Submodular Functions, Optimization, and Applications to Machine Learning

— Spring Quarter, Lecture 14

http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563_spring_2018/

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May 14th, 2018



 $\begin{array}{ll} f(A)+f(B) \geq f(A \cup B) + f(A \cap B) \\ & \xrightarrow{-f(A_r)+2f(C)+f(B_r)} & \xrightarrow{-f(A_r)+f(C)+f(B_r)} & \xrightarrow{-f(A \cap B)} \end{array}$







Cumulative Outstanding Reading

- Read chapter 1 from Fujishige's book.
- Read chapter 2 from Fujishige's book.
- Read chapter 3 from Fujishige's book.
- Read chapter 4 from Fujishige's book.

Announcements, Assignments, and Reminders

- Next homework is posted on canvas. Due Thursday 5/10, 11:59pm.
- As always, if you have any questions about anything, please ask then
 via our discussion board
 (https://canvas.uw.edu/courses/1216339/discussion_topics).
 Can meet at odd hours via zoom (send message on canvas to schedule
 time to chat).

Class Road Map - EE563

- L1(3/26): Motivation, Applications, & Basic Definitions.
- L2(3/28): Machine Learning Apps (diversity, complexity, parameter, learning target, surrogate).
- L3(4/2): Info theory exs, more apps, definitions, graph/combinatorial examples
- L4(4/4): Graph and Combinatorial Examples, Matrix Rank, Examples and Properties, visualizations
- L5(4/9): More Examples/Properties/ Other Submodular Defs., Independence,
- L6(4/11): Matroids, Matroid Examples, Matroid Rank, Partition/Laminar Matroids
- L7(4/16): Laminar Matroids, System of Distinct Reps, Transversals, Transversal Matroid, Matroid Representation, Dual Matroids
- L8(4/18): Dual Matroids, Other Matroid Properties, Combinatorial Geometries, Matroids and Greedy.
- L9(4/23): Polyhedra, Matroid Polytopes, Matroids → Polymatroids
- L10(4/29): Matroids → Polymatroids, Polymatroids, Polymatroids and Greedy,

- L11(4/30): Polymatroids, Polymatroids and Greedy
- L12(5/2): Polymatroids and Greedy, Extreme Points, Cardinality Constrained Maximization
- L13(5/7): Constrained Submodular Maximization
- L14(5/9): Submodular Max w. Other Constraints, Cont. Extensions, Lovasz Extension
- L15(5/14):
 L16(5/16):
- L17(5/21):
- L17(5/21
- L18(5/23):
- L-(5/28): Memorial Day (holiday)
- L19(5/30):
- L21(6/4): Final Presentations maximization.

Priority Queue

- ullet Use a priority queue Q as a data structure: operations include:
 - Insert an item (v, α) into queue, with $v \in V$ and $\alpha \in \mathbb{R}$.

$$\mathsf{insert}(Q,(v,\alpha))$$
 (14.14)

 \bullet Pop the item (v,α) with maximum value α off the queue.

$$(v,\alpha) \leftarrow \mathsf{pop}(Q) \tag{14.15}$$

Query the value of the max item in the queue

$$\max(Q) \in \mathbb{R} \tag{14.16}$$

- On next slide, we call a popped item "fresh" if the value (v,α) popped has the correct value $\alpha=f(v|S_i)$. Use extra "bit" to store this info
- If a popped item is fresh, it must be the maximum this can happen if, at given iteration, v was first popped and neither fresh nor maximum so placed back in the queue, and it then percolates back to the top at which point it is fresh thereby avoid extra queue check.

Minoux's Accelerated Greedy Algorithm Submodular Max

Algorithm 1: Minoux's Accelerated Greedy Algorithm

```
1 Set S_0 \leftarrow \emptyset; i \leftarrow 0; Initialize priority queue Q;
 2 for v \in E do
     | INSERT(Q, f(v))
 4 repeat
        (v,\alpha) \leftarrow \mathsf{pop}(Q);
        if \alpha not "fresh" then
          recompute \alpha \leftarrow f(v|S_i)
         if (popped \alpha in line 5 was "fresh") OR (\alpha \geq \max(Q)) then
 8
             Set S_{i+1} \leftarrow S_i \cup \{v\};
          i \leftarrow i+1;
10
         else
11
             \mathsf{insert}(Q,(v,\alpha))
12
13 until i = |E|;
```

(Minimum) Submodular Set Cover

ullet Given polymatroid f, goal is to find a covering set of minimum cost:

$$S^* \in \underset{S \subseteq V}{\operatorname{argmin}} |S| \text{ such that } f(S) \ge \alpha$$
 (14.14)

where α is a "cover" requirement.

• Normally take $\alpha=f(V)$ but defining $f'(A)=\min\left\{f(A),\alpha\right\}$ we can take any α . Hence, we have equivalent formulation:

$$S^* \in \underset{S \subseteq V}{\operatorname{argmin}} |S| \text{ such that } f'(S) \ge f'(V) \tag{14.15}$$

- Note that this immediately generalizes standard set cover, in which case f(A) is the cardinality of the union of sets indexed by A.
- Greedy Algorithm: Pick the first chain item S_i chosen by aforementioned greedy algorithm such that $f(S_i) \geq \alpha$ and output that as solution.

(Minimum) Submodular Set Cover: Approximation Analysis

• For integer valued f, this greedy algorithm an $O(\log(\max_{s \in V} f(\{s\})))$ approximation. Let S^* be optimal, and S^G be greedy solution, then

$$|S^{\mathsf{G}}| \le |S^*| H(\max_{s \in V} f(\{s\})) = |S^*| O(\log_e(\max_{s \in V} f(\{s\})))$$
 (14.14)

where H is the harmonic function, i.e., $H(d) = \sum_{i=1}^{d} (1/i)$.

ullet If f is not integral value, then bounds we get are of the form:

$$|S^{\mathsf{G}}| \le |S^*| \left(1 + \log_e \frac{f(V)}{f(V) - f(S_{T-1})}\right)$$
 (14.15)

wehre S_T is the final greedy solution that occurs at step T.

• Set cover is hard to approximate with a factor better than $(1 - \epsilon) \log \alpha$, where α is the desired cover constraint.



Curvature of a Submodular function

$$f(3)=0$$
 =7 $f(3|A)=0$ $\forall A$,
 $f(3|\Phi)=f(3|\Phi)-f(0)=f(3)$

By submodularity, total curvature can be computed in either form:

$$c \stackrel{\Delta}{=} 1 - \min_{S, j \notin S: f(j|\emptyset) \neq 0} \frac{f(j|S)}{f(j|\emptyset)} = 1 - \min_{j: f(j|\emptyset) \neq 0} \frac{f(j|V \setminus \{j\})}{f(j|\emptyset)} \quad \text{(14.17)}$$

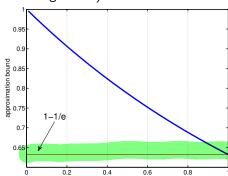
- Note: Matroid rank is either modular c=0 or maximally curved c=1 hence, matroid rank can have only the extreme points of curvature, namely 0 or 1.
- Polymatroid functions are, in this sense, more nuanced, in that they allow non-extreme curvature, with $c\in[0,1].$
- It will be remembered the notion of "partial dependence" within polymatroid functions.

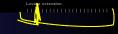
Curvature and approximation

- Curvature limitation can help the greedy algorithm in terms of approximation bounds.
- Conforti & Cornuéjols showed that greedy gives a 1/(1+c) approximation to $\max{\{f(S):S\in\mathcal{I}\}}$ when f has total curvature c.
- Hence, greedy subject to matroid constraint is a $\max(1/(1+c),1/2)$ approximation algorithm, and if c<1 then it is better than 1/2 (e.g., with c=1/4 then we have a 0.8 algorithm).

For k-uniform matroid (i.e., k-cardinality constraints), then approximation factor becomes

$$\frac{1}{c}(1-e^{-c})$$





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$$c(\zeta) = \sum_{v \in S} c(v)$$

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- We may wish to maximize f subject to multiple matroid constraints. I.e., $S \in \mathcal{I}_1, S \in \mathcal{I}_2, \ldots, S \in \mathcal{I}_p$ where \mathcal{I}_i are independent sets of the i^{th} matroid.

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- Combinations of the above (e.g., knapsack & multiple matroid constraints).

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 (14.1)

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Given a polymatroid function f, and set of matroids $\{M_j = (E, \mathcal{I}_j)\}_{j=1}^p$, the above greedy algorithm returns sets S_i such that for each i we have $f(S_i) \geq \frac{1}{p+1} \max_{|S| \leq i, S \in \bigcap_{i=1}^p \mathcal{I}_i} f(S)$, assuming such sets exists.

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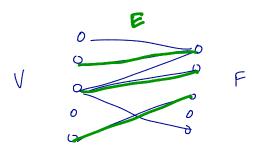
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- For one matroid, we have a 1/2 approximation.
- Very easy algorithm, Minoux trick still possible, while addresses multiple matroid constraints — but the bound is not that good when there are many matroids.

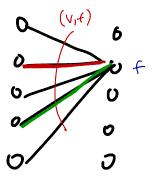
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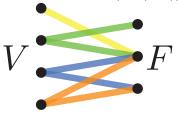


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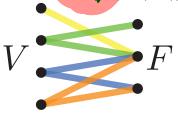
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- In bipartite graph case, therefore, can be solved in polynomial time.

Matroid Intersection and Network Communication

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Matroid Intersection and Network Communication

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- Consider two cycle matroids associated with these graphs $M_1=(E,\mathcal{I}_1)$ and $M_2=(E,\mathcal{I}_2)$. They might be very different (e.g., an edge might be between two distinct nodes in G_1 but the same edge is a loop in multi-graph G_2 .)

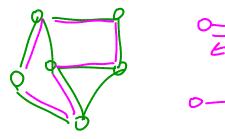
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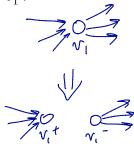
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- This is again a matroid intersection problem.

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- Let M_3 be the partition matroid having as independent sets those that have no more than one edge entering any node i.e., $I \in \mathcal{I}(M_3)$ if $|I \cap \delta^+(v)| \leq 1$ for all $v \in V(G')$.

- Definition: a Hamiltonian cycle is a cycle that passes through each node exactly once.
- ullet Given directed graph G, goal is to find such a Hamiltonian cycle.
- From G with n nodes, create G' with n+1 nodes by duplicating (w.l.o.g.) a particular node $v_1 \in V(G)$ to v_1^+, v_1^- , and have all outgoing edges from v_1 come instead from v_1^- and all edges incoming to v_1 go instead to v_1^+ .
- Let M_1 be the cycle matroid on G'.
- Let M_2 be the partition matroid having as independent sets those that have no more than one edge leaving any node i.e., $I \in \mathcal{I}(M_2)$ if $|I \cap \delta^-(v)| \leq 1$ for all $v \in V(G')$.
- Let M_3 be the partition matroid having as independent sets those that have no more than one edge entering any node i.e., $I \in \mathcal{I}(M_3)$ if $|I \cap \delta^+(v)| \leq 1$ for all $v \in V(G')$.
- Then a Hamiltonian cycle exists iff there is an n-element intersection of M_1 , M_2 , and M_3 .

$$M_{1} = \begin{pmatrix} V_{1} & \{I \leq V: |II| \leq h \} \end{pmatrix}$$

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- Since TSP is NP-complete, we obviously can't solve matroid intersections of 3 more matroids, unless P=NP.
- But bipartite graph example gives us hope for 2 matroids, as in that case we can easily solve $\max |X|$ s.t. $x \in \mathcal{I}_1 \cap \mathcal{I}_2$.

r Max w. Other Constraints Cont. Extensions

Greedy over multiple matroids: Generalized Bipartite Matching

 Generalized bipartite matching (i.e., max bipartite matching with submodular costs on the edges). Use two partition matroids (as mentioned earlier in class)

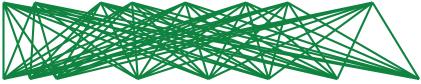
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- ullet E corresponds to, say, an English language sentence and F corresponds to a French language sentence goal is to form a matching (an alignment) between the two.

• Consider English string and French string, set up as a bipartite graph.

I have ... as an example of public ownership



je le ai ... comme exemple de propriété publique

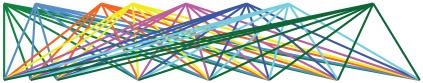
One possible alignment, a matching, with score as sum of edge weights.

I have ... as an example of public ownership

ie le ai ... comme exemple de propriété publique

• Edges incident to English words constitute an edge partition

I have ... as an example of public ownership



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- The two edge partitions can be used to set up two 1-partition matroids on the edges.
- For each matroid, a set of edges is independent only if the set intersects each partition block no more than one time.

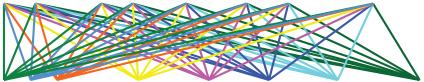
alar Max w. Other Constraints Cont. E

Cont. Extensions Lovász extension

• Edges incident to French words constitute an edge partition

I have ... as an example of public ownership

Greedy over > 1 matroids: Multiple Language Alignment



je le ai ... comme exemple de propriété publique

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Fertility at most 1

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. . . le ... de propriété publique

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 Generalizing further, each block of edges in each partition matroid can have its own "fertility" limit:

$$\mathcal{I} = \{X \subseteq V : |X \cap V_i| \le k_i \text{ for all } i = 1, \dots, \ell\}.$$

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 Maximizing submodular function subject to multiple matroid constraints addresses this problem. • Submodular Welfare Maximization: Consider E a set of m goods to be distributed/partitioned among n people ("players").

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• We can solve this via submodular maximization subject to multiple matroid independence constraints as we next describe . . .

ullet Create new ground set E' as disjoint union of n copies of the ground set. I.e.,

$$E' = \underbrace{E \uplus E \uplus \cdots \uplus E}_{n \times} \tag{14.3}$$

Submodular Welfare: Submodular Max over matroid partition

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- ullet Create a 1-partition matroid $\mathcal{M}=(E',\mathcal{I})$ where

$$\mathcal{I} = \left\{ S \subseteq E' : \forall e \in E, |S \cap E_e| \le 1 \right\} \tag{14.4}$$

Submodular Welfare: Submodular Max over matroid partition

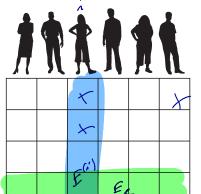
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- Submodular welfare maximization becomes matroid constrained submodular max $\max\{f'(S):S\in\mathcal{I}\}$, so greedy algorithm gives a 1/2 approximation.

Submodular Social Welfare



• Have n=6 people (who don't like to share) and |E|=m=7 pieces of sushi. E.g., $e \in E$ might be e= "salmon roll".

e









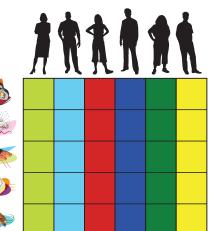








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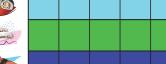


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Submodular Social Welfare







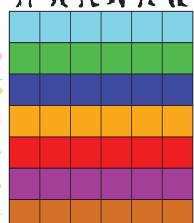












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- Partition matroid partitions: $E_{e_1} \cup E_{e_2} \cup E_{e_3} \cup E_{e_4} \cup E_{e_5} \cup$ $E_{ee} \cup E_{e7}$.









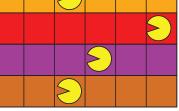




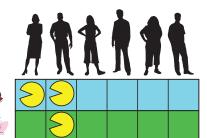


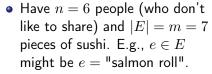






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Monotone Submodular over Knapsack Constraint

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- Important: A knapsack constraint yields an independence system (down closed) but it is not a matroid!
- c(e) may be seen as the cost of item e and if c(e)=1 for all e, then we recover the cardinality constraint we saw earlier.

• Greedy can be seen as choosing the best gain: Starting with $S_0 = \emptyset$, we repeat the following greedy step

$$S_{i+1} = S_i \cup \left\{ \underset{v \in V \setminus S_i}{\operatorname{argmax}} \left(f(S_i \cup \{v\}) - f(S_i) \right) \right\}$$
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ullet Core idea in knapsack case: Greedy can be extended to choose next whatever looks cost-normalized best, i.e., Starting some initial set S_0 , we repeat the following cost-normalized greedy step

$$S_{i+1} = S_i \cup \left\{ \underset{v \in V \setminus S_i}{\operatorname{argmax}} \frac{f(S_i \cup \{v\}) - f(S_i)}{c(v)} \right\}$$
(14.6)

which we repeat until $c(S_{i+1}) > b$ and then take S_i as the solution.

- There are a number of ways of getting approximation bounds using this strategy.
- If we run the normalized greedy procedure starting with $S_0=\emptyset$, and compare the solution found with the max of the singletons $\max_{v\in V}f(\{v\})$, choosing the max, then we get a $(1-e^{-1/2})\approx 0.39$ approximation, in $O(n^2)$ time (Minoux trick also possible for further speed)
- Partial enumeration: On the other hand, we can get a $(1-e^{-1}) \approx 0.63$ approximation in $O(n^5)$ time if we run the above procedure starting from all sets of cardinality three (so restart for all S_0 such that $|S_0|=3$), and compare that with the best singleton and pairwise solution.
- ullet Extending something similar to this to d simultaneous knapsack constraints is possible as well.

From J. Vondrak

- ullet Local search involves switching up to t elements, as long as it provides a (non-trivial) improvement; can iterate in several phases. Some examples follow:
- 1/3 approximation to unconstrained non-monotone maximization [Feige, Mirrokni, Vondrak, 2007]
- $1/(k+2+\frac{1}{k}+\delta_t)$ approximation for non-monotone maximization subject to k matroids [Lee, Mirrokni, Nagarajan, Sviridenko, 2009]
- $1/(k+\delta_t)$ approximation for monotone submodular maximization subject to $k\geq 2$ matroids [Lee, Sviridenko, Vondrak, 2010].

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- Thus, any approximation algorithm must be for unipolar submodular functions. E.g., non-negative but otherwise arbitrary submodular functions.
- We may get a $(\frac{1}{3} \frac{\epsilon}{n})$ approximation for maximizing non-monotone non-negative submodular functions, with most $O(\frac{1}{\epsilon}n^3\log n)$ function calls using approximate local maxima.

• Given any submodular function f, a set $S \subseteq V$ is a local maximum of f if $f(S-v) \leq f(S)$ for all $v \in S$ and $f(S+v) \leq f(S)$ for all $v \in V \setminus S$ (i.e., local in a Hamming ball of radius 1).

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Submodularity and local optima

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Lemma 14.3.2

Given a submodular function f, if S is a local maximum of f, and $I \subseteq S$ or $I \supseteq S$, then $f(I) \le f(S)$.

• Idea of proof: Given $v_1, v_2 \in S$, suppose $f(S-v_1) \leq f(S)$ and $f(S-v_2) \leq f(S)$. Submodularity requires $f(S-v_1) + f(S-v_2) \geq f(S) + f(S-v_1-v_2)$ which would be impossible unless $f(S-v_1-v_2) \leq f(S)$.

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- Similarly, given $v_1, v_2 \notin S$, and $f(S + v_1) \leq f(S)$ and $f(S + v_2) \leq f(S)$. Submodularity requires $f(S + v_1) + f(S + v_2) \ge f(S) + f(S + v_1 + v_2)$ which requires $f(S + v_1 + v_2) < f(S)$.

- Given any submodular function f, a set $S \subseteq V$ is a local maximum of f if $f(S-v) \leq f(S)$ for all $v \in S$ and $f(S+v) \leq f(S)$ for all $v \in V \setminus S$ (i.e., local in a Hamming ball of radius 1).
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- This is the approach that yields the $(\frac{1}{3} \frac{\epsilon}{n})$ approximation algorithm.

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Linear time algorithm unconstrained non-monotone max

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Algorithm 5: Randomized Linear-time non-monotone submodular max

```
1 Set L \leftarrow \emptyset; U \leftarrow V /* Lower L, upper U. Invariant: L \subseteq U */;
2 Order elements of V = (v_1, v_2, \dots, v_n) arbitrarily;
3 for i \leftarrow 0 \dots |V| do
                                                         f(v| v/";)
= f(r, ) v/";)
       a \leftarrow [f(v_i|L)]_+; b \leftarrow [-f(U|U \setminus \{v_i\})]_+;
     if a = b = 0 then p \leftarrow 1/2;
       else p \leftarrow a/(a+b):
       if Flip of coin with Pr(heads) = p draws heads then
       L \leftarrow L \cup \{v_i\};
10
        Otherwise /* if the coin drew tails, an event with prob. 1 - p */
11
        U \leftarrow U \setminus \{v\}
12
```

13 **return** L (which is the same as U at this point)

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- It may be possible to choose the random order smartly to get better results in practice.

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- Often the computational costs of the algorithms are prohibitive (e.g., exponential in k) with large constants, so these algorithms might not scale.
- On the other hand, these algorithms offer deep and interesting intuition into submodular functions, beyond what we have covered here.

Some results on submodular maximization

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- We can recover 1-1/e approximation using the continuous greedy algorithm on the multilinear extension and then using pipage rounding to re-integerize the solution (see J. Vondrak's publications).
- More general constraints are possible too, as we see on the next table (for references, see Jan Vondrak's publications http://theory.stanford.edu/~jvondrak/).

Monotone Maximization

Constraint	Approximation	Hardness	Technique
$ S \le k$	1 - 1/e	1 - 1/e	greedy
matroid	1 - 1/e	1 - 1/e	multilinear ext.
O(1) knapsacks	1 - 1/e	1 - 1/e	multilinear ext.
k matroids	$k + \epsilon$	$k/\log k$	local search
k matroids and $O(1)$ knapsacks	O(k)	$k/\log k$	multilinear ext.

Nonmonotone Maximization

Constraint	Approximation	Hardness	Technique
Unconstrained	1/2	1/2	combinatorial
matroid	1/e	0.48	multilinear ext.
O(1) knapsacks	1/e	0.49	multilinear ext.
k matroids	k + O(1)	$k/\log k$	local search
k matroids and $O(1)$ knapsacks	O(k)	$k/\log k$	multilinear ext.

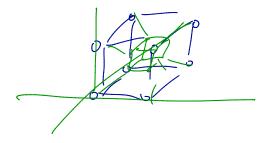
$$f(\hat{S}) \ge \lambda$$
. mor $f(s)$

$$\int_{A} f(\hat{s}) \geq OPT$$

$$V_{A} = k$$

$$d = V_{A}$$

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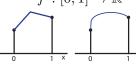
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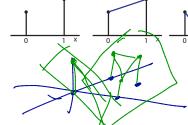
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Discrete Function
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 $\tilde{f}:[0,1]\to\mathbb{R}$ $f:\{0,1\}^V\to\mathbb{R}$





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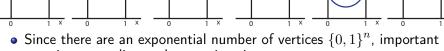
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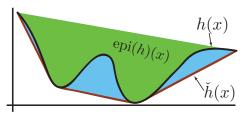
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- Alternatively,

$$\check{h}(x) = \inf \left\{ t : (x, t) \in \mathsf{convexhull}(\mathsf{epigraph}(h)) \right\} \tag{14.8}$$



Convex Closure of Discrete Set Functions

• Given set function $f: 2^V \to \mathbb{R}$, an arbitrary (i.e., not necessarily submodular nor supermodular) set function, define a function $\check{f}: [0,1]^V \to \mathbb{R}$, as

$$\check{f}(x) = \min_{p \in \triangle^n(x)} \sum_{S \subseteq V} p_S f(S) \tag{14.9}$$

where
$$\triangle^n(x) = \left\{ p \in \mathbb{R}^{2^n} : \sum_{S \subseteq V} p_S = 1, \ p_S \ge 0 \forall S \subseteq V, \ \& \ \sum_{S \subseteq V} p_S \mathbf{1}_S = x \right\}$$

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• Hence, $\triangle^n(x)$ is the set of all probability distributions over the 2^n vertices of the hypercube, and where the expected value of the characteristic vectors of those points is equal to x, i.e., for any $p \in \triangle^n(x)$, $E_{S \sim p}(\mathbf{1}_S) = \sum_{S \subset V} p_S \mathbf{1}_S = x$.

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- Hence, $\check{f}(x) = \min_{p \in \triangle^n(x)} E_{S \sim p}[f(S)]$
- Note, this is not (necessarily) the Lovász extension, rather this is a convex extension.

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 - **4** The definition of the Lovász extension of a set function, and that \check{f} is the Lovász extension iff f is submodular.

Lemma 14.4.1

$$\forall A \subseteq V$$
, we have $\check{f}(\mathbf{1}_A) = f(A)$.

Proof.

• Define p^x to be an achiving argmin in $\check{f}(x) = \min_{p \in \triangle^n(x)} E_{S \sim p}[f(S)]$.

Tightness of Convex Closure

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- Suppose $\exists S'$ s.t. $A \setminus S' \neq \emptyset$ with $p_{S'}^{\mathbf{1}_A} > 0$.
- ullet Then, for any $v \in A \setminus S'$, consider below leading to a contradiction

$$\underbrace{p_{S'}\mathbf{1}_{S'}}_{>0} + \sum_{\substack{S \subseteq A \\ S \neq S'}} p_S \mathbf{1}_S \Rightarrow \left(\sum_{\substack{S \subseteq A \\ S \neq S'}} p_s \mathbf{1}_S\right)(v) < 1 \tag{14.10}$$

can't sum to 1

I.e., $v \in A$ so it must get value 1, but since $v \notin S'$, v is deficient.

Convexity of the Convex Closure

Lemma 14.4.2

$$\check{f}(x) = \min_{p \in \triangle^n(x)} E_{S \sim p}[f(S)]$$
 is convex in $[0, 1]^V$.

Proof.

• Let $x, y \in [0, 1]^V$, $0 \le \lambda \le 1$, and $z = \lambda x + (1 - \lambda)y$, then

$$\lambda \check{f}(x) + (1 - \lambda)\check{f}(y) = \lambda \sum_{S} p_S^x f(S) + (1 - \lambda) \sum_{S} p_S^y f(S) \quad (14.11)$$

$$= \sum_{\alpha} (\lambda p_S^x + (1 - \lambda) p_S^y) f(S) \tag{14.12}$$

$$= \sum_{S} p_{S}^{z'} f(S) \ge \min_{p \in \triangle^{n}(z)} E_{S \sim p}[f(S)] \quad (14.13)$$

$$= \check{f}(z) = \check{f}(\lambda x + (1 - \lambda)y) \tag{14.14}$$

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• Note that $p_S^{z'}=\lambda p_S^x+(1-\lambda)p_S^y$ and is feasible in the min since $\sum_S p_S^{z'}=1,\ p_S^{z'}\geq 0$ and $\sum_S p_S^z \mathbf{1}_S=z.$

ullet Given any function $h:\mathbb{R}^n o \mathbb{R}$, define new function $\check{h}:\mathbf{R}^n o \mathbb{R}$ via:

$$\check{h}(x) = \sup \left\{ g(x) : g \text{ is convex \& } g(y) \le h(y), \forall y \in \mathbb{R}^n \right\} \tag{14.7}$$

Lemma 14.4.3

 $\check{f}(x) = \min_{p \in \triangle^n(x)} E_{S \sim p}[f(S)]$ is the convex envelope.

Proof.

- Suppose \exists a convex \bar{f} with $\bar{f}(\mathbf{1}_A) = f(A) = \check{f}(\mathbf{1}_A), \forall A \subseteq V$ and $\exists x \in [0,1]^V$ s.t. $\bar{f}(x) > \check{f}(x)$.
- Define p^x to be an achiving argmin in $\check{f}(x) = \min_{p \in \triangle^n(x)} E_{S \sim p}[f(S)]$. Hence, we have $x = \sum_S p_S^x \mathbf{1}_S$. Thus

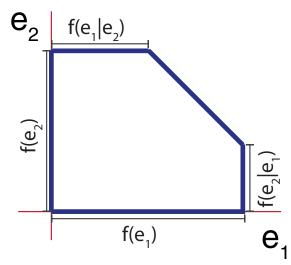
$$\check{f}(x) = \sum_{S} p_S^x f(S) = \sum_{S} p_S^x \bar{f}(\mathbf{1}_S)$$
(14.15)

$$\langle \bar{f}(x) = \bar{f}(\sum_{S} p_S^x \mathbf{1}_S)$$
 (14.16)

but this contradicts the convexity of \bar{f} .

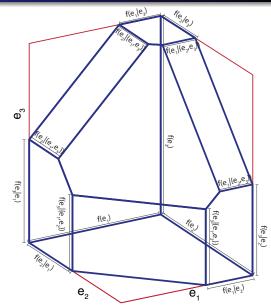
Polymatroid with labeled edge lengths

- Recall f(e|A) = f(A+e) - f(A)
- Notice how submodularity, $f(e|B) \leq f(e|A)$ for $A \subseteq B$, defines the shape of the polytope.
- In fact, we have strictness here f(e|B) < f(e|A) for $A \subset B$.
- Also, consider how the greedy algorithm proceeds along the edges of the polytope.



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- In fact, we have strictness here f(e|B) < f(e|A) for $A \subset B$.
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$$\begin{array}{ll} \text{maximize} & w^{\mathsf{T}}x & \text{(14.17a)} \\ \text{subject to} & x \in P_f & \text{(14.17b)} \end{array}$$

maximize
$$w^{\mathsf{T}}x$$
 (14.17a)
subject to $x \in P_f$ (14.17b)

• Since P_f is down closed, if $\exists e \in E$ with w(e) < 0 then the solution above is unboundedly large.

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• Since P_f is down closed, if $\exists e \in E$ with w(e) < 0 then the solution above is unboundedly large. Hence, assume $w \in \mathbb{R}_+^E$.

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- Since P_f is down closed, if $\exists e \in E$ with w(e) < 0 then the solution above is unboundedly large. Hence, assume $w \in \mathbb{R}_+^E$.
- Due to Theorem ??, any $x \in P_f$ with $x \notin B_f$ is dominated by $x \leq y \in B_f$ which can only increase $w^\intercal x \leq w^\intercal y$ when $w \in \mathbb{R}_+^E$.

Optimization over P_f

• Consider the following optimization. Given $w \in \mathbb{R}^E$,

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- Since P_f is down closed, if $\exists e \in E$ with w(e) < 0 then the solution above is unboundedly large. Hence, assume $w \in \mathbb{R}^E_+$.
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- Hence, the problem is equivalent to: given $w \in \mathbb{R}_+^E$,

maximize
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- Due to Theorem ??, any $x \in P_f$ with $x \notin B_f$ is dominated by $x \leq y \in B_f$ which can only increase $w^\intercal x \leq w^\intercal y$ when $w \in \mathbb{R}_+^E$.
- Hence, the problem is equivalent to: given $w \in \mathbb{R}_+^E$,

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• Moreover, we can have $w \in \mathbb{R}^E$ if we insist on $x \in B_f$.

A continuous extension of *f*

• Consider again optimization problem. Given $w \in \mathbb{R}^E$,

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ullet We may consider this optimization problem a function $reve{f}:\mathbb{R}^E o \mathbb{R}$ of $w \in \mathbb{R}^E$. defined as:

$$\check{f}(w) = \max(wx : x \in B_f) \tag{14.20}$$

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ullet Hence, for any w, from the solution to the above theorem (as we have seen), we can compute the value of this function using Edmond's greedy algorithm.

- Edmonds proved that the solution to $\check{f}(w) = \max(wx : x \in B_f)$ is solved by the greedy algorithm iff f is submodular.
- In particular, sort choose element order (e_1, e_2, \dots, e_m) based on decreasing w, so that $w(e_1) \ge w(e_2) \ge \cdots \ge w(e_m)$.
- Define the chain with i^{th} element $E_i = \{e_1, e_2, \dots, e_i\}$.
- Define a vector $x^* \in \mathbb{R}^V$ where element e_i has value $x(e_i) = f(e_i|E_{i-1})$ for all $i \in V$.
- Then $\langle w, x^* \rangle = \max(wx : x \in B_f)$

Theorem 14.5.1 (Edmonds)

If $f: 2^E \to \mathbb{R}_+$ is given, and B is a polytope in \mathbb{R}_+^E of the form $B = \left\{x \in \mathbb{R}_+^E: x(A) \leq f(A), \forall A \subseteq E, x(E) = f(E)\right\}$, then the greedy solution to the problem $\max(w^\intercal x: x \in P)$ is $\forall w$ optimum iff f is monotone non-decreasing submodular (i.e., iff P is a polymatroid).

• That is, given a submodular function f, a $w \in \mathbb{R}^E$, choose element order (e_1, e_2, \dots, e_m) based on decreasing w, so that $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$.

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- ullet Define the chain with $i^{ ext{th}}$ element $E_i = \{e_1, e_2, \ldots, e_i\}$, we have

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- Define the chain with i^{th} element $E_i = \{e_1, e_2, \dots, e_i\}$, we have

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$$= \sum_{i=1}^{m} w(e_i) f(e_i | E_{i-1}) = \sum_{i=1}^{m} w(e_i) x(e_i)$$
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- That is, given a submodular function f, a $w \in \mathbb{R}^E$, choose element order (e_1, e_2, \ldots, e_m) based on decreasing w, so that $w(e_1) > w(e_2) > \cdots > w(e_m)$.
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• We say that $\emptyset \triangleq E_0 \subset E_1 \subset E_2 \subset \cdots \subset E_m = E$ forms a chain based on w.

• Definition of the continuous extension, once again, for reference:

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• Convex analysis $\Rightarrow \check{f}(w) = \max(wx : x \in P)$ is always convex in w for any set $P \subseteq R^E$, since a maximum of a set of linear functions (true even when f is not submodular or P is not itself a convex set).

An extension of f

ullet Recall, for any such $w \in \mathbb{R}^E$, we have

$$\begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{pmatrix} = \underbrace{\begin{pmatrix} w_1 - w_2 \end{pmatrix}}_{\lambda_1} \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \underbrace{\begin{pmatrix} w_2 - w_3 \end{pmatrix}}_{\lambda_2} \begin{pmatrix} 1 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \underbrace{\begin{pmatrix} w_1 - w_2 \end{pmatrix}}_{\lambda_m} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 0 \end{pmatrix} + \underbrace{\begin{pmatrix} w_1 - w_2 \end{pmatrix}}_{\lambda_m} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 0 \end{pmatrix} + \underbrace{\begin{pmatrix} w_1 - w_2 \end{pmatrix}}_{\lambda_m} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 1 \end{pmatrix}$$
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$$\cdots + \underbrace{(w_{n-1} - w_n)}_{\lambda_{m-1}} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 0 \end{pmatrix} + \underbrace{(w_m)}_{\lambda_m} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 1 \end{pmatrix} \qquad (14.28)$$

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- If we take w in decreasing order, then each coefficient of the vectors is non-negative (except possibly the last one, $\lambda_m=w_m$).
- Often, we take $w \in \mathbb{R}^V_+$ or even $w \in [0,1]^V$, where $\lambda_m \geq 0$.

ullet Define sets E_i based on this decreasing order of w as follows, for $i=0,\ldots,n$

$$E_i \stackrel{\text{def}}{=} \{e_1, e_2, \dots, e_i\}$$
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Note that

$$\mathbf{1}_{E_0} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \mathbf{1}_{E_1} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \dots, \mathbf{1}_{E_\ell} = \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \begin{pmatrix} \times \\ \vdots \\ 1 \\ 0 \\ 0 \\ \vdots \\ (n-\ell) imes \end{pmatrix}, \; etc.$$

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ullet Hence, from the previous and current slide, we have $w=\sum_{i=1}^m \lambda_i \mathbf{1}_{E_i}$

From \check{f} back to f, even when f is not submodular

• From the continuous \check{f} , we can recover f(A) for any $A \subseteq V$.

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- This means

$$w = (w(e_1), w(e_2), \dots, w(e_m)) = (\underbrace{1, 1, 1, \dots, 1}_{|A| \text{ times}}, \underbrace{0, 0, \dots, 0}_{m-|A| \text{ times}})$$
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so that $1_A(i) = 1$ if $i \leq |A|$, and $1_A(i) = 0$ otherwise.

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$$w = (w(e_1), w(e_2), \dots, w(e_m)) = \underbrace{(1, 1, 1, \dots, 1, \underbrace{0, 0, \dots, 0}_{m-|A| \text{ times}})}_{|A| \text{ times}}, \underbrace{0, 0, \dots, 0}_{m-|A| \text{ times}})$$
(14.30)

• For any $f: 2^E \to \mathbb{R}$, $w = \mathbf{1}_A$, since $E_{|A|} = \{e_1, e_2, \dots, e_{|A|}\} = A$:

$$\check{f}(w) = \sum_{i=1}^{m} \lambda_i f(E_i) = w(e_m) f(E_m) + \sum_{i=1}^{m-1} (w(e_i) - w(e_{i+1}) f(E_i))$$

- From the continuous \check{f} , we can recover f(A) for any $A \subseteq V$.
- Take $w = \mathbf{1}_A$ for some $A \subseteq E$, so w is vertex of the hypercube.
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$$= \mathbf{1}_{A}(m)f(E_{m}) + \sum_{i=1}^{n} (\mathbf{1}_{A}(i) - \mathbf{1}_{A}(i+1))f(E_{i})$$
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From f back to f

• We can view $\check{f}:[0,1]^E\to\mathbb{R}$ defined on the hypercube, with f defined as \check{f} evaluated on the hypercube extreme points (vertices).

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• ... and when f is submodular, we also have have

$$\check{f}(\mathbf{1}_A) = \max \left\{ \mathbf{1}_A^{\mathsf{T}} x : x \in B_f \right\} \tag{14.34}$$

$$= \max \left\{ \mathbf{1}_A^{\mathsf{T}} x : x(B) \le f(B), \forall B \subseteq E \right\} \tag{14.35}$$

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• Note when considering only $\check{f}:[0,1]^E\to\mathbb{R}$, then any $w\in[0,1]^E$ is in positive orthant, and we have

$$\check{f}(w) = \max\left\{w^{\mathsf{T}}x : x \in P_f\right\} \tag{14.36}$$

An extension of an arbitrary $f: 2^V \to \mathbb{R}$

• Thus, for any $f: 2^E \to \mathbb{R}$, even non-submodular f, we can define an extension, having $\check{f}(\mathbf{1}_A) = f(A), \ \forall A$, in this way where

$$\check{f}(w) = \sum_{i=1}^{m} \lambda_i f(E_i)$$
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with the $E_i = \{e_1, \dots, e_i\}$'s defined based on sorted descending order of w as in $w(e_1) > w(e_2) > \cdots > w(e_m)$, and where

for
$$i \in \{1, ..., m\}$$
, $\lambda_i = \begin{cases} w(e_i) - w(e_{i+1}) & \text{if } i < m \\ w(e_m) & \text{if } i = m \end{cases}$ (14.38)

so that $w = \sum_{i=1}^m \lambda_i \mathbf{1}_{E_i}$.

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- $\check{f}(w) = \sum_{i=1}^{m} \lambda_i f(E_i)$ is the associated interpolation of the values of f at sets corresponding to each hypercube vertex.

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- $w = \sum_{i=1}^{m} \lambda_i \mathbf{1}_{E_i}$ is an interpolation of certain hypercube vertices.
- $\check{f}(w) = \sum_{i=1}^{m} \lambda_i f(E_i)$ is the associated interpolation of the values of f at sets corresponding to each hypercube vertex.
- This extension is called the Lovász extension!

Weighted gains vs. weighted functions

ullet Again sorting E descending in w, the extension summarized:

$$\check{f}(w) = \sum_{i=1}^{m} w(e_i) f(e_i | E_{i-1})$$
(14.39)

$$= \sum_{i=1}^{m} w(e_i)(f(E_i) - f(E_{i-1}))$$
(14.40)

$$= w(e_m)f(E_m) + \sum_{i=1}^{m-1} (w(e_i) - w(e_{i+1}))f(E_i)$$
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$$=\sum_{i=1}^{m}\lambda_{i}f(E_{i})\tag{14.42}$$

• So $\check{f}(w)$ seen either as sum of weighted gain evaluations (Eqn. (14.39)), or as sum of weighted function evaluations (Eqn. (14.42)).

• So if f is submodular, then we can write $f(w) = \max(wx : x \in B_f)$ (which is clearly convex) in the form:

$$\check{f}(w) = \max(wx : x \in B_f) = \sum_{i=1}^{m} \lambda_i f(E_i)$$
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where $w = \sum_{i=1}^{m} \lambda_i \mathbf{1}_{E_i}$ and $E_i = \{e_1, \dots, e_i\}$ defined based on sorted descending order $w(e_1) \geq w(e_2) \geq \cdots \geq w(e_m)$.

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• On the other hand, for any f (even non-submodular), we can produce an extension \check{f} having the form

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Summary: comparison of the two extension forms

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• In both Eq. (14.43) and Eq. (14.44), we have $\check{f}(\mathbf{1}_A) = f(A), \ \forall A, \ \mathsf{but}$ Eq. (14.44), might not be convex.

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- In both Eq. (14.43) and Eq. (14.44), we have $\check{f}(\mathbf{1}_A) = f(A), \ \forall A, \ \mathsf{but}$ Eq. (14.44), might not be convex.
- Submodularity is sufficient for convexity, but is it necessary?

• Lovász showed that if a function $\check{f}(w)$ defined as in Eqn. (14.37) is convex, then f must be submodular.

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- This continuous extension \check{f} of f, in any case (f being submodular or not), is typically called the Lovász extension of f (but also sometimes called the Choquet integral, or the Lovász-Edmonds extension).

Lovász Extension, Submodularity and Convexity

Theorem 14.5.2

A function $f: 2^E \to \mathbb{R}$ is submodular iff its Lovász extension \check{f} of f is convex.

Proof.

• We've already seen that if f is submodular, its extension can be written via Eqn.(14.37) due to the greedy algorithm, and therefore is also equivalent to $\check{f}(w) = \max\{wx : x \in P_f\}$, and thus is convex.

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- Conversely, suppose the Lovász extension $\check{f}(w) = \sum_i \lambda_i f(E_i)$ of some function $f: 2^E \to \mathbb{R}$ is a convex function.

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- Conversely, suppose the Lovász extension $\check{f}(w) = \sum_i \lambda_i f(E_i)$ of some function $f: 2^E \to \mathbb{R}$ is a convex function.
- We note that, based on the extension definition, in particular the definition of the $\{\lambda_i\}_i$, we have that $\check{f}(\alpha w) = \alpha \check{f}(w)$ for any $\alpha \in \mathbb{R}_+$. I.e., f is a positively homogeneous convex function.

. . .

... proof of Thm. 14.5.2 cont.

ullet Earlier, we saw that $\check{f}(\mathbf{1}_A)=f(A)$ for all $A\subseteq E.$

Lovász Extension, Submodularity and Convexity

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- Earlier, we saw that $\check{f}(\mathbf{1}_A) = f(A)$ for all $A \subseteq E$.
- Now, given $A, B \subseteq E$, we will show that

$$\check{f}(\mathbf{1}_A + \mathbf{1}_B) = \check{f}(\mathbf{1}_{A \cup B} + \mathbf{1}_{A \cap B})$$
(14.45)

$$= f(A \cup B) + f(A \cap B). \tag{14.46}$$

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• Let $C = A \cap B$, order E based on decreasing $w = \mathbf{1}_A + \mathbf{1}_B$ so that

$$w = (w(e_1), w(e_2), \dots, w(e_m))$$
(14.47)

$$= (\underbrace{2, 2, \dots, 2}_{i \in C}, \underbrace{1, 1, \dots, 1}_{i \in A \triangle B}, \underbrace{0, 0, \dots, 0}_{i \in E \setminus (A \cup B)})$$
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Lovász Extension, Submodularity and Convexity

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• Then, considering $\check{f}(w) = \sum_i \lambda_i f(E_i)$, we have $\lambda_{|C|} = 1$, $\lambda_{|A \cup B|} = 1$, and $\lambda_i = 0$ for $i \notin \{|C|, |A \cup B|\}$.

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- Then, considering $\check{f}(w) = \sum_i \lambda_i f(E_i)$, we have $\lambda_{|C|} = 1$, $\lambda_{|A \cup B|} = 1$, and $\lambda_i = 0$ for $i \notin \{|C|, |A \cup B|\}$.
- But then $E_{|C|} = A \cap B$ and $E_{|A \cup B|} = A \cup B$. Therefore, $\breve{f}(w) = \breve{f}(\mathbf{1}_A + \mathbf{1}_B) = f(A \cap B) + f(A \cup B).$

... proof of Thm. 14.5.2 cont.

ullet Also, since \check{f} is convex (by assumption) and positively homogeneous, we have for any $A,B\subseteq E$,

$$0.5[f(A\cap B) + f(A\cup B)]$$

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... proof of Thm. 14.5<u>.2 cont.</u>

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Lovász Extension, Submodularity and Convexity

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$$\leq 0.5 \check{f}(\mathbf{1}_A) + 0.5 \check{f}(\mathbf{1}_B)$$
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Lovász Extension, Submodularity and Convexity

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$$= 0.5(f(A) + f(B))$$
 (14.52)

ullet Thus, we have shown that for any $A,B\subseteq E$,

$$f(A \cup B) + f(A \cap B) \le f(A) + f(B)$$
 (14.53)

so f must be submodular.



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- ullet Hence, convex closure is easy to evaluate when f is submodular and is this particular form iff f is submodular.

Theorem 14.5.3

Let $\check{f}(w) = \max(wx : x \in B_f) = \sum_{i=1}^m \lambda_i f(E_i)$ be the Lovász extension and $\check{f}(x) = \min_{p \in \triangle^n(x)} E_{S \sim p}[f(S)]$ be the convex closure. Then \check{f} and \check{f} coincide iff f is submodular.

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- Then we may update p^x as follows:

$$\bar{p}_A^x \leftarrow p_A^x - p_B^x \qquad \bar{p}_B^x \leftarrow p_B^x - p_B^x \qquad (14.54)$$

 $\bar{p}_{A \cup B}^x \leftarrow p_{A \cup B}^x + p_B^x \qquad \bar{p}_{A \cap B}^x \leftarrow p_{A \cap B}^x + p_B^x \qquad (14.55)$ and by submodularity, this does not increase $\sum_S p_S^x f(S)$.

... proof cont.

ullet This does increase $\sum_S p_S^x |S|^2$ however since

$$|A \cup B|^{2} + |A \cap B|^{2} = (|A| + |B \setminus A|)^{2} + (|B| - |B \setminus A|)^{2}$$
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$$= |A|^{2} + |B|^{2} + 2|B \setminus A|(|A| - |B| + |B \setminus A|)$$
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• Contradiction! Hence, there can be no crossing sets A,B and we must have, for any A,B with $p_A^x>0$ and $p_B^x>0$ either $A\subset B$ or $B\subset A$.

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- Hence, the sets $\{A\subseteq V: p_A^x>0\}$ form a chain and can be as large only as size n=|V|.

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- Hence, the sets $\{A\subseteq V: p_A^x>0\}$ form a chain and can be as large only as size n=|V|.
- This is the same chain that defines the Lovász extension $\check{f}(x)$, namely $\emptyset = E_0 \subseteq E_1 \subseteq E_2 \subset \ldots$ where $E_i = \{e_1, e_2, \ldots, e_i\}$ and e_i is orderd so that $x(e_1) \ge x(e_2) \ge \cdots \ge x(e_n)$.

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- Since f is not submodular, $\exists S$ and $i,j \notin S$ such that f(S)+f(S+i+j)>f(S+i)+f(S+j), a strict violation of submodularity.

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- Then $\check{f}(x)=\frac{1}{2}f(S)+\frac{1}{2}f(S+i+j)$ and p^x is feasible for \check{f} with $p_S^x=1/2$ and $p_{S+i+j}^x=1/2$.

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- An alternate feasible distribution for x in the convex closure is $\bar{p}^x_{S+i} = \bar{p}^x_{S+j} = 1/2.$

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- An alternate feasible distribution for x in the convex closure is $\bar{p}_{S+i}^x = \bar{p}_{S+j}^x = 1/2.$
- This gives

$$\check{f}(x) \le \frac{1}{2} [f(S+i) + f(S+j)] < \check{f}(x)$$
(14.59)

meaning $\check{f}(x) \neq \check{f}(x)$.