

# Submodular Functions, Optimization, and Applications to Machine Learning

— Spring Quarter, Lecture 3 —

[http://j.ee.washington.edu/~bilmes/classes/ee596b\\_spring\\_2014/](http://j.ee.washington.edu/~bilmes/classes/ee596b_spring_2014/)

Prof. Jeff Bilmes

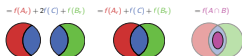
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April 7th, 2014



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# Cumulative Outstanding Reading

- Read chapter 1 from Fujishige's book.

# Announcements, Assignments, and Reminders

- our room (Mueller Hall Room 154) is changed!
- Please do use our discussion board ([https://canvas.uw.edu/courses/895956/discussion\\_topics](https://canvas.uw.edu/courses/895956/discussion_topics)) for all questions, comments, so that all will benefit from them being answered.
- Weekly Office Hours: Wednesdays, 5:00-5:50, or by skype or google hangout (email me).

# Class Road Map - IT-I

- L1 (3/31): Motivation, Applications, & Basic Definitions
- L2: (4/2): Applications, Basic Definitions, Properties
- L3: More examples and properties (e.g., closure properties), and examples, spanning trees
- L4: proofs of equivalent definitions, independence, start matroids
- L5:
- L6:
- L7:
- L8:
- L9:
- L10:
- L11:
- L12:
- L13:
- L14:
- L15:
- L16:
- L17:
- L18:
- L19:
- L20:

Finals Week: June 9th-13th, 2014.

# Submodular Definitions

## Definition 3.2.2 (submodular concave)

A function  $f : 2^V \rightarrow \mathbb{R}$  is **submodular** if for any  $A, B \subseteq V$ , we have that:

$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B) \quad (3.2)$$

An alternate and (as we will soon see) equivalent definition is:

## Definition 3.2.3 (diminishing returns)

A function  $f : 2^V \rightarrow \mathbb{R}$  is **submodular** if for any  $A \subseteq B \subset V$ , and  $v \in V \setminus B$ , we have that:

$$f(A \cup \{v\}) - f(A) \geq f(B \cup \{v\}) - f(B) \quad (3.3)$$

This means that the incremental “value”, “gain”, or “cost” of  $v$  decreases (diminishes) as the context in which  $v$  is considered grows from  $A$  to  $B$ .

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- We began to see that there were many functions that were submodular, and operations on sets of submodular functions that preserved submodularity.

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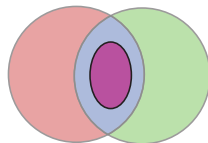
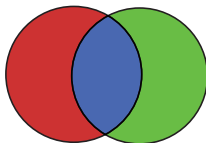
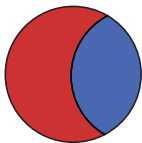
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- Information and Summarization - document summarization via sentence selection



# The Venn and Art of Submodularity

$$\underbrace{r(A) + r(B)}_{= r(A_r) + 2r(C) + r(B_r)} \geq \underbrace{r(A \cup B)}_{= r(A_r) + r(C) + r(B_r)} + \underbrace{r(A \cap B)}_{= r(A \cap B)}$$



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- Then, defining  $f : 2^S \rightarrow \mathbb{R}_+$  as follows,

$$f(X) = r(\cup_{s \in S} X_s) \quad (3.1)$$

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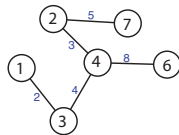
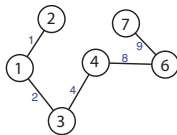
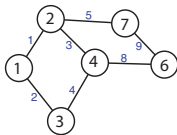
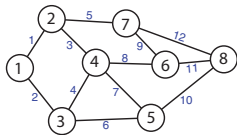
- In general (as we will see) **polymatroid rank functions** are submodular, normalized  $f(\emptyset) = 0$ , and monotone non-decreasing ( $f(A) \leq f(B)$  whenever  $A \subseteq B$ ).

# Spanning trees

- Let  $E$  be a set of edges of some graph  $G = (V, E)$ , and let  $r(S)$  for  $S \subseteq E$  be the maximum size (in terms of number of edges) spanning forest in the vertex-induced graph, induced by vertices incident to edges  $S$ .

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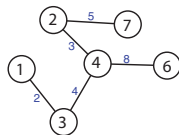
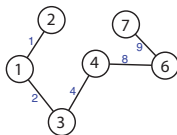
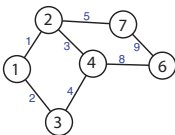
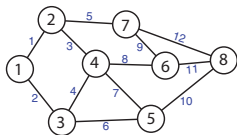
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- Example: Given  $G = (V, E)$ ,  $V = \{1, 2, 3, 4, 5, 6, 7, 8\}$ ,  $E = \{1, 2, \dots, 12\}$ .  $S = \{1, 2, 3, 4, 5, 8, 9\} \subset E$ . Two spanning trees have the same edge count (the rank of  $S$ ).





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- Then  $r(S)$  is submodular, and is another matrix rank function corresponding to the incidence matrix of the graph.

# Supply Side Economies of scale

- What is a good model of the **cost** of manufacturing a set of items?
- Let  $V$  be a set of possible items that a company might possibly wish to manufacture, and let  $f(S)$  for  $S \subseteq V$  be the cost to that company to manufacture subset  $S$ .
- Ex:  $V$  might be colors of paint in a paint manufacturer: green, red, blue, yellow, white, etc.
- Producing green when you are already producing yellow and blue is probably cheaper than if you were only producing some other colors.

$$f(\text{green}, \text{blue}, \text{yellow}) - f(\text{blue}, \text{yellow}) \leq f(\text{green}, \text{blue}) - f(\text{blue}) \quad (3.1)$$

- So diminishing returns (a submodular function) would be a good model.

# A model of Influence in Social Networks

- Given a graph  $G = (V, E)$ , each  $v \in V$  corresponds to a person, to each  $v$  we have an activation function  $f_v : 2^V \rightarrow [0, 1]$  dependent only on its neighbors. I.e.,  $f_v(A) = f_v(A \cap \Gamma(v))$ .
- Goal - Viral Marketing: find a small subset  $S \subseteq V$  of individuals to directly influence, and thus indirectly influence the greatest number of possible other individuals (via the social network  $G$ ).
- We define a function  $f : 2^V \rightarrow \mathbb{Z}^+$  that models the ultimate influence of an initial set  $S$  of nodes based on the following iterative process: At each step, a given set of nodes  $S$  are activated, and we activate new nodes  $v \in V \setminus S$  if  $f_v(S) \geq U[0, 1]$  (where  $U[0, 1]$  is a uniform random number between 0 and 1).
- It can be shown that for many  $f_v$  (including simple linear functions, and where  $f_v$  is submodular itself) that  $f$  is submodular.

# The value of a friend

- Let  $V$  be a group of individuals. How valuable to you is a given friend  $v \in V$ ?
- It depends on how many friends you have.
- Given a group of friends  $S \subseteq V$ , can you value them with a function  $f(S)$  and how?
- Let  $f(S)$  be the value of the set of friends  $S$ . Is submodular or supermodular a good model?

# Information and Summarization

- Let  $V$  be a set of information containing elements ( $V$  might say be either words, sentences, documents, web pages, or blogs, each  $v \in V$  is one element, so  $v$  might be a word, a sentence, a document, etc.). The total amount of information in  $V$  is measure by a function  $f(V)$ , and any given subset  $S \subseteq V$  measures the amount of information in  $S$ , given by  $f(S)$ .
- How informative is any given item  $v$  in different sized contexts? Any such real-world information function would exhibit diminishing returns, i.e., the value of  $v$  decreases when it is considered in a larger context.
- So a submodular function would likely be a good model.

# Submodular Polyhedra

- Submodular functions have associated polyhedra with nice properties: when a set of constraints in a linear program is a submodular polyhedron, a simple greedy algorithm can find the optimal solution even though the polyhedron is formed via an exponential number of constraints.

$$P_f = \{x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E\} \quad (3.2)$$

$$P_f^+ = P_f \cap \{x \in \mathbb{R}^E : x \geq 0\} \quad (3.3)$$

$$B_f = P_f \cap \{x \in \mathbb{R}^E : x(E) = f(E)\} \quad (3.4)$$

- The linear programming problem is to, given  $c \in \mathbb{R}^E$ , compute:

$$\tilde{f}(c) \triangleq \max \{c^T x : x \in P_f\} \quad (3.5)$$

- This can be solved using the greedy algorithm! Moreover,  $\tilde{f}(c)$  computed using greedy is convex if and only if  $f$  is submodular (we will go into this in some detail this quarter).

# Ground set: $E$ or $V$ ?

Submodular functions are functions defined on subsets of some finite set, called the **ground set**.

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- We will follow this inconsistency in the literature and will inconsistently use either  $E$  or  $V$  as our ground set (hopefully not in the same equation, if so, please point this out).



# Notation $\mathbb{R}^E$

What does  $x \in \mathbb{R}^E$  mean?

$$\mathbb{R}^E = \{x = (x_j \in \mathbb{R} : j \in E)\} \quad (3.6)$$

$$\mathbb{R}_+^E = \{x = (x_j : j \in E) : x \geq 0\} \quad (3.7)$$

Any vector  $x \in \mathbb{R}^E$  can be treated as a normalized modular function, and vice verse. That is

$$x(A) = \sum_{a \in A} x_a \quad (3.8)$$

Note that  $x$  is said to be **normalized** since  $x(\emptyset) = 0$ .

# characteristic vectors of sets & modular functions

- Given an  $A \subseteq E$ , define the vector  $\mathbf{1}_A \in \mathbb{R}_+^E$  to be

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- Thus, given modular function  $x \in \mathbb{R}^E$ , we can write  $x(A)$  in a variety of ways, i.e.,

$$x(A) = x \cdot \mathbf{1}_A = \sum_{i \in A} x(i) \quad (3.10)$$

## Other Notation: singletons and sets

When  $A$  is a set and  $k$  is a singleton (i.e., a single item), the union is properly written as  $A \cup \{k\}$ , but sometimes I will write just  $A + k$ .

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- Hence, given a finite set  $E$ ,  $\mathbb{R}^E$  is the set of all functions that map from elements of  $E$  to the reals  $\mathbb{R}$ , and such functions are identical to a vector in a vector space with axes labeled as elements of  $E$  (i.e., if  $m \in \mathbb{R}^E$ , then for all  $e \in E$ ,  $m(e) \in \mathbb{R}$ ).



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- Similarly,  $2^E$  is the set of all functions from  $E$  to “two” — in this case, we really mean  $2 \equiv \{0, 1\}$ , so  $2^E$  is shorthand for  $\{0, 1\}^E$ .

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# Summing Submodular Functions

Given  $E$ , let  $f_1, f_2 : 2^E \rightarrow \mathbb{R}$  be two submodular functions. Then

$$f : 2^E \rightarrow \mathbb{R} \text{ with } f(A) = f_1(A) + f_2(A) \quad (3.11)$$

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is submodular. This follows easily since

$$f(A) + f(B) = f_1(A) + f_2(A) + f_1(B) + f_2(B) \quad (3.12)$$

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$$= f(A \cup B) + f(A \cap B). \quad (3.14)$$

I.e., it holds for each component of  $f$  in each term in the inequality.

# Summing Submodular Functions

Given  $E$ , let  $f_1, f_2 : 2^E \rightarrow \mathbb{R}$  be two submodular functions. Then

$$f : 2^E \rightarrow \mathbb{R} \text{ with } f(A) = f_1(A) + f_2(A) \quad (3.11)$$

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$$= f(A \cup B) + f(A \cap B). \quad (3.14)$$

I.e., it holds for each component of  $f$  in each term in the inequality. In fact, any **conic combination** (i.e., non-negative linear combination) of submodular functions is submodular, as in  $f(A) = \alpha_1 f_1(A) + \alpha_2 f_2(A)$  for  $\alpha_1, \alpha_2 \geq 0$ .

# Summing Submodular and Modular Functions

Given  $E$ , let  $f_1, m : 2^E \rightarrow \mathbb{R}$  be a submodular and a modular function.

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That is, the modular component with

$m(A) + m(B) = m(A \cup B) + m(A \cap B)$  never destroys the inequality.

Note of course that if  $m$  is modular then so is  $-m$ .

# Restricting Submodular Functions

Given  $E$ , let  $f : 2^E \rightarrow \mathbb{R}$  be a submodular functions. And let  $S \subseteq E$  be an arbitrary fixed set. Then

$$f' : 2^E \rightarrow \mathbb{R} \text{ with } f'(A) = f(A \cap S) \quad (3.19)$$

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Proof.

Given  $A \subseteq B \subseteq E \setminus v$ , consider

$$f((A + v) \cap S) - f(A \cap S) \geq f((B + v) \cap S) - f(B \cap S) \quad (3.20)$$



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$$f((A + v) \cap S) - f(A \cap S) \geq f((B + v) \cap S) - f(B \cap S) \quad (3.20)$$

If  $v \notin S$ , then both differences on each side are zero. If  $v \in S$ , then we can consider this

$$f(A' + v) - f(A') \geq f(B' + v) - f(B') \quad (3.21)$$

with  $A' = A \cap S$  and  $B' = B \cap S$ . Since  $A' \subseteq B'$ , this holds due to submodularity of  $f$ . □

# Summing Restricted Submodular Functions

Given  $V$ , let  $f_1, f_2 : 2^V \rightarrow \mathbb{R}$  be two submodular functions and let  $S_1, S_2$  be two arbitrary fixed sets. Then

$$f : 2^V \rightarrow \mathbb{R} \text{ with } f(A) = f_1(A \cap S_1) + f_2(A \cap S_2) \quad (3.22)$$

is submodular. This follows easily from the preceding two results.



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Given  $V$ , let  $\mathcal{C} = \{C_1, C_2, \dots, C_k\}$  be a set of subsets of  $V$ , and for each  $C \in \mathcal{C}$ , let  $f_C : 2^V \rightarrow \mathbb{R}$  be a submodular function. Then

$$f : 2^V \rightarrow \mathbb{R} \text{ with } f(A) = \sum_{C \in \mathcal{C}} f_C(A \cap C) \quad (3.23)$$

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$$f : 2^V \rightarrow \mathbb{R} \text{ with } f(A) = \sum_{C \in \mathcal{C}} f_C(A \cap C) \quad (3.23)$$

is submodular. This property is critical for image processing and graphical models. For example, let  $\mathcal{C}$  be all pairs of the form  $\{\{u, v\} : u, v \in V\}$ , or let it be all pairs corresponding to the edges of some undirected graphical model. We plan to revisit this topic later in the term.

# Max - normalized

Given  $V$ , let  $c \in \mathbb{R}_+^V$  be a given fixed vector. Then  $f : 2^V \rightarrow \mathbb{R}_+$ , where

$$f(A) = \max_{j \in A} c_j \quad (3.24)$$

is submodular and normalized (we take  $f(\emptyset) = 0$ ).

## Proof.

Consider

$$\max_{j \in A} c_j + \max_{j \in B} c_j \geq \max_{j \in A \cup B} c_j + \max_{j \in A \cap B} c_j \quad (3.25)$$

which follows since we have that

$$\max(\max_{j \in A} c_j, \max_{j \in B} c_j) = \max_{j \in A \cup B} c_j \quad (3.26)$$

and

$$\min(\max_{j \in A} c_j, \max_{j \in B} c_j) \geq \max_{j \in A \cap B} c_j \quad (3.27)$$



# Max

Given  $V$ , let  $c \in \mathbb{R}^V$  be a given fixed vector (not necessarily non-negative). Then  $f : 2^V \rightarrow \mathbb{R}$ , where

$$f(A) = \max_{j \in A} c_j \quad (3.28)$$

is submodular, where we take  $f(\emptyset) \leq \min_j c_j$  (so the function is not normalized).

Proof.

The proof is identical to the normalized case. □

# Facility/Plant Location (uncapacitated)

- Let  $F = \{1, \dots, f\}$  be a set of possible factory/plant locations for facilities to be built.
- $S = \{1, \dots, s\}$  is a set of sites (e.g., cities, clients) needing service.
- Let  $c_{ij}$  be the “benefit” (e.g.,  $1/c_{ij}$  is the cost) of servicing site  $i$  with facility location  $j$ .
- Let  $m_j$  be the benefit (e.g., either  $1/m_j$  is the cost or  $-m_j$  is the cost) to build a plant at location  $j$ .
- Each site should be serviced by only one plant but no less than one.
- Define  $f(A)$  as the “delivery benefit” plus “construction benefit” when the locations  $A \subseteq F$  are to be constructed.
- We can define the (uncapacitated) facility location function

$$f(A) = \sum_{j \in A} m_j + \sum_{i \in F} \max_{j \in A} c_{ij}. \quad (3.4)$$

- Goal is to find a set  $A$  that maximizes  $f(A)$  (the benefit) placing a bound on the number of plants  $A$  (e.g.,  $|A| \leq k$ ).

# Facility Location

Given  $V, E$ , let  $c \in \mathbb{R}^{V \times E}$  be a given  $|V| \times |E|$  matrix. Then

$$f : 2^E \rightarrow \mathbb{R}, \text{ where } f(A) = \sum_{i \in V} \max_{j \in A} c_{ij} \quad (3.29)$$

is submodular.

## Proof.

We can write  $f(A)$  as  $f(A) = \sum_{i \in V} f_i(A)$  where  $f_i(A) = \max_{j \in A} c_{ij}$  is submodular (max of a  $i^{\text{th}}$  row vector), so  $f$  can be written as a sum of submodular functions. □

Thus, the facility location function (which only adds a modular function to the above) is submodular.

# Log Determinant

- Let  $\Sigma$  be an  $n \times n$  positive definite matrix. Let  $V = \{1, 2, \dots, n\} \equiv [n]$  be an index set, and for  $A \subseteq V$ , let  $\Sigma_A$  be the (square) submatrix of  $\Sigma$  obtained by including only entries in the rows/columns given by  $A$ .

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- We have that:

$$f(A) = \log \det(\Sigma_A) \text{ is submodular.} \quad (3.30)$$



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- The submodularity of the log determinant is crucial for determinantal point processes (DPPs) (defined later in the class).

## Proof of submodularity of the logdet function.

Suppose  $X \in \mathbf{R}^n$  is multivariate Gaussian random variable, that is

$$p(x) = \frac{1}{\sqrt{|2\pi\Sigma|}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right) \quad (3.31)$$

...

# Log Determinant

...cont.

Then the (differential) entropy of the r.v.  $X$  is given by

$$h(X) = \log \sqrt{|2\pi e \Sigma|} = \log \sqrt{(2\pi e)^n |\Sigma|} \quad (3.32)$$

and in particular, for a variable subset  $A$ ,

$$f(A) = h(X_A) = \log \sqrt{(2\pi e)^{|A|} |\Sigma_A|} \quad (3.33)$$

Entropy is submodular (conditioning reduces entropy), and moreover

$$f(A) = h(X_A) = m(A) + \frac{1}{2} \log |\Sigma_A| \quad (3.34)$$

where  $m(A)$  is a modular function. □

Note: still submodular in the semi-definite case as well.

# Summary so far

- Summing: if  $\alpha_i \geq 0$  and  $f_i : 2^V \rightarrow \mathbb{R}$  is submodular, then so is  $\sum_i \alpha_i f_i$ .

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- Restrictions:  $f'(A) = f(A \cap S)$
- max:  $f(A) = \max_{j \in A} c_j$  and facility location.
- Log determinant  $f(A) = \log \det(\Sigma_A)$

# Concave over non-negative modular

Let  $m \in \mathbb{R}_+^E$  be a modular function, and  $g$  a concave function over  $\mathbb{R}$ . Define  $f : 2^E \rightarrow \mathbb{R}$  as

$$f(A) = g(m(A)) \quad (3.35)$$

then  $f$  is submodular.

## Proof.

Given  $A \subseteq B \subseteq E \setminus v$ , we have  $0 \leq a = m(A) \leq b = m(B)$ , and  $0 \leq c = m(v)$ . For  $g$  concave, we have  $g(a + c) - g(a) \geq g(b + c) - g(b)$ , and thus

$$g(m(A) + m(v)) - g(m(A)) \geq g(m(B) + m(v)) - g(m(B)) \quad (3.36)$$



A form of converse is true as well.



# Concave composed with non-negative modular

## Theorem 3.5.1

*Given a ground set  $V$ . The following two are equivalent:*

- ① *For all modular functions  $m : 2^V \rightarrow \mathbb{R}_+$ , then  $f : 2^V \rightarrow \mathbb{R}$  defined as  $f(A) = g(m(A))$  is submodular*
  - ②  *$g : \mathbb{R}_+ \rightarrow \mathbb{R}$  is concave.*
- If  $g$  is non-decreasing concave, then  $f$  is polymatroidal.

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- If  $g$  is non-decreasing concave, then  $f$  is polymatroidal.
- Sums of concave over modular functions are submodular

$$f(A) = \sum_{i=1}^K g_i(m_i(A)) \quad (3.37)$$

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- Very large class of functions, including graph cut, bipartite neighborhoods, set cover (Stobbe & Krause).
- However, Vondrak showed that a graphic matroid rank function over  $K_4$  (we'll define this after we define matroids) are not members.

# Monotonicity

## Definition 3.6.1

A function  $f : 2^V \rightarrow \mathbb{R}$  is **monotone nondecreasing** (resp. **monotone increasing**) if for all  $A \subset B$ , we have  $f(A) \leq f(B)$  (resp.  $f(A) < f(B)$ ).

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## Definition 3.6.2

A function  $f : 2^V \rightarrow \mathbb{R}$  is **monotone nonincreasing** (resp. **monotone decreasing**) if for all  $A \subset B$ , we have  $f(A) \geq f(B)$  (resp.  $f(A) > f(B)$ ).

# Composition of non-decreasing submodular and non-decreasing concave

## Theorem 3.6.3

*Given two functions, one defined on sets*

$$f : 2^V \rightarrow \mathbb{R} \quad (3.38)$$

*and another continuous valued one:*

$$g : \mathbb{R} \rightarrow \mathbb{R} \quad (3.39)$$

*the composition formed as  $h = g \circ f : 2^V \rightarrow \mathbb{R}$  (defined as  $h(S) = g(f(S))$ ) is nondecreasing submodular, if  $g$  is non-decreasing concave and  $f$  is nondecreasing submodular.*

# Monotone difference of two functions

Let  $f$  and  $g$  both be submodular functions on subsets of  $V$  and let  $(f - g)(\cdot)$  be either monotone increasing or monotone decreasing. Then  $h : 2^V \rightarrow R$  defined by

$$h(A) = \min(f(A), g(A)) \quad (3.40)$$

is submodular.

Proof.

If  $h(A)$  agrees with either  $f$  or  $g$  on **both**  $X$  and  $Y$ , and since

$$f(X) + f(Y) \geq f(X \cup Y) + f(X \cap Y) \quad (3.41)$$

$$g(X) + g(Y) \geq g(X \cup Y) + g(X \cap Y), \quad (3.42)$$

the result (Equation 3.40) follows since

$$\begin{aligned} f(X) + f(Y) &\geq \min(f(X \cup Y), g(X \cup Y)) + \min(f(X \cap Y), g(X \cap Y)) \\ g(X) + g(Y) &\geq \min(f(X \cup Y), g(X \cup Y)) + \min(f(X \cap Y), g(X \cap Y)) \end{aligned} \quad (3.43)$$



# Monotone difference of two functions

...cont.

Otherwise, w.l.o.g.,  $h(X) = f(X)$  and  $h(Y) = g(Y)$ , giving

$$h(X) + h(Y) = f(X) + g(Y) \geq f(X \cup Y) + f(X \cap Y) + g(Y) - f(Y) \quad (3.44)$$

# Monotone difference of two functions

...cont.

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$$h(X) + h(Y) = f(X) + g(Y) \geq f(X \cup Y) + f(X \cap Y) + g(Y) - f(Y) \quad (3.44)$$

Assume the case where  $f - g$  is monotone increasing. Hence,  $f(X \cup Y) + g(Y) - f(Y) \geq g(X \cup Y)$  giving

$$h(X) + h(Y) \geq g(X \cup Y) + f(X \cap Y) \geq h(X \cup Y) + h(X \cap Y) \quad (3.45)$$



What is an easy way to prove the case where  $f - g$  is monotone decreasing?

# Saturation via the $\min(\cdot)$ function

Let  $f : 2^V \rightarrow \mathbb{R}$  be an monotone increasing or decreasing submodular function and let  $k$  be a constant. Then the function  $h : 2^V \rightarrow \mathbb{R}$  defined by

$$h(A) = \min(k, f(A)) \quad (3.46)$$

is submodular.

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For constant  $k$ , we have that  $(f - k)$  is increasing (or decreasing) so this follows from the previous result.  $\square$

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Proof.

For constant  $k$ , we have that  $(f - k)$  is increasing (or decreasing) so this follows from the previous result.  $\square$

Note also,  $g(a) = \min(k, a)$  for constant  $k$  is a non-decreasing concave function, so when  $f$  is monotone nondecreasing submodular, we can use the earlier result about composing a monotone concave function with a monotone submodular function to get a version of this.

# More on Min - the saturate trick

- In general, the minimum of two submodular functions is not submodular (unlike concave functions).

# More on Min - the saturate trick

- In general, the minimum of two submodular functions is not submodular (unlike concave functions).
- However, when wishing to maximize two monotone non-decreasing submodular functions, we can define function  $h : 2^V \rightarrow \mathbb{R}$  as

$$h(A) = \frac{1}{2}(\min(k, f) + \min(k, g)) \quad (3.47)$$

then  $h$  is submodular, and  $h(A) \geq k$  if and only if both  $f(A) \geq k$  and  $g(A) \geq k$ .

# More on Min - the saturate trick

- In general, the minimum of two submodular functions is not submodular (unlike concave functions).
- However, when wishing to maximize two monotone non-decreasing submodular functions, we can define function  $h : 2^V \rightarrow \mathbb{R}$  as

$$h(A) = \frac{1}{2}(\min(k, f) + \min(k, g)) \quad (3.47)$$

then  $h$  is submodular, and  $h(A) \geq k$  if and only if both  $f(A) \geq k$  and  $g(A) \geq k$ .

- This can be useful in many applications. Moreover, this is an instance of a **submodular surrogate** (where we take a non-submodular problem and find a submodular one that can tell us something). We hope to revisit this again later in the quarter.



# Arbitrary functions as difference between submodular funcs.

Given an arbitrary set function  $f$ , it can be expressed as a difference between two submodular functions:  $f = g - h$  where both  $g$  and  $h$  are submodular.

## Proof.

Let  $f$  be given and arbitrary, and define:

$$\alpha \triangleq \min_{X,Y} \left( f(X) + f(Y) - f(X \cup Y) - f(X \cap Y) \right) \quad (3.48)$$

If  $\alpha \geq 0$  then  $f$  is submodular, so by assumption  $\alpha < 0$ .

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If  $\alpha \geq 0$  then  $f$  is submodular, so by assumption  $\alpha < 0$ . Now let  $h$  be an arbitrary strict submodular function and define

$$\beta \triangleq \min_{X,Y} \left( h(X) + h(Y) - h(X \cup Y) - h(X \cap Y) \right). \quad (3.49)$$

Strict means that  $\beta > 0$ .

...

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...cont.

Define  $f' : 2^V \rightarrow \mathbb{R}$  as

$$f'(A) = f(A) + \frac{|\alpha|}{\beta} h(A) \quad (3.50)$$

Then  $f'$  is submodular (why?), and  $f = f'(A) - \frac{|\alpha|}{\beta} h(A)$ , a difference between two submodular functions as desired.



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$$f(A \cup \{j\}) - f(A) \triangleq \rho_j(A) \quad (3.51)$$

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- We'll use  $f(j|A)$ .
- Submodularity's **diminishing returns** definition can be stated as saying that  $f(j|A)$  is a monotone non-increasing function of  $A$ , since  $f(j|A) \geq f(j|B)$  whenever  $A \subseteq B$  (conditioning reduces valuation).

# Gain Notation

It will also be useful to extend this to sets.

Let  $A, B$  be any two sets. Then

$$f(A|B) \triangleq f(A \cup B) - f(B) \quad (3.56)$$

So when  $j$  is any singleton

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Note that this is inspired from information theory and the notation used for conditional entropy  $H(X_A|X_B) = H(X_A, X_B) - H(X_B)$ .

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- But both  $\bar{g} + m_{g-h}^+$  and  $\bar{h} + (-m_{g-h})^+$  are polymatroid functions.
- Thus, any function can be expressed as a difference between two polymatroid functions.

# Applications

- **Sensor placement with submodular costs.** I.e., let  $V$  be a set of possible sensor locations,  $f(A) = I(X_A; X_{V \setminus A})$  measures the quality of a subset  $A$  of placed sensors, and  $c(A)$  the submodular cost. We have  $f(A) - \lambda c(A)$  as the overall objective.

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- **Graphical Model Inference.** Finding  $x$  that maximizes  $p(x) \propto \exp(-v(x))$  where  $x \in \{0, 1\}^n$  and  $v$  is a pseudo-Boolean function. When  $v$  is non-submodular, it can be represented as a difference between submodular functions.