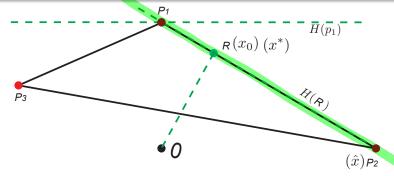
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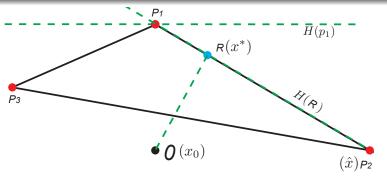
 $x_0 = R$ is the min-norm point in aff $\{p_1, p_2\}$ computed in Line 9.



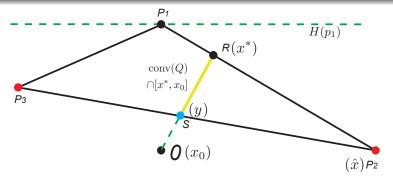
 $x_0=R$ is the min-norm point in $\inf\{p_1,p_2\}$ computed in Line 9. Also, with $Q=\{p_1,p_2\}$, since $R\in\operatorname{conv} Q$, we set $x^*\leftarrow x_0=R$ in Line 11, not violating the invariant $x^*\in\operatorname{conv} Q$. Note, after Line 11, we still have $x^*\in\operatorname{conv} P$ and $\|x^*\|_2=\|x^*_{\mathsf{new}}\|_2<\|x^*_{\mathsf{old}}\|_2$ strictly.



 $R=x_0=x^*.$ We consider next $H(R)=H(x^*)$ in Line 4. $H(x^*)$ is not a supporting hyperplane of $\operatorname{conv} P.$ So we choose p_3 on the "near" side of $H(x^*)$ in Line 6. Add $Q \leftarrow Q \cup \{p_3\}$ in Line 7. Now $Q=P=\{p_1,p_2,p_3\}.$



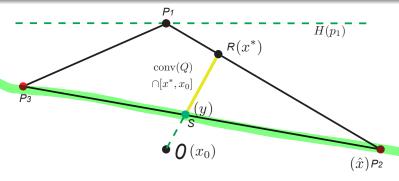
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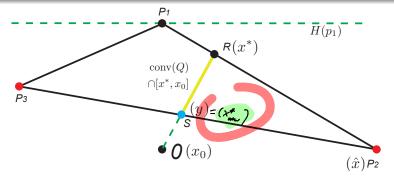
 $Q = P = \{p_1, p_2, p_3\}. \text{ Line 14: } S = y = \mathop{\rm argmin}_{x \in \mathop{\rm conv}\nolimits Q \cap [x^*, x_0]} \|x - x_0\|_2$ where x_0 is 0 and x^* is R here. Thus, y lies on the boundary of $\mathop{\rm conv}\nolimits Q$. Note, $\|y\|_2 < \|x^*\|_2$ since $x^* \in \mathop{\rm conv}\nolimits Q$, $\|x_0\|_2 < \|x^*\|_2$.

Fund. Circuit/Dep

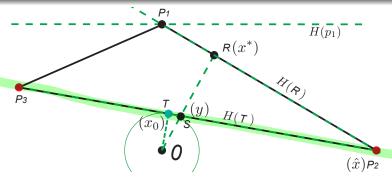
Fujishige-Wolfe Min-Norm algorithm: Geometric Example



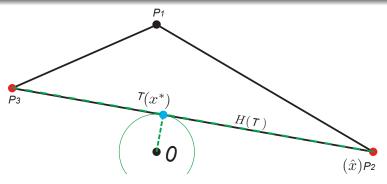
 $Q = P = \{p_1, p_2, p_3\}.$ Line 14: $S = y = \operatorname{argmin}_{x \in \operatorname{conv} Q \cap [x^*, x_0]} \|x - x_0\|_2$ where x_0 is 0 and x^* is R here. Thus, y lies on the boundary of conv Q. Note, $||y||_2 < ||x^*||_2$ since $x^* \in \text{conv } Q$, $||x_0||_2 < ||x^*||_2$. Line 15: Delete p_1 from Q since not on face where y = S lies. $Q = \{p_2, p_3\}$ after Line 15. We still have $y = S \in \text{conv } Q$ for the updated Q.



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 $Q = \{p_2, p_3\}$, and so $x_0 = T$ computed in Line 9 is the min-norm point in aff Q. We also have $x_0 \in \operatorname{conv} Q$ in Line 10 so we assign $x^* \leftarrow x_0$ in Line 11 and break.



H(T) separates P from the origin in Line 4, and therefore is a supporting hyperplane, and therefore x^* is the min-norm point in $\operatorname{conv} P$, so we return with x^* .

Condition for Min-Norm Point

Theorem 19.7.1

$$P = \{p_1, p_2, \dots, p_m\}, \ x^* \in \text{conv } P \text{ is the min. norm point in } \text{conv } P \text{ iff}$$

$$p_i^{\mathsf{T}} x^* \ge \|x^*\|_2^2 \quad \forall i = 1, \dots, m.$$
(19.44)

Proof.

Fund. Circuit/Dep

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Proof.

- Assume x^* is the min-norm point, let $y \in \text{conv } P$, and $0 < \theta < 1$.
- Then $z \triangleq x^* + \theta(y x^*) = (1 \theta)x^* + \theta y \in \text{conv } P$, and $||z||_2^2 = ||x^* + \theta(y - x^*)||_2^2$ (19.45) $= \|x^*\|_2^2 + 2\theta(x^{*\intercal}y - x^{*\intercal}x^*) + \theta^2 \|y - x^*\|_2^2$ (19.46)

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- It is possible for $||z||_2^2 < ||x^*||_2^2$ for small θ , unless $x^{*\intercal}y \ge x^{*\intercal}x^*$ for all $y \in \operatorname{conv} P \Rightarrow \text{Equation (19.44)}$.

Computing Min-Norm Vector for B_{4}

Condition for Min-Norm Point

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- Assume x^* is the min-norm point, let $y \in \operatorname{conv} P$, and $0 \le \theta \le 1$.
- Then $z \triangleq x^* + \theta(y x^*) = (1 \theta)x^* + \theta y \in \text{conv } P$, and $||z||_2^2 = ||x^* + \theta(y x^*)||_2^2$ (19.45) $= ||x^*||_2^2 + 2\theta(x^{*\mathsf{T}}y x^{*\mathsf{T}}x^*) + \theta^2 ||y x^*||_2^2$ (19.46)
- It is possible for $||z||_2^2 < ||x^*||_2^2$ for small θ , unless $x^{*\intercal}y \ge x^{*\intercal}x^*$ for all $y \in \operatorname{conv} P \Rightarrow \text{Equation (19.44)}.$
- Conversely, given Eq (19.44), and given that $y = \sum_i \lambda_i p_i \in \operatorname{conv} P$, $y^{\mathsf{T}} x^* = \sum_i \lambda_i p_i^{\mathsf{T}} x^* \geq \sum_i \lambda_i x^{*\mathsf{T}} x^* = x^{*\mathsf{T}} x^* \qquad (19.47)$ implying that $\|z\|_2^2 > \|x^*\|_2^2$ in Equation 19.46 for arbitrary $z \in \operatorname{conv} P$.

Computing Min-Norm Vector for B 4

Lemma 19.7.2

Fund, Circuit/Dep

The set Q in the MN Algorithm is always affinely independent.

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Proof.



Min-Norm Point Definitions Review & Support for Min-Norm Proof that min-norm gives optimal Computing Min-Norm Vector for B &

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Min-Norm Point Definitions Review & Support for Min-Horm Proof that min-norm gives optimal Computing Min-Norm Vector for B #

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- Q is of course affinely independent when there is at most one point in it (e.g., after Line 2).
- After the initialization, it changes only by deletion of points, or adding a single point. Deletion does not change the independence.



Min-Norm Point Definitions Review & Support for Min-Norm Proof that min-norm gives optimal Computing Min-Norm Vector for B f

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- Therefore, x^* is normal to aff Q, which implies aff $Q \subseteq H(x^*)$.



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Thus, by Lemma 19.7.2, we have for any $x \in \operatorname{aff} Q$ such that $x = \sum_i w_i q_i$ with $\sum_i w_i = 1$, the weights w_i are uniquely determined.

The set Q is never too large

Lemma 19.7.3

The set Q in the MN Algorithm has size never more than n+1.

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Proof.

Fund. Circuit/Dep

This is immediate, since Q is always affinely independent, and in \mathbb{R}^V , an affinely independent set can have at most n+1 entries, with |V|=n.

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- ullet When Q is affinely independent, this is relatively easy.
- Let Q represent $n \times k$ matrix with points as columns $q \in Q$. The following is solvable with matrix inversion/linear solver, where x = Qw:

minimize
$$||x||_2^2 = w^{\mathsf{T}} Q^{\mathsf{T}} Q w$$
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• Form Lagrangian $w^{\intercal}Q^{\intercal}Qw + 2\lambda(\mathbf{1}^{\intercal}w - 1)$, and differentiating w.r.t. λ and w, and setting to zero, we get:

$$\mathbf{1}^{\mathsf{T}}w = 1\tag{19.50}$$

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$$\begin{bmatrix} 0 & \mathbf{1}^{\mathsf{T}} \\ \mathbf{1} & Q^{\mathsf{T}} Q \end{bmatrix} \begin{bmatrix} \lambda \\ w \end{bmatrix} = \begin{bmatrix} 1 \\ \mathbf{0} \end{bmatrix} \tag{19.52}$$

Minimum Norm in an affine set

- Line 9 of the algorithm requires $x_0 \leftarrow \min_{x \in \text{aff } O} ||x||_2$.
- When Q is affinely independent, this is relatively easy.
- Let Q represent $n \times k$ matrix with points as columns $q \in Q$. The following is solvable with matrix inversion/linear solver, where x = Qw:

• Form Lagrangian $w^{\mathsf{T}}Q^{\mathsf{T}}Qw + 2\lambda(\mathbf{1}^{\mathsf{T}}w - 1)$, and differentiating w.r.t. λ and w, and setting to zero, we get:

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Thanks to Q being affine, matrix on l.h.s. is invertable.

Minimum Norm in an affine set

• Note, this also solves Line 10, since feasibility requires $\sum_i w_i = 1$, we need only check $w \geq 0$ to ensure $x_0 = \sum_i w_i q_i \in \text{conv } Q$.

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- In fact, a feature of the algorithm (in Wolfe's 1976 paper) is that we keep the convex coefficients $\{w_i\}_i$ where $x^* = \sum_i w_i p_i$ of x^* and from this vector. We also keep v such that $x_0 = \sum_i v_i q_i$ for points $q_i \in Q$, from Line 9.

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- Given w and v, we can also easily solve Lines 14 and 15 (see "Step 3" on page 133 of Wolfe-1976, which also defines numerical tolerances).

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- Given w and v, we can also easily solve Lines 14 and 15 (see "Step 3" on page 133 of Wolfe-1976, which also defines numerical tolerances).
- We have yet to see how to efficiently solve Lines 4 and 6, however.

Min-Norm Point Definitions Review & Support for Min-Norm Proof that min-norm gives optimal Computing Min-Norm Vector for B &

MN Algorithm finds the MN point in finite time.

Theorem 19.7.4

The MN Algorithm finds the minimum norm point in $\operatorname{conv} P$ after a finite number of iterations of the major loop.

Proof.

Fund. Circuit/Dep

• In minor loop, we always have $x^* \in \text{conv } Q$, since whenever Q is modified, x^* is updated as well (Line 16) such that the updated x^* remains in new conv Q.

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• Moreover, there can be no more iterations within a minor loop than the dimension of $\operatorname{conv} Q$ for the initial Q given to the minor loop initially at Line 8 (dimension of $\operatorname{conv} Q$ is |Q|-1 since Q is affinely independent).

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- Thus, the minor loop terminates in finite number of iterations, at most dimension of Q.
- In fact, total number of iterations of minor loop in entire algorithm is at most number of points in P since we never add back in points to Q that have been removed.

Min-Norm Point Definitions Review & Support for Min-Norm Proof that min-norm gives optimal Computing Min-Norm

MN Algorithm finds the MN point in finite time.

...proof of Theorem 19.7.4 continued.

• Each time Q is augmented with \hat{x} at Line 7, followed by updating x^* with x_0 at Line 11, (i.e., when the minor loop returns with only one iteration), $\|x^*\|_2$ strictly decreases from what it was before.



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- Therefore, we have $||x^* + \theta(\hat{x} x^*)||_2 \ge ||x_0||_2$, which implies

$$||x^* + \theta(\hat{x} - x^*)||_2^2 = ||x^*||_2^2 + 2\theta\left((x^*)^\top \hat{x} - ||x^*||_2^2\right) + \theta^2 ||\hat{x} - x^*||_2^2$$

$$\geq ||x_0||_2^2$$
(19.53)

and from Line 6, \hat{x} is on the same side of $H(x^*)$ as the origin, i.e. $(x^*)^{\top}\hat{x} < \|x^*\|_2^2$, so middle term of r.h.s. of equality is negative.

MN Algorithm finds the MN point in finite time.

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• Therefore, for sufficiently small θ , specifically for

$$\theta < \frac{2\left(\|x^*\|_2^2 - (x^*)^\top \hat{x}\right)}{\|\hat{x} - x^*\|_2^2} \tag{19.54}$$

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- For a similar reason, we have $\|x^*\|_2$ strictly decreases each time Q is updated at Line 7 and followed by updating x^* with y at Line 16.
- Therefore, in each iteration of major loop, $\|x^*\|_2$ strictly decreases, and the MN Algorithm must terminate and it can only do so when the optimal is found.



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- Ideally, find \hat{x} such that the reduction of $\|x^*\|_2$ is maximized to reduce number of major iterations.
- From Eqn. 19.53, reduction on norm is lower-bounded:

$$\Delta = \|x^*\|_2^2 - \|x_0\|_2^2 \ge 2\theta \left(\|x^*\|_2^2 - (x^*)^\top \hat{x} \right) - \theta^2 \|\hat{x} - x^*\|_2^2 \triangleq \underline{\Delta}$$
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Line: 6: Finding $\hat{x} \in P$ on the near side of $H(x^*)$

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• When $0 \le \theta < \frac{2\left(\|x^*\|_2^2 - (x^*)^{\top} \hat{x}\right)}{\|\hat{x} - x^*\|_2^2}$, we can get the maximal value of the lower bound, over θ , as follows:

$$\max_{0 \le \theta < \frac{2\left(\|x^*\|_2^2 - (x^*)^{\top} \hat{x}\right)}{\|\hat{x} - x^*\|_2^2}} \underline{\Delta} = \left(\frac{\|x^*\|_2^2 - (x^*)^{\top} \hat{x}}{\|\hat{x} - x^*\|_2}\right)^2 \tag{19.56}$$

• To maximize lower bound of norm reduction at each major iteration, want to find an \hat{x} such that the above lower bound (Equation 19.56) is maximized.

Line: 6: Finding $\hat{x} \in P$ on the near side of $H(x^*)$

- To maximize lower bound of norm reduction at each major iteration, want to find an \hat{x} such that the above lower bound (Equation 19.56) is maximized.
- That is, we want to find

$$\hat{x} \in \underset{x \in P}{\operatorname{argmax}} \left(\frac{\|x^*\|_2^2 - (x^*)^\top x}{\|x - x^*\|_2} \right)^2 \tag{19.57}$$

to ensure that a large norm reduction is assured.

- To maximize lower bound of norm reduction at each major iteration, want to find an \hat{x} such that the above lower bound (Equation 19.56) is maximized.
- That is, we want to find

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to ensure that a large norm reduction is assured.

• This problem, however, is at least as hard as the MN problem itself as we have a quadratic term in the denominator.

• As a surrogate, we maximize numerator in Eqn. 19.57, i.e., find

$$\hat{x} \in \underset{x \in P}{\operatorname{argmax}} \|x^*\|_2^2 - (x^*)^\top x = \underset{x \in P}{\operatorname{argmin}} (x^*)^\top x,$$
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- Also, solution \hat{x} in Line 6 can be used to determine if hyperplane $H(x^*)$ separates $\operatorname{conv} P$ from the origin (Line 4): if the point in P having greatest distance to $H(x^*)$ is not on the side where origin lies, then $H(x^*)$ separates $\operatorname{conv} P$ from the origin.

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- Mathematically and theoretically, we terminate the algorithm if

$$(x^*)^{\top} \hat{x} \ge \|x^*\|_2^2,$$
 (19.59)

where \hat{x} is the solution of Eq. 19.58.

• In practice, the above optimality test might never hold numerically. Hence, as suggested by Wolfe, we introduce a tolerance parameter $\epsilon>0$, and terminates the algorithm if

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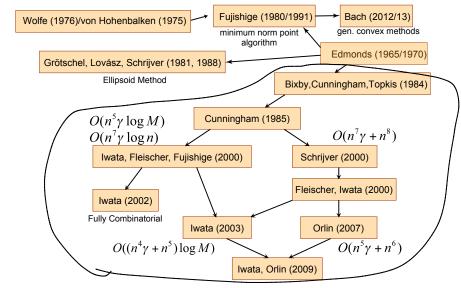
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- Hence, Edmonds's discovery is one of the main reasons that the MN algorithm is applicable to submodular function minimization.

SFM Summary (modified from S. Iwata's slides)

General Submodular Function Minimization



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• Since the number of major iterations required is unknown, the complexity of MN is also unknown.

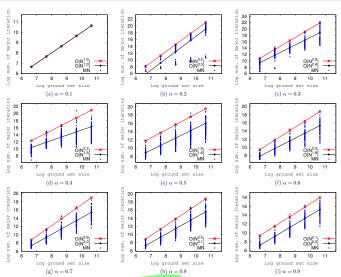


Figure: The number of major iteration for $f(S) = -m_1(S) + 100 \cdot (w_1(N'(S)))^{\alpha}$. The red lines are the linear interpolations of the worst case points, and the black lines are the linear interpolations of the average case points. From Lin&Bilmes 2014 (unpublished)

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- This is pseudo-polynomial since it depends on the function values.
- There currently is no known polynomial time complexity analysis for this algorithm.