## Submodular Functions, Optimization, and Applications to Machine Learning

- Spring Quarter, Lecture 5 http://j.ee.washington.edu/~bilmes/classes/ee596b_spring_2014/


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$$
f(A)+f(B) \geq f(A \cup B)+f(A \cap B)
$$

$=r\left(A,+2 f(C)+\left(B B_{i}\right)=r(A)+f(C)+r(B) \quad=r\left(A A_{B}\right)\right.$
00


## Cumulative Outstanding Reading

- Read chapter 1 from Fujishige's book.


## Announcements, Assignments, and Reminders

- our room (Mueller Hall Room 154) is changed!
- Please do use our discussion board (https:
//canvas.uw.edu/courses/895956/discussion_topics) for all questions, comments, so that all will benefit from them being answered.
- Weekly Office Hours: Wednesdays, 5:00-5:50, or by skype or google hangout (email me).


## Class Road Map - IT-I

- L1 (3/31): Motivation, Applications, \& Basic Definitions
- L2: (4/2): Applications, Basic Definitions, Properties
- L3: More examples and properties (e.g., closure properties), and examples, spanning trees
- L4: proofs of equivalent definitions, independence, start matroids
- L5: matroids, basic definitions and examples
- L6: More on matroids, System of Distinct Reps, Transversals, Transversal Matroid, Matroid and representation
- L7: Dual Matroids, other matroid properties, Combinatorial Geometries
- L8: Combinatorial Geometries, matroids and greedy, Polyhedra, Matroid Polytopes,
- L9: From Matroid Polytopes to Polymatroids.
- L10: Polymatroids and Submodularity
- L11: More properties of polymatroids, SFM special cases
L12: polymatroid properties, extreme points polymatroids,
- L13: sat, dep, supp, exchange capacity, examples
- L14: Lattice theory: partially ordered sets; lattices; distributive, modular, submodular, and boolean lattices; ideals and join irreducibles.
- L15: Supp, Base polytope, polymatroids and entropic Venn diagrams, exchange capacity,
- L16: proof that minimum norm point yields min of submodular function, and the lattice of minimizers of a submodular function, Lovasz extension
- L17: Lovasz extension, Choquet Integration, more properties/examples of Lovasz extension, convex minimization and SFM.
- L18: Lovasz extension examples and structured convex norms, The Min-Norm Point Algorithm detailed.
- L19: symmetric submodular function minimization, maximizing monotone submodular function w . card constraints.
- L20: maximizing monotone submodular function $w$. other constraints, non-monotone maximization.

Finals Week: June 9th-13th, 2014.

## Many (Equivalent) Definitions of Submodularity

$$
\begin{align*}
f(A)+f(B) & \geq f(A \cup B)+f(A \cap B), \forall A, B \subseteq V  \tag{5.6}\\
f(j \mid S) & \geq f(j \mid T), \forall S \subseteq T \subseteq V, \text { with } j \in V \backslash T  \tag{5.7}\\
f(C \mid S) & \geq f(C \mid T), \forall S \subseteq T \subseteq V, \text { with } C \subseteq V \backslash T  \tag{5.8}\\
f(j \mid S) & \geq f(j \mid S \cup\{k\}), \forall S \subseteq V \text { with } j \in V \backslash(S \cup\{k\}) \tag{5.9}
\end{align*}
$$

$$
\begin{equation*}
f(A \cup B \mid A \cap B) \leq f(A \mid A \cap B)+f(B \mid A \cap B), \quad \forall A, B \subseteq V \tag{5.10}
\end{equation*}
$$

$$
\begin{equation*}
f(T) \leq f(S)+\sum_{j \in T \backslash S} f(j \mid S)-\sum_{j \in S \backslash T} f(j \mid S \cup T-\{j\}), \forall S, T \subseteq V \tag{5.11}
\end{equation*}
$$

$$
\begin{equation*}
f(T) \leq f(S)+\sum_{j \in T \backslash S} f(j \mid S), \forall S \subseteq T \subseteq V \tag{5.12}
\end{equation*}
$$

$$
f(T) \leq f(S)-\sum_{j \in S \backslash T} f(j \mid S \backslash\{j\})+\sum_{j \in T \backslash S} f(j \mid S \cap T) \forall S, T \subseteq
$$

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- We saw several different "greedy" algorithms that proced optimal spanning trees (Borůvka's, Jarník/Prim/Dijkstra's, and Kruskal's).
- We wish to more formally connect the above, and generalize further.


## From Matrix Rank $\rightarrow$ Matroid

- So $V$ is set of column vector indices of a matrix.
- Let $\mathcal{I}$ be a set of all subsets of $V$ such that for any $I \in \mathcal{I}$, the vectors indexed by $I$ are linearly independent.
- Given a set $B \in \mathcal{I}$ of linearly independent vectors, then any subset $A \subseteq B$ is also linearly independent. Hence, $\mathcal{I}$ is down-closed or "subclusive", under subsets. In other words,

$$
\begin{equation*}
A \subseteq B \text { and } B \in \mathcal{I} \Rightarrow A \in \mathcal{I} \tag{5.32}
\end{equation*}
$$

- maxInd: Inclusionwise maximal independent subsets (or bases) of any set $B \subseteq V$.

$$
\begin{equation*}
\max \operatorname{lnd}(B) \triangleq\{A \subseteq B: A \in \mathcal{I} \text { and } \forall v \in B \backslash A, A \cup\{v\} \notin \mathcal{I}\} \tag{5.33}
\end{equation*}
$$

- Given any set $B \subset V$ of vectors, all maximal (by set inclusion) subsets of linearly independent vectors are the same size. That is, for all $B \subseteq V$,

$$
\begin{equation*}
\forall A_{1}, A_{2} \in \operatorname{max\operatorname {lnd}(B),\quad |A_{1}|=|A_{2}|...} \tag{5.34}
\end{equation*}
$$

## From Matrix Rank $\rightarrow$ Matroid

- Thus, for all $I \in \mathcal{I}$, the matrix rank function has the property

$$
\begin{equation*}
r(I)=|I| \tag{5.32}
\end{equation*}
$$

and for any $B \notin \mathcal{I}$,

$$
\begin{equation*}
r(B)=\max \{|A|: A \subseteq B \text { and } A \in \mathcal{I}\} \leq|B| \tag{5.33}
\end{equation*}
$$

## Matroid

Independent set definition of a matroid is perhaps most natural. Note, if $J \in \mathcal{I}$, then $J$ is said to be an independent set.

## Definition 5.2.4 (Matroid)

A set system $(E, \mathcal{I})$ is a Matroid if
(I1) $\emptyset \in \mathcal{I}$
(I2) $\forall I \in \mathcal{I}, J \subset I \Rightarrow J \in \mathcal{I}$
(I3) $\forall I, J \in \mathcal{I}$, with $|I|=|J|+1$, then there exists $x \in I \backslash J$ such that $J \cup\{x\} \in \mathcal{I}$.

Why is (I1) is not redundant given (I2)? Because without (I1) could have a non-matroid where $\mathcal{I}=\{ \}$.

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- Matroid independent sets (i.e., $A$ s.t. $r(A)=|A|$ ) are useful constraint set, and fast algorithms for submodular optimization subject to one (or more) matroid independence constraints exist.


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- Crapo \& Rota preferred the term "combinatorial geometry", or more specifically a "pregeometry" and said that pregeometries are "often described by the ineffably cacaphonic [sic] term 'matroid', which we prefer to avoid in favor of the term 'pregeometry'."


## Matroid

Slight modification (non unit increment) that is equivalent.

## Definition 5.3.1 (Matroid-II)

A set system $(E, \mathcal{I})$ is a Matroid if
(I1') $\emptyset \in \mathcal{I}$
(I2') $\forall I \in \mathcal{I}, J \subset I \Rightarrow J \in \mathcal{I}$ (or "down-closed")
(I3') $\forall I, J \in \mathcal{I}$, with $|I|>|J|$, then there exists $x \in I \backslash J$ such that $J \cup\{x\} \in \mathcal{I}$

Note $(I 1)=\left(I 1^{\prime}\right),(I 2)=\left(I 2^{\prime}\right)$, and we get $(I 3) \equiv\left(I 3^{\prime}\right)$ using induction.

## Matroids, independent sets, and bases

- Independent sets: Given a matroid $M=(E, \mathcal{I})$, a subset $A \subseteq E$ is called independent if $A \in \mathcal{I}$ and otherwise $A$ is called dependent.


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- A base of a matroid: If $U=E$, then a "base of $E$ " is just called a base of the matroid $M$ (this corresponds to a basis in a linear space).


## Matroids - important property

## Proposition 5.3.2

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(I3') $\forall X \subseteq V$, and $I_{1}, I_{2} \in \max \operatorname{lnd}(X)$, we have $\left|I_{1}\right|=\left|I_{2}\right|$ (all maximally independent subsets of $X$ have the same size).

## Matroids - rank

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## Definition 5.3.4 (matroid rank function)

The rank of a matroid is a function $r: 2^{E} \rightarrow \mathbb{Z}_{+}$defined by

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\begin{equation*}
r(A)=\max \{|X|: X \subseteq A, X \in \mathcal{I}\}=\max _{X \in \mathcal{I}}|A \cap X| \tag{5.1}
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- From the above, we immediately see that $r(A) \leq|A|$.
- Moreover, if $r(A)=|A|$, then $A \in \mathcal{I}$, meaning $A$ is independent (in this case, $A$ is a self base).


## Matroids, other definitions using matroid rank $r: 2^{V} \rightarrow \mathbb{Z}_{+}$

## Definition 5.3.5 (closed/flat/subspace)

A subset $A \subseteq E$ is closed (equivalently, a flat or a subspace) of matroid $M$ if for all $x \in E \backslash A, r(A \cup\{x\})=r(A)+1$.

A hyperplane is a flat of rank $r(M)-1$.

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## Definition 5.3.6 (closure)

Given $A \subseteq E$, the closure (or span) of $A$, is defined by $\operatorname{span}(A)=\{b \in E: r(A \cup\{b\})=r(A)\}$.

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## Definition 5.3.7 (circuit)

A subset $A \subseteq E$ is circuit or a cycle if it is an inclusionwise-minimal dependent set (i.e., if $r(A)<|A|$ and for any $a \in A$, $r(A \backslash\{a\})=|A|-1)$.

## Matroids by bases

In general, besides independent sets and rank functions, there are other equivalent ways to characterize matroids.

## Theorem 5.3.8 (Matroid (by bases))

Let $E$ be a set and $\mathcal{B}$ be a nonempty collection of subsets of $E$. Then the following are equivalent.
(1) $\mathcal{B}$ is the collection of bases of a matroid;
(2) if $B, B^{\prime} \in \mathcal{B}$, and $x \in B^{\prime} \backslash B$, then $B^{\prime}-x+y \in \mathcal{B}$ for some $y \in B \backslash B^{\prime}$.
(3) If $B, B^{\prime} \in \mathcal{B}$, and $x \in B^{\prime} \backslash B$, then $B-y+x \in \mathcal{B}$ for some $y \in B \backslash B^{\prime}$.

Properties 2 and 3 are called "exchange properties."

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Properties 2 and 3 are called "exchange properties."
Proof here is omitted but think about this for a moment in terms of linear spaces and matrices, and (alternatively) spanning trees.

## Matroids by circuits

A set is independent if and only if it contains no circuit. Therefore, it is not surprising that circuits can also characterize a matroid.

## Theorem 5.3.9 (Matroid by circuits)

Let $E$ be a set and $\mathcal{C}$ be a collection of subsets of $E$ that satisfy the following three properties:
(1) (C1): $\emptyset \notin \mathcal{C}$
(2) (C2): if $C_{1}, C_{2} \in \mathcal{C}$ and $C_{1} \subseteq C_{2}$, then $C_{1}=C_{2}$.

3 (C3): if $C_{1}, C_{2} \in \mathcal{C}$ with $C_{1} \neq C_{2}$, and $e \in C_{1} \cap C_{2}$, then there exists a $C_{3} \in \mathcal{C}$ such that $C_{3} \subseteq\left(C_{1} \cup C_{2}\right) \backslash\{e\}$.

## Matroids by circuits

Several circuit definitions for matroids.

## Theorem 5.3.10 (Matroid by circuits)

Let $E$ be a set and $\mathcal{C}$ be a collection of nonempty subsets of $E$, such that no two sets in $\mathcal{C}$ are contained in each other. Then the following are equivalent.
(1) $\mathcal{C}$ is the collection of circuits of a matroid;
(2) if $C, C^{\prime} \in \mathcal{C}$, and $x \in C \cap C^{\prime}$, then $\left(C \cup C^{\prime}\right) \backslash\{x\}$ contains a set in $\mathcal{C}$;
(3) if $C, C^{\prime} \in \mathcal{C}$, and $x \in C \cap C^{\prime}$, and $y \in C \backslash C^{\prime}$, then $\left(C \cup C^{\prime}\right) \backslash\{x\}$ contains a set in $\mathcal{C}$ containing $y$;

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Several circuit definitions for matroids.

## Theorem 5.3.10 (Matroid by circuits)

Let $E$ be a set and $\mathcal{C}$ be a collection of nonempty subsets of $E$, such that no two sets in $\mathcal{C}$ are contained in each other. Then the following are equivalent.
(1) $\mathcal{C}$ is the collection of circuits of a matroid;
(2) if $C, C^{\prime} \in \mathcal{C}$, and $x \in C \cap C^{\prime}$, then $\left(C \cup C^{\prime}\right) \backslash\{x\}$ contains a set in $\mathcal{C}$;

- if $C, C^{\prime} \in \mathcal{C}$, and $x \in C \cap C^{\prime}$, and $y \in C \backslash C^{\prime}$, then $\left(C \cup C^{\prime}\right) \backslash\{x\}$ contains a set in $\mathcal{C}$ containing $y$;

Again, think about this for a moment in terms of linear spaces and matrices, and spanning trees.

## Matroids by submodular functions

## Theorem 5.3.11 (Matroid by submodular functions)

Let $f: 2^{E} \rightarrow \mathbb{Z}$ be a integer valued monotone non-decreasing submodular function. Define a set of sets as follows:

$$
\mathcal{C}(f)=\{C \subseteq E: C \text { is non-empty, }
$$

is inclusionwise-minimal, and has $f(C)<|C|\}$

Then $\mathcal{C}(f)$ is the collection of circuits of a matroid on $E$.
Inclusionwise-minimal in this case means that if $C \in \mathcal{C}(f)$, then there exists no $C^{\prime} \subset C$ with $C^{\prime} \in \mathcal{C}(f)$ (i.e., $C^{\prime} \subset C$ would either be empty or have $\left.f\left(C^{\prime}\right) \geq\left|C^{\prime}\right|\right)$. Also, recall inclusionwise-minimal in Definition 5.3.7, the definition of a circuit.

## Uniform Matroid

- Given $E$, consider $\mathcal{I}$ to be all subsets of $E$ that are at most size $k$. That is $\mathcal{I}=\{A \subseteq E:|A| \leq k\}$.


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- A "free" matroid sets $k=|E|$, so everything is independent.


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- rank is submodular, it is intuitive that it satisfies the diminishing returns property (a given vector can only become linearly dependent in a greater context, thereby no longer contributing to rank).
- Called both linear matroids and matric matroids.


## Cycle Matroid of a graph: Graphic Matroids

- Let $G=(V, E)$ be a graph. Consider $(E, \mathcal{I})$ where the edges of the graph $E$ are the ground set and $A \in \mathcal{I}$ if the edge-induced graph $G(V, A)$ by $A$ does not contain any cycle.


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- Bases are spanning forests (spanning trees if $G$ is connected).
- Rank function $r(A)$ is the size of the largest spanning forest contained in $G(V, A)$.
- Closure function adds all edges between the vertices adjacent to any edge in $A$. Closure of a spanning forest is $G$.


## Example: graphic matroid

- A graph defines a matroid on edge sets, independent sets are those without a cycle.



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\begin{equation*}
\mathcal{I}=\left\{X \subseteq V:\left|X \cap V_{i}\right| \leq k_{i} \text { for all } i=1, \ldots, \ell\right\} \tag{5.5}
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- Parameters associated with a partition matroid: $\ell$ and $k_{1}, k_{2}, \ldots, k_{\ell}$ although often the $k_{i}$ 's are all the same.
- We'll show that property (I3') in Def 5.3.3 holds. If $X, Y \in \mathcal{I}$ with $|Y|>|X|$, then there must be at least one $i$ with $\left|Y \cap V_{i}\right|>\left|X \cap V_{i}\right|$. Therefore, adding one element $e \in V_{i} \cap(Y \backslash X)$ to $X$ won't break independence.


## Partition Matroid

Ground set of objects, $V=\{$


## Partition Matroid

Partition of $V$ into six blocks, $V_{1}, V_{2}, \ldots, V_{6}$


## Partition Matroid

Limit associated with each block, $\left\{k_{1}, k_{2}, \ldots, k_{6}\right\}$


## Partition Matroid

## Independent subset but not maximally independent.



## Partition Matroid

Maximally independent subset, what is called a base.


Partition Matroid
Not independent since over limit in set six.


## Matroids - rank

## Lemma 5.5.1

The rank function $r: 2^{E} \rightarrow \mathbb{Z}_{+}$of a matroid is submodular, that is $r(A)+r(B) \geq r(A \cup B)+r(A \cap B)$

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& \geq|X|+|Y|=r(A \cap B)+r(A \cup B) \tag{5.8}
\end{align*}
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## Matroids

In fact, we can use the rank of a matroid for its definition.

## Theorem 5.5.2 (Matroid from rank)

Let $E$ be a set and let $r: 2^{E} \rightarrow \mathbb{Z}_{+}$be a function. Then $r(\cdot)$ defines a matroid with $r$ being its rank function if and only if for all $A, B \subseteq E$ :
(R1) $\forall A \subseteq E \quad 0 \leq r(A) \leq|A|$ (non-negative cardinality bounded)
(R2) $r(A) \leq r(B)$ whenever $A \subseteq B \subseteq E$ (monotone non-decreasing)
(R3) $r(A \cup B)+r(A \cap B) \leq r(A)+r(B)$ for all $A, B \subseteq E$ (submodular)

- So submodularity and non-negative monotone non-decreasing, and unit increase is necessary and sufficient to define the matroid.
- Given above, unit increment (if $r(A)=k$, then either $r(A \cup\{v\})=k$ or $r(A \cup\{v\})=k+1)$ holds.
- A matroid is sometimes given as $(E, r)$ where $E$ is ground set and $r$ is rank function.


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- From above, $r(\emptyset)=0$. Let $v \notin A$, then by monotonicity and submodularity, $r(A) \leq r(A \cup\{v\}) \leq r(A)+r(\{v\})$ which gives only two possible values to $r(A \cup\{v\})$.


## Matroids from rank

## Proof of Theorem 5.5.2 (matroid from rank).

- Given a matroid $M=(E, \mathcal{I})$, we see its rank function as defined in Eq. 5.1 satisfies (R1), (R2), and, as we saw in Lemma 5.5.1, (R3) too.


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implying $r(X)=|X|$, and thus $X \in \mathcal{I}$.

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Proof of Theorem 5.5.2 (matroid from rank) cont.

- Let $A, B \in \mathcal{I}$, with $|A|<|B|$, so $r(A)=|A|<r(B)=|B|$. Let $B \backslash A=\left\{b_{1}, b_{2}, \ldots, b_{k}\right\}$ (note $k \leq|B|$ ).


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(5.14)

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(5.14)
(5.15)

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(5.16)
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(5.14)
(5.15)
(5.16)
giving a contradiction since $B \in \mathcal{I}$.

## Matroids from rank II

Another way of using function $r$ to define a matroid.

## Theorem 5.5.3 (Matroid from rank II)

Let $E$ be a finite set and let $r: 2^{E} \rightarrow \mathbb{Z}_{+}$be a function. Then $r(\cdot)$ defines a matroid with $r$ being its rank function if and only if for all $A \subseteq E$, and $x, y \in E$ :
$\left(\mathrm{R} 1^{\prime}\right) r(\emptyset)=0$;
$\left(\mathrm{R} 2^{\prime}\right) r(X) \leq r(X \cup\{y\}) \leq r(X)+1$;
(R3') If $r(X \cup\{x\})=r(X \cup\{y\})=r(X)$, then $r(X \cup\{x, y\})=r(X)$.

## Summarizing: Many ways to define a Matroid

Summarizing what we've so far seen, we saw that it is possible to uniquely define a matroid based on any of:

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- Independence (define the independent sets).
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- Closure axioms (we didn't see this, but it is possible)
- Rank axioms (normalized, monotone, cardinality bounded, submodular)


## Maximization problems for matroids

- Given a matroid $M=(E, \mathcal{I})$ and a modular cost function $c: E \rightarrow \mathbb{R}$, the task is to find an $X \in \mathcal{I}$ such that $c(X)=\sum_{x \in X} c(x)$ is maximum.
- This seems remarkably similar to the max spanning tree problem.


## Minimization problems for matroids

- Given a matroid $M=(E, \mathcal{I})$ and a modular cost function $c: E \rightarrow \mathbb{R}$, the task is to find a basis $B \in \mathcal{B}$ such that $c(B)$ is minimized.
- This sounds like a set cover problem (find the minimum cost covering set of sets).


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\begin{equation*}
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(3) sums of submodular functions are submodular.

- $r(A)$ is also non-negative integral monotone non-decreasing, so it defines a matroid (the partition matroid).


## Matroid and Rank

- Thus, we can define a matroid as $M=(V, r)$ where $r$ satisfies matroid rank axioms.
- Example: 2-partition matroid rank function: Given natural numbers $a, b \in \mathbb{Z}_{+}$with $a>b$, and any set $R \subseteq V$ with $|R|=a$, two-block partition $V=(R, \bar{R})$, where $\bar{R}=V \backslash R$, define:

$$
\begin{align*}
r(A) & =\min (|A \cap R|, b)+\min (|A \cap \bar{R}|,|\bar{R}|)  \tag{5.19}\\
& =\min (|A \cap R|, b)+|A \cap \bar{R}| \tag{5.20}
\end{align*}
$$

- Partition matroid figure showing this:



## Truncated Matroid Rank Function

- Can use this to define a truncated matroid rank function. With $r(A)=\min (|A \cap R|, b)+|A \cap \bar{R}|, b<a$, define:

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\begin{align*}
f_{R}(A) & =\min \{r(A), a\}  \tag{5.21}\\
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- For any $B$ with $|B \cap R|=\ell$, with $b<\ell<a, f_{R}(B)=b+a-\ell$.
- $R$, the set with minimum valuation amongst size- $a$ sets, is hidden within an exponentially larger set of size- $a$ sets with larger valuation.


## Partition Matroid, rank as matching

- A partition matroid can be viewed using a bipartite graph.
- Letting $V$ denote the ground set, and $V_{1}, V_{2}, \ldots$ the partition, the graph is $G=(V, I, E)$ where $V$ is the ground set, $I$ is a set of "indices", and $E$ is the set of edges.
- $I=\left(I_{1}, I_{2}, \ldots, I_{\ell}\right)$ is a set of $k=\sum_{i=1}^{\ell} k_{i}$ nodes, grouped into $\ell$ clusters, where there are $k_{i}$ nodes in the $i^{\text {th }}$ group $I_{i}$.
- $(v, i) \in E(G)$ iff $v \in V_{j}$ and $i \in I_{j}$.


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- For such a constructed bipartite graph, the rank function of a partition matroid is $r(X)=\sum_{i=1}^{\ell} \min \left(\left|X \cap V_{i}\right|, k_{i}\right)=$ the maximum matching involving $X$.


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- Exercise: what is the rank function here?

