Submodular Functions, Optimization, and Applications to Machine Learning

— Spring Quarter, Lecture 15 —

http://j.ee.washington.edu/~bilmes/clases/ee596b_spring_2014/

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 $f(A) + f(B) \ge f(A \cup B) + f(A \cap B)$ = $f(A) + 2f(C) + f(B) - f(A) + f(C) + f(B) - f(A \cap B)$









Cumulative Outstanding Reading

- Good references for today: Schrijver-2003, Oxley-1992/2011,
 Welsh-1973, Goemans-2010, Cunningham-1984, Edmonds-1969.
- Read Tom McCormick's overview paper on SFM http://people.commerce.ubc.ca/faculty/mccormick/sfmchap8a.pdf
- Read chapters 1 4 from Fujishige book.
- Matroid properties http: //www-math.mit.edu/~goemans/18433S09/matroid-notes.pdf
- Read lecture 14 slides on lattice theory at our web page (http://j.ee.washington.edu/~bilmes/classes/ee596b_spring_2014/)

Announcements, Assignments, and Reminders

 Weekly Office Hours: Wednesdays, 5:00-5:50, or by skype or google hangout (email me).

Class Road Map - IT-I

- L1 (3/31): Motivation, Applications, & Basic Definitions
- L2: (4/2): Applications, Basic Definitions, Properties
- L3: More examples and properties (e.g., closure properties), and examples, spanning trees
- L4: proofs of equivalent definitions, independence, start matroids
- L5: matroids, basic definitions and examples
- L6: More on matroids, System of Distinct Reps, Transversals, Transversal Matroid, Matroid and representation
- L7: Dual Matroids, other matroid properties, Combinatorial Geometries
- L8: Combinatorial Geometries, matroids and greedy, Polyhedra, Matroid Polytopes,
- L9: From Matroid Polytopes to Polymatroids.
- L10: Polymatroids and Submodularity

- L11: More properties of polymatroids, SFM special cases
- L12: polymatroid properties, extreme points polymatroids.
- L13: sat, dep, supp, exchange capacity, examples
- L14: Lattice theory: partially ordered sets; lattices; distributive, modular, submodular, and boolean lattices; ideals and join irreducibles.
- L15: Supp, Base polytope, exchange capacity, minimum norm point algorithm and the lattice of minimizers of a submodular function, Lovasz extension
- L16:
 I 17:
- LII.
- L18:
- L19:
- L20:

Summary of Concepts

- Most violated inequality $\max \{x(A) f(A) : A \subseteq E\}$
- Matroid by circuits, and the fundamental circuit $C(I,e) \subseteq I+e$.
- Minimizers of submodular functions form a lattice.
- Minimal and maximal element of a lattice.
- x-tight sets, maximal and minimal tight set.
- sat function & Closure
- Saturation Capacity
- e-containing tight sets
- dep function & fundamental circuit of a matroid

Summary important definitions so far: tight, dep, & sat

- x-tight sets: For $x \in P_f$, $\mathcal{D}(x) = \{A \subseteq E : x(A) = f(A)\}$.
- Polymetroid closure/maximal x-tight set: For $x \in P_f$, $\operatorname{sat}(x) = \bigcup \{A : A \in \mathcal{D}(x)\} = \{e : e \in E, \forall \alpha > 0, x + \alpha \mathbf{1}_e \notin P_f\}.$
- Saturation capacity: for $x \in P_f$, $0 \le c(x; e) = \min\{f(A) x(A) | \forall A \ni e\} = \max\{\alpha : \alpha \in \mathbb{R}, x + \alpha \mathbf{1}_e \in P_f\}$
- Recall: $sat(x) = \{e : \hat{c}(x; e) = 0\}$ and $E \setminus sat(x) = \{e : \hat{c}(x; e) > 0\}.$
- e-containing x-tight sets: For $x \in P_f$, $\mathcal{D}(x,e) = \{A : e \in A \subseteq E, x(A) = f(A)\} \subseteq \mathcal{D}(x).$
- Minimal e-containing x tight set/polymatroidal fundamental circuit/: For $x \in P_f$, $\operatorname{dep}(x,e) = \begin{cases} \bigcap \{A: e \in A \subseteq E, x(A) = f(A)\} & \text{if } e \in \operatorname{sat}(x) \\ \emptyset & \text{else} \end{cases}$

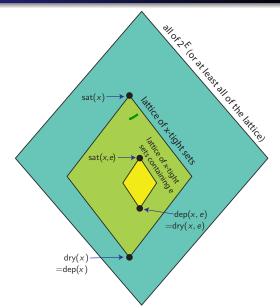
 $= \{e' : \exists \alpha > 0, \text{ s.t. } x + \alpha (\mathbf{1}_e - \mathbf{1}_{e'}) \in P_f \}$

dep and sat in a lattice

Given some $x \in P_f$,

The picture on the right summarizes the relationships between the lattices and sublattices.

• Note, $\bigcap_{e} \operatorname{dep}(x, e) = \operatorname{dep}(x).$



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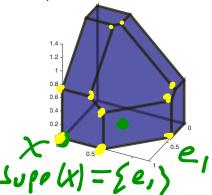
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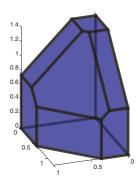
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Example





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 - 2 Now, for $1 \le i \le k$, if $e_i \notin \operatorname{supp}(x)$, $x(E_k) = x(E_k e_i)$
 - \blacksquare Also, for $1 \le i \le k$, if $e_i \notin \text{supp}(x)$, then $x(e_i)$ $0 = f(e_i|E_{i-1}) \ge f(e_i|E_k - e_i) + f(E_k|E_k - e_i) \ge 0 \text{ since }$ monotone submodular, hence we have $f(E_k) = f(E_k - e_i).$

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 - 4 Thus, $x(E_k e_i) = f(E_k e_i)$ and $E_k e_i$ is also tight.

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- Since supp(x) is tight, we immediately have that $sat(x) \supseteq supp(x)$.

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- For modular functions, they are always equal at extreme points (e.g., think of "hyperrectangular" polymatroids).



- For $x \in P_f$, supp $(x) = \{e : x(e) \neq 0\} \subseteq \operatorname{sat}(x)$
- For $x \in P_f$, $\operatorname{sat}(x)$ (span, closure) is the maximal saturated (x-tight) set w.r.t. x. I.e., $sat(x) = \{e : e \in E, \forall \alpha > 0, x + \alpha \mathbf{1}_e \notin P_f\}$. That is,

$$\operatorname{cl}(x) \stackrel{\text{def}}{=} \operatorname{sat}(x) \triangleq \bigcup \{A : A \in \mathcal{D}(x)\}$$
 (15.29)

$$= \bigcup \{A : A \subseteq E, x(A) = f(A)\}$$
 (15.30)

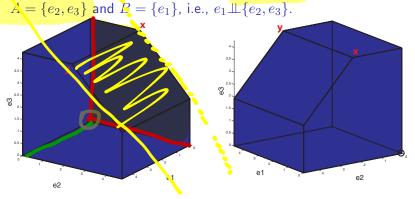
$$= \{e : e \in E, \forall \alpha > 0, x + \alpha \mathbf{1}_e \notin P_f\}$$
 (15.31)

• For $e \in \operatorname{sat}(x)$, we have $\operatorname{dep}(x,e) \subseteq \operatorname{sat}(x)$ (fundamental circuit) is the minimal (common) saturated (x-tight) set w.r.t. x containing e. l.e.,

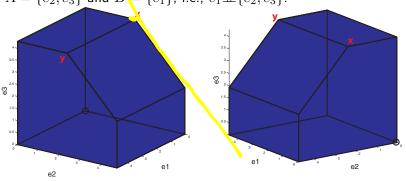
$$dep(x,e) = \begin{cases} \bigcap \{A : e \in A \subseteq E, x(A) = f(A)\} & \text{if } e \in sat(x) \\ \emptyset & \text{else} \end{cases}$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } x + \alpha(\mathbf{1}_e - \mathbf{1}_{e'}) \in P_f\}$$
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• Example polymatroid where there is perfect independence between

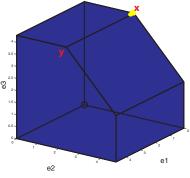


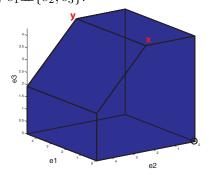
• Example polymatroid where there is perfect independence between $A = \{e_2, e_3\}$ and $B = \{e_1\}$, i.e., $e_1 \perp \!\!\! \perp \{e_2, e_3\}$.



• Point x is extreme and $x(\{e_2, e_3\}) = f(e_2, e_3)$ (why?).

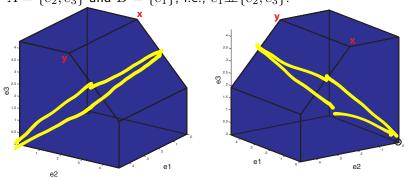
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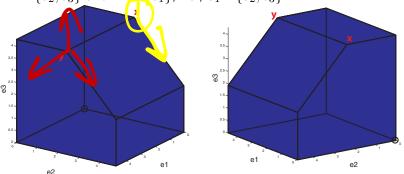
- Point x is extreme and $x(\lbrace e_2,e_3\rbrace)=f(e_2,e_3)$ (why?).
- But $x(\{e_1, e_2, e_3\}) = x(\{e_2, e_3\}) < f(e_1, e_2, e_3) = f(e_1) + f(e_2, e_3)$. Thus, $supp(x) = sat(x) = \{e_2, e_3\}.$

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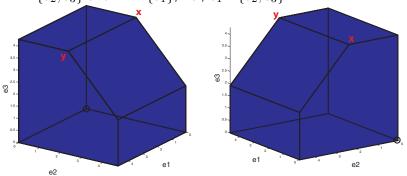
 Note that considering a submodular function on clustered ground set $E = \{e_1, e_{23}\}$ where $f'(e_1) = f(e_1)$, $f'(e_{23}) = f(e_2, e_3)$ leads to a rectangle (no dependence between $\{e1\}$ and $\{e2, e3\}$).

• Example polymatroid where there is perfect independence between $A = \{e_2, e_3\}$ and $B = \{e_1\}$, i.e., $e_1 \perp \!\!\! \perp \{e_2, e_3\}$.



- We also have $sat(x) = \{e_3, e_2\}$. So $dep(x, e_1)$ is not defined, $dep(x, e_2) = \{e_3\}$, and $dep(x, e_3) = \emptyset$.
- $sat(y) = \{e_1, e_2, e_3\}$. So $dep(y, e_1) = \emptyset$, $dep(y, e_2) = e_3$, and $dep(y, e_3) = \emptyset$.

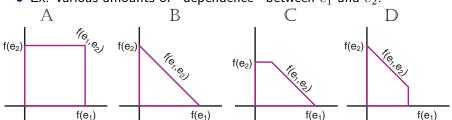
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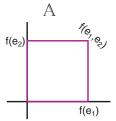
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supp, sat, and polymatroid dependence in 2D

ullet Ex: various amounts of "dependence" between e_1 and e_2 .

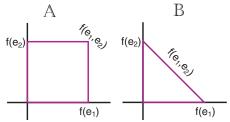


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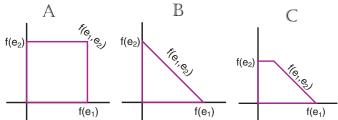
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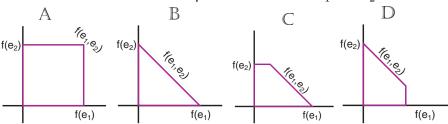
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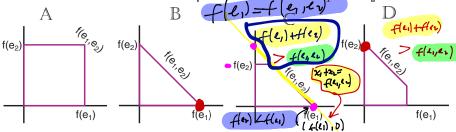
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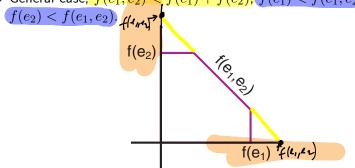
• Ex: various amounts of "dependence" between e_1 and e_2 .



- In each case, we see points x where $supp(x) \subseteq sat(x)$.
- Example: Case B or C, let $x = (f(e_1), 0)$ so $supp(x) = \{e_1\}$ but since $x(\{e_1, e_2\}) = x(\{e_1\}) = f(e_1) = f(e_1, e_2)$ we have $sat(x) = \{e_1, e_2\}.$
- Similar for case D with $x = (0, f(e_2))$.

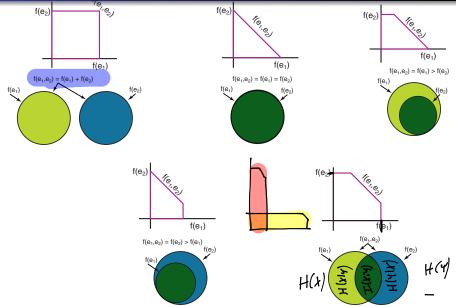
supp, sat, and dependence in 2D

• General case, $f(e_1, e_2) < f(e_1) + f(e_2)$, $f(e_1) < f(e_1, e_2)$, and



• Entropy case: We have a random variable Z and two separate deterministic functions $e_1 = h_1(Z)$ and $e_2 = h_2(Z)$ such that the entropy $H(e_1, e_2) = H(Z)$, but each deterministic function gives a different "view" of Z, each contains more than half the information, and the two are redundant w.r.t. each other $(H(e_1) + H(e_2) > H(Z))$.

2D polymatroids and Information Venn Diagrams

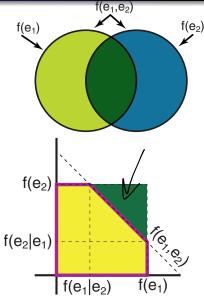


2D polymatroids and Information Venn Diagrams

 Consider symmeterized combinatorial mutual information function:

$$I_f(e_1, e_2)$$

= $f(e_1) + f(e_2) - f(e_1, e_2)$



2D polymatroids and Information Venn Diagrams

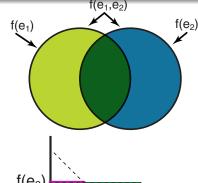
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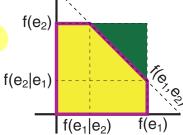
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= $f(e_1) + f(e_2) - f(e_1, e_2)$

• Consider area of green triangle:

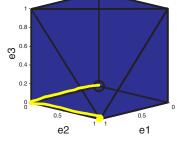
$$\frac{1}{2} \left(f(e_2) - f(e_2|e_1) \right) \left(f(e_1) - f(e_1|e_2) \right)
= \frac{1}{2} \left(f(e_1) + f(e_2) - f(e_1, e_2) \right)^2
= \frac{1}{2} \left(I_f(e_1, e_2) \right)^2$$

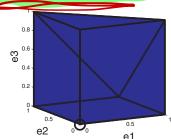




ullet Ex: polymatroid with perfect independence between e_2 and e_3 , so

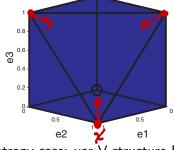
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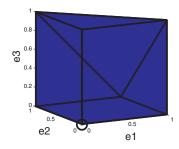




$$f(e_3|e_1,e_1) = D$$
 $f(e_1,e_1) = H(e_1,e_1,e_2)$

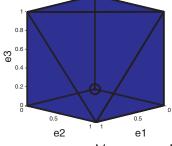
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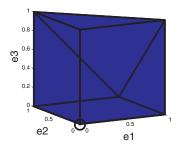




• Entropy case: xor V-structure Bayesian network $e_1 = h(e_2, e_3)$ where h is the xor function $(e_2 \rightarrow e_1 \leftarrow e_3)$, and e_2, e_3 are both independent binary with unity entropy.

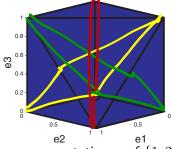
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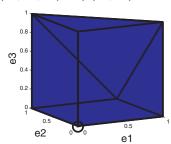




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- Q: Why does the polytope have a symmetry? Notice independence (square) for any pair.

• Ex: polymatroid with perfect independence between e_2 and e_3 , so $f(e_2,e_3)=f(e_2)+f(e_3)$, but perfect dependence between $A=\{e_2,e_3\}$ and $B=\{e_1\}$, so $f(e_1,e_2,e_3)=f(e_2,e_3)$



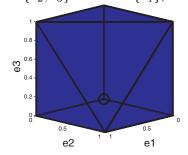


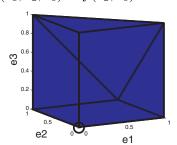
• For any permutation σ of $\{1,2,3\}$, considering $\{e_{\sigma_1},e_{\sigma_2}\}$ vs. $\{e_{\sigma_3}\}$:

 e_{σ_3} is a deterministic function of $\{e_{\sigma_1}, e_{\sigma_2}\}$

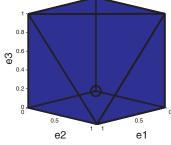


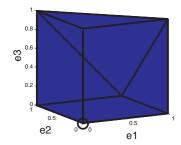
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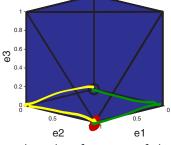
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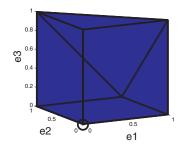




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- Note also, that for some of the extreme points, multiple orders generate them.
- Consider extreme point $x=(x_1,x_2,x_3)=(1,1,0)$. Then we get this either with orders (e_1,e_2,e_3) , or (e_2,e_1,e_3) . This is true since $f(e_{\sigma_e}|\{e_{\sigma_1},e_{\sigma_2}\})=0$ for all permutations σ of $\{1,2,3\}$.

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- Moreover, for any permutation σ of $\{1,2,3\}$, we have the relationship $X_{\sigma_1} = X_{\sigma_2} \oplus X_{\sigma_3}$.
- The entropy function $f(A) = H(X_A)$ is a submodular function that will have the symmetric 3D polytope of the previous example.

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- Note also, for any $A \subseteq \operatorname{sat}(x) \setminus \operatorname{supp}(x)$, we have $f(A|\operatorname{supp}(x)) = 0$

• Note that all of these results hold when f is monotone non-decreasing submodular (e.g., for a polymatroid function).

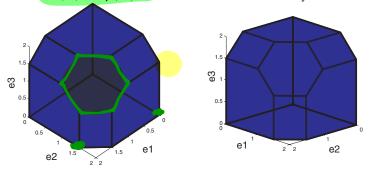
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- For general $x \in P_f$ (not nec. extremal), sat(x) and supp(x) might have an arbitrary relationship (but we want to strengthen this relationship further, and we will do so below).
- For the most part, we are interested in these quantities when x is extremal as we will see.

supp and sat, example under limited curvature

- Strict monotone f polymatroids, where $f(e|E \setminus e) > 0, \forall e$.
- Example: $f(A) = \sqrt{|A|}$, where all m! vertices of B_f are unique.



• In such cases, taking any extremal point $x \in P_f$ based on prefix order $E = (e_1, \ldots)$, where $\operatorname{supp}(x) \subset E$, we have that $\operatorname{sat}(x) = \operatorname{supp}(x)$ since the largest tight set corresponds to $x(E_i) = f(E_i)$ for some i, and while any $e \in E \setminus E_i$ is such that $x(E_i + e) = x(E_i)$, there is **no** such e with $f(E_i + e) = f(E_i)$.

Examples More on B_f Exchange Capacity Min-Norm Point and SFM Lovász extension

Another revealing theorem

Theorem 15.5.1

Let f be a polymatroid function and suppose that E can be partitioned into (E_1, E_2, \ldots, E_k) such that $f(A) = \sum_{i=1}^k f(A \cap E_i)$ for all $A \subseteq E$, and k is maximum. Then the base polytope

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• Thus, "independence" between disjoint A and B (leading to a rectangular projection of the polymatroid polytope) reduces the dimension of the base polytope, as expected.

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- Thus, "independence" between disjoint A and B (leading to a rectangular projection of the polymatroid polytope) reduces the dimension of the base polytope, as expected.
- Thus, any point $x \in B_f$ is a convex combination of at most |E| k + 1 vertices of B_f .

Theorem 15.5.1

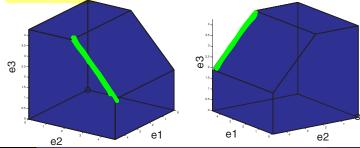
Let f be a polymatroid function and suppose that E can be partitioned into (E_1, E_2, \ldots, E_k) such that $f(A) = \sum_{i=1}^k f(A \cap E_i)$ for all $A \subseteq E$, and k is maximum. Then the base polytope $B_f = \{x \in P_f : x(E) = f(E)\}$ (the E-tight subset of P_f) has dimension |E| - k.

- Thus, "independence" between disjoint A and B (leading to a rectangular projection of the polymatroid polytope) reduces the dimension of the base polytope, as expected.
- Thus, any point $x \in B_f$ is a convex combination of at most |E| k + 1 vertices of B_f .
- And if f does not have such independence, dimension of B_f is |E|-1 and any point $x \in B_f$ is a convex combination of at most |E| vertices of B_f .

Theorem 15.5.1

Let f be a polymatroid function and suppose that E can be partitioned into (E_1, E_2, \ldots, E_k) such that $f(A) = \sum_{i=1}^k f(A \cap E_i)$ for all $A \subseteq E$, and k is maximum. Then the base polytope $B_f = \{x \in P_f : x(E) = f(E)\}$ (the E-tight subset of P_f) has dimension |E| - k.

• Example f with independence between $A = \{e_2, e_3\}$ and $B = \{e_1\}$, i.e., $e_1 \perp \{e_2, e_3\}$, with B_f marked in green.



• Given polymatroid function f, the base polytope

$$B_f = \left\{ x \in \mathbb{R}_+^E : x(A) \le f(A) \ \forall A \subseteq E, \text{ and } x(E) = f(E) \right\}$$
 always exists.

- Given polymatroid function f, the base polytope $B_f = \left\{ x \in \mathbb{R}_+^E : x(A) \leq f(A) \; \forall A \subseteq E, \text{ and } x(E) = f(E) \right\}$ always exists.
- Consider any order of E and generate a vector x by this order (i.e., $x(e_1) = f(\{e_1\}), x(e_2) = f(\{e_1, e_2\}) f(\{e_1\}), \text{ and so on}$).

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- From past lectures, we now know that:

- Given polymatroid function f, the base polytope $B_f = \left\{ x \in \mathbb{R}_+^E : x(A) \leq f(A) \; \forall A \subseteq E, \text{ and } x(E) = f(E) \right\}$ always exists.
- Consider any order of E and generate a vector x by this order (i.e., $x(e_1)=f(\{e_1\}),\ x(e_2)=f(\{e_1,e_2\})-f(\{e_1\}),\ \text{and so on}).$
- From past lectures, we now know that: (1) $x \in P_f$

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 - (1) $x \in P_f$
 - (2) x is an extreme point in P_f

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 - (2) x is an extreme point in P_f
 - (3) Since x is generated using an ordering of all of E, we have that x(E) = f(E).
- Thus $x \in B_f$, and B_f is never empty.
- Moreover, in this case, x is a vertex of B_f since it is extremal.

ullet Now, for any $A\subseteq E$, we can generate a particular point in B_f

$$\chi(A) = f(A)$$

$$\chi(A) = f(B) \forall B$$

- ullet Now, for any $A\subseteq E$, we can generate a particular point in B_f
- That is, choose the ordering of $E=(e_1,e_2,\ldots,e_n)$ where n=|E|, and where $E_i=(e_1,e_2,\ldots,e_i)$, so that we have $E_k=A$ with k=|A|.

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$$B_f \cap \left\{ x \in \mathbb{R}^E : x(A) = f(A) \right\} \neq \emptyset \tag{15.2}$$

• In words, B_f intersects all "multi-axis congruent" hyperplanes within R^E of the form $\{x \in \mathbb{R}^E : x(A) = f(A)\}$ for all $A \subseteq E$.

• In fact, every $x \in P_f$ is dominated by $x \le y \in B_f$.

Theorem 15.5.2

If $x \in P_f$ and T is tight for x (meaning x(T) = f(T)), then there exists $y \in B_f$ with $x \le y$ and y(e) = x(e) for $e \in T$.

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Proof.

• We construct the y algorithmically: initially set $y \leftarrow x$.

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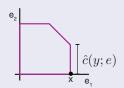
- We construct the y algorithmically: initially set $y \leftarrow x$.
- $y \in P_f$, T is tight for y so y(T) = f(T).
- Recall saturation capacity: for $y \in P_f$, $\hat{c}(y; e) = \min\{f(A) y(A) | \forall A \ni e\} = \max\{\alpha : \alpha \in \mathbb{R}, y + \alpha \mathbf{1}_e \in P_f\}$

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- Consider following algorithm:
- 1 $T' \leftarrow T$;
- 2 for $e \in E \setminus T$ do
- $\mathbf{3} \quad | \quad y \leftarrow y + c(y;e) \mathbf{1}_e \; ; \; T' \leftarrow T' \cup \{e\};$



... proof of Thm. 15.5.2 cont.

• Each step maintains feasibility: consider one step adding e to T' — for $e \notin T'$, feasibility requires $y(T'+e) = y(T') + y(e) \le f(T'+e)$, or y(e) < f(T'+e) - y(T')

... proof of Thm. 15.5.2 cont.

• Each step maintains feasibility: consider one step adding e to T' — for $e \notin T'$, feasibility requires $y(T'+e) = y(T') + y(e) \le f(T'+e)$, or $y(e) \le f(T'+e) - y(T') = y(e) + f(T'+e) - y(T'+e)$.

- Each step maintains feasibility: consider one step adding e to T' for $e \notin T'$, feasibility requires $y(T'+e) = y(T') + y(e) \le f(T'+e)$, or $y(e) \le f(T'+e) y(T') = y(e) + f(T'+e) y(T'+e)$.
- We set $y(e) \leftarrow y(e) + \hat{c}(y; e) \le y(e) + f(T' + e) y(T' + e)$.

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- We set $y(e) \leftarrow y(e) + \hat{c}(y;e) \leq y(e) + f(T'+e) y(T'+e)$. Hence, after each step, $y \in P_f$ and $\hat{c}(y;e) \geq 0$. (also, consider r.h. version of $\hat{c}(y;e)$).

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- Also, only y(e) for $e \notin T$ changed, final y has y(e) = x(e) for $e \in T$.

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- Also, only y(e) for $e \notin T$ changed, final y has y(e) = x(e) for $e \in T$.
- Let $S_e \ni e$ be a set that achieves $c(y; e) = f(S_e) y(S_e)$.

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- Let $S_e \ni e$ be a set that achieves $c(y;e) = f(S_e) y(S_e)$.
- At iteration e, let y'(e) (resp. y(e)) be new (resp. old) entry for e, then $y'(S_e) = y(S_e \setminus \{e\}) + y'(e)$ (15.3)

$$= y(S_e \setminus \{e\}) + [y(e) + f(S_e) - y(S_e)] = f(S_e)$$

... proof of Thm. 15.5.2 cont.

- Each step maintains feasibility: consider one step adding e to T' for $e \notin T'$, feasibility requires $y(T'+e) = y(T') + y(e) \le f(T'+e)$, or $y(e) \le f(T'+e) - y(T') = y(e) + f(T'+e) - y(T'+e).$
- We set $y(e) \leftarrow y(e) + \hat{c}(y;e) \le y(e) + f(T'+e) y(T'+e)$. Hence, after each step, $y \in P_f$ and $\hat{c}(y;e) \geq 0$. (also, consider r.h. version of $\hat{c}(y;e)$.
- Also, only y(e) for $e \notin T$ changed, final y has y(e) = x(e) for $e \in T$.
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- At iteration e, let y'(e) (resp. y(e)) be new (resp. old) entry for e, then $y'(S_e) = y(S_e \setminus \{e\}) + y'(e)$ (15.3) $= y(S_e \setminus \{e\}) + [y(e) + f(S_e) - y(S_e)] = f(S_e)$

So, S_e is tight for y'. It remains tight in further iterations since ydoesn't decrease and it stays within P_f .

... proof of Thm. 15.5.2 cont.

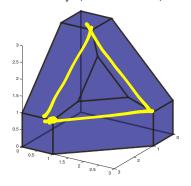
- Each step maintains feasibility: consider one step adding e to T' for $e \notin T'$, feasibility requires $y(T'+e) = y(T') + y(e) \le f(T'+e)$, or $y(e) \le f(T'+e) y(T') = y(e) + f(T'+e) y(T'+e)$.
- We set $y(e) \leftarrow y(e) + \hat{c}(y;e) \leq y(e) + f(T'+e) y(T'+e)$. Hence, after each step, $y \in P_f$ and $\hat{c}(y;e) \geq 0$. (also, consider r.h. version of $\hat{c}(y;e)$).
- Also, only y(e) for $e \notin T$ changed, final y has y(e) = x(e) for $e \in T$.
- Let $S_e \ni e$ be a set that achieves $c(y;e) = f(S_e) y(S_e)$.
- At iteration e, let y'(e) (resp. y(e)) be new (resp. old) entry for e, then $y'(S_e) = y(S_e \setminus \{e\}) + y'(e)$ (15.3) $= y(S_e \setminus \{e\}) + [y(e) + f(S_e) y(S_e)] = f(S_e)$

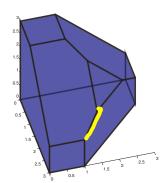
So, S_e is tight for y'. It remains tight in further iterations since y doesn't decrease and it stays within P_f .

ullet Also, $E=T\cup igcup_{e
otin T}S_e$ is also tight, meaning the final y has $y\in B_f$:

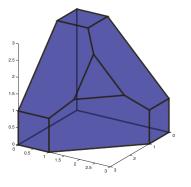
More on B_f

Polytope example 1 \bullet Observe: P_f (at two views):

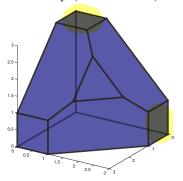


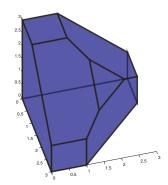


• Observe: P_f (at two views):

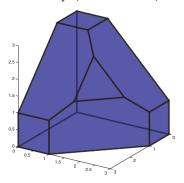


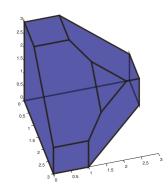
• Is this a polymatroidal polytope?





- Is this a polymatroidal polytope?
- No, " B_f " doesn't intersect sets of the form $\{x: x(e) = f(e)\}$ for $e \in E$.

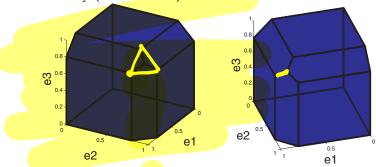




- Is this a polymatroidal polytope?
- No, " B_f " doesn't intersect sets of the form $\{x: x(e) = f(e)\}$ for $e \in E$.
- This was generated using function g(0)=0, g(1)=3, g(2)=4, and g(3)=5.5. Then f(S)=g(|S|) is not submodular since (e.g.) $f(\{e_1,e_3\})+f(\{e_1,e_2\})=4+4=8$ but

Examples **More on B** f Exchange Capacity Min-Norm Point and SFM Lovász extension

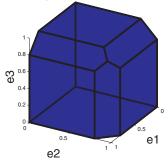
Polytope example 2



$$\chi: \chi(e_1) = f(e_1)$$

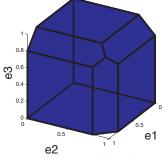
$$\chi: \chi(e_1e_2) = f(e_1e_2)$$

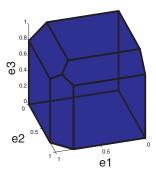
• Observe: P_f (at two views):



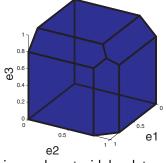
0.8 0.6 0.4 0.2 0.5 e2

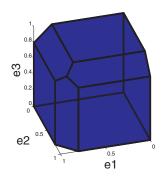
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- Is this a polymatroidal polytope?
- No, " B_f " (which would be a single point in this case) doesn't intersect sets of the form $\{x: x(e) = f(e)\}$ for $e \in E$.





- Is this a polymatroidal polytope?
- No, " B_f " (which would be a single point in this case) doesn't intersect sets of the form $\{x: x(e) = f(e)\}$ for $e \in E$.
- This was generated using function g(0) = 0, g(1) = 1, g(2) = 1.8, and g(3) = 3. Then f(S) = g(|S|) is not submodular since (e.g.) $f(\{e_1, e_3\}) + f(\{e_1, e_2\}) = 1.8 + 1.8 = 3.6$ but $f(\{e_1, e_2, e_3\}) + f(\{e_1\}) = 3 + 1 = 4$.

Review

The next slide is review from lecture 13.

Saturation Capacity

• The max is achieved when

$$\alpha = \hat{c}(x; e) \stackrel{\text{def}}{=} \min \left\{ f(A) - x(A), \forall A \supseteq \{e\} \right\}$$
 (15.22)

• $\hat{c}(x;e)$ is known as the saturation capacity associated with $x \in P_f$ and e.

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- Also, recall that given a matroid $\mathcal{M}=(E,\mathcal{I})$, if $I\in\mathcal{I}$ is independent, and $e\in\mathrm{span}(I)$, and $e'\in C(I,e)$ where C(I,e) is the fundamental circuit created when adding e to I, then we have:

$$I + e - e' \in \mathcal{I} \tag{15.4}$$

- Recall, matroids have a number of "exchange" properties.
- Also, recall that given a matroid $\mathcal{M}=(E,\mathcal{I})$, if $I\in\mathcal{I}$ is independent, and $e\in\mathrm{span}(I)$, and $e'\in C(I,e)$ where C(I,e) is the fundamental circuit created when adding e to I, then we have:

$$I + e - e' \in \mathcal{I} \tag{15.4}$$

• Note, this holds for any $e' \in C(I, e)$.

- Recall, matroids have a number of "exchange" properties.
- Also, recall that given a matroid $\mathcal{M}=(E,\mathcal{I})$, if $I\in\mathcal{I}$ is independent, and $e\in\mathrm{span}(I)$, and $e'\in C(I,e)$ where C(I,e) is the fundamental circuit created when adding e to I, then we have:

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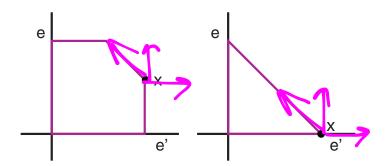
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- Yes, and it is called the "exchange capacity"

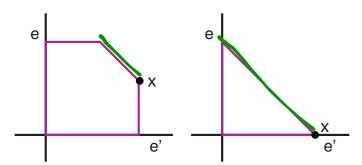
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- Examples:



• How much can we move in positive e direction if we simultaneously move in negative e' direction?

•
$$x \in P_f$$
, $e \in \operatorname{sat}(x)$ and $e' \in \operatorname{dep}(x, e) \setminus \{e\}$, consider
$$\max \left\{ \alpha : \alpha \in \mathbb{R}, x + \alpha(\mathbf{1}_e - \mathbf{1}_{e'}) \notin P_f \right\}$$
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• Identical to:

$$\max \left\{ \alpha : \alpha \in \mathbb{R}, (x + \alpha(\mathbf{1}_e - \mathbf{1}_{e'}))(A) \le f(A), \forall A \right\}$$
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• Which is identical to: $\max \big\{\alpha: \alpha \in \mathbb{R}, \alpha(\mathbf{1}_e - \mathbf{1}_{e'}))(A) \leq f(A) - x(A), \forall A \supseteq \{e\}, e' \notin A \big\}$ (15.8)

• In such case, we get $\mathbf{1}_{e'}(A) = 0$, thus above identical to

$$\max \left\{ \alpha : \alpha \in \mathbb{R}, \alpha \mathbf{1}_e(A) \le f(A) - x(A), \forall A \ge \{e\}, e' \notin A \right\}$$
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- For any α with $0 \le \alpha \le \hat{c}(x; e, e')$, we have that $x + \alpha(\mathbf{1}_e \mathbf{1}_{e'}) \in P_f$.
- As we will see, if e and e' are successive in an order that generates extreme point x, then we get a "neighbor" extreme point via $x' = x + \hat{c}(x; e, e')(\mathbf{1}_e \mathbf{1}_{e'})$.

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- Note that Eqn. (15.11) is a form of SFM.

Theorem 15.7.1

Let f be a submodular function defined on subsets of E. For any $x \in \mathbb{R}^E$, we have:

$$rank(x) = \max(y(E) : y \le x, y \in P_f) = \min(x(A) + f(E \setminus A) : A \subseteq E)$$
(15.5)

If we take x to be zero, we get:



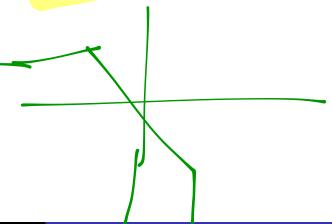
Corollary 15.7.2

Let f be a submodular function defined on subsets of E. $x \in \mathbb{R}^E$, we have:

$$rank(0) = \max(y(E) : y \le 0, y \in P_f) = \min(f(A) : A \subseteq E)$$
 (15.6)

• Restating what we saw before, we have:

$$\max\{y(E)|y \in P_f, y \le 0\} = \min\{f(X)|X \subseteq V\}$$
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• Consider the optimization:

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$$||x||_2^2 \Rightarrow (15.13a)$$

subject to $x \in B_f$ (15.13b)

where B_f is the base polytope of submodular f, and $\|x\|_2^2 = \sum_{e \in E} x(e)^2$ is the squared 2-norm. Let x^* be the optimal solution.

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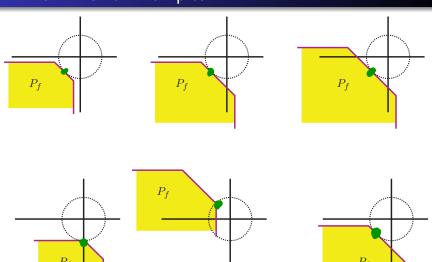
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- Note, x^* is the unique optimal solution since we have a strictly convex objective over a set of convex constraints.
- x^* is called the minimum norm point of the base polytope.

Min-Norm Point: Examples



Min-Norm Point and Submodular Function Minimization

ullet Given optimal solution x^* to the above, consider the quantities

$$y^* = x^* \land 0 = (\min(x^*(e), 0) | e \in E)$$
 (15.14)

$$A_{-} = \{e : x^{*}(e) < 0\} \tag{15.15}$$

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- It turns out, these quantities will solve the submodular function minimization problem, as we now show.
- The proof is nice since it uses the tools we've been recently developing.

p Examples More on B_f Exchange Capacity **Min-Norm Point and SFM** Lovász extension

Min-Norm Point and SFM

Theorem 15.7.1

Let y^* , A_- , and A_0 be as given. Then y^* is a maximizer of the l.h.s. of Eqn. (15.12). Moreover, A_- is the unique minimal minimizer of f and A_0 is the unique maximal minimizer of f.

Proof.

• First note, since $x^* \in B_f$, we have $x^*(E) = f(E)$, meaning $\operatorname{sat}(x^*) = E$. Thus, we can consider any $e \in E$ within $\operatorname{dep}(x^*, e)$.

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- Consider any pair (e,e') with $e'\in \operatorname{dep}(x^*,e)$ and $e\in A_-$. Then $x^*(e)<0$, and $\exists \alpha>0$ s.t. $x^*+\alpha \mathbf{1}_e-\alpha \mathbf{1}_{e'}\in P_f$.
- We have $x^*(E)=f(E)$ and x^* is minimum in I2 sense. We have $(x^*+\alpha \mathbf{1}_e-\alpha \mathbf{1}_{e'})\in P_f$, and in fact

$$(x^* + \alpha \mathbf{1}_e - \alpha \mathbf{1}_{e'})(E) = x^*(E) + \alpha - \alpha = f(E)$$
(15.17)

so $x^* + \alpha \mathbf{1}_e - \alpha \mathbf{1}_{e'} \in B_f$ also.

$$\bullet \text{ Then } (x^* + \alpha \mathbf{1}_e - \alpha \mathbf{1}_{e'})(E) \\ = x^*(E \setminus \{e, e'\}) + \underbrace{(x^*(e) + \alpha)}_{x^*_{\mathsf{new}}(e)} + \underbrace{(x^*(e') - \alpha)}_{x^*_{\mathsf{new}}(e')} = f(E).$$

..proof of Thm. 15.7.1 cont.

- Then $(x^* + \alpha \mathbf{1}_e \alpha \mathbf{1}_{e'})(E)$ = $x^*(E \setminus \{e, e'\}) + \underbrace{(x^*(e) + \alpha)}_{x^*_{\text{new}}(e)} + \underbrace{(x^*(e') - \alpha)}_{x^*_{\text{new}}(e')} = f(E).$
- Minimality of $x^* \in B_f$ in I2 sense requires that, with such an $\alpha > 0$,

$$\left(x^{*}(e)\right)^{2} + \left(x^{*}(e')\right)^{2} < \left(x^{*}_{\mathsf{new}}(e)\right)^{2} + \left(x^{*}_{\mathsf{new}}(e')\right)^{2}$$

Lovász extension

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- Given that $e \in A_-$, $x^*(e) < 0$. Thus, if $x^*(e') > 0$, we could have $(x^*(e) + \alpha)^2 + (x^*(e') \alpha)^2 < (x^*(e))^2 + (x^*(e'))^2$, contradicting the optimality of x^* .

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- If $x^*(e') = 0$, we would have $(x^*(e) + \alpha)^2 + (\alpha)^2 < (x^*(e))^2$, for any $0 < \alpha < |x^*(e)|$, again contradicting the optimality of x^* .
- Thus, we must have $x^*(e') < 0$ (strict negativity).

... proof of Thm. 15.7.1 cont.

• Thus, for a pair (e,e') with $e' \in dep(x^*,e)$ and $e \in A_-$, we have x(e') < 0 and hence $e' \in A_-$.

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... proof of Thm. 15.7.1 cont.

- Thus, for a pair (e,e') with $e' \in dep(x^*,e)$ and $e \in A_-$, we have x(e') < 0 and hence $e' \in A_-$.
- Hence, $\forall e \in A_-$, we have $dep(x^*, e) \subseteq A_-$.

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- Thus, for a pair (e,e') with $e' \in dep(x^*,e)$ and $e \in A_-$, we have x(e') < 0 and hence $e' \in A_-$.
- Hence, $\forall e \in A_-$, we have $dep(x^*, e) \subseteq A_-$.
- A very similar argument can show that, $\forall e \in A_0$, we have $dep(x^*,e) \subseteq A_0$.

... proof of Thm. 15.7.1 cont.

 \bullet Therefore, we have $\cup_{e\in A_-} \operatorname{dep}(x^*,e) = A_-$ and $\cup_{e\in A_0} \operatorname{dep}(x^*,e) = A_0$

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- le., $\{ dep(x^*, e) \}_{e \in A_-}$ is cover for A_- , as is $\{ dep(x^*, e) \}_{e \in A_0}$ for A_0 .
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$$x^*(A_-) = f(A_-) \tag{15.18}$$

- Therefore, we have $\cup_{e\in A_-} \operatorname{dep}(x^*,e) = A_-$ and $\cup_{e\in A_0} \operatorname{dep}(x^*,e) = A_0$
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and therefore, all together we have

$$f(A_{-}) = f(A_{0}) = x^{*}(A_{-}) = x^{*}(A_{0}) = y^{*}(E)$$
 (15.21)

... proof of Thm. 15.7.1 cont.

• Now, y^* is feasible for the l.h.s. of Eqn. (15.12).

Examples More on B_f Exchange Capacity **Min-Norm Point and SFM** Lovász ext

Min-Norm Point and SFM

... proof of Thm. 15.7.1 cont.

• Now, y^* is feasible for the l.h.s. of Eqn. (15.12). This follows since, we have $y^* = x^* \wedge 0 \leq 0$, and since $x^* \in B_f \subset P_f$, and $y^* \leq x^*$ and P_f is down-closed, we have that $y^* \in P_f$.

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- Also, for any $y \in P_f$ with $y \le 0$ and for any $X \subseteq E$, we have $y(E) \le y(X) \le f(X)$.

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- Also, for any $y \in P_f$ with $y \le 0$ and for any $X \subseteq E$, we have $y(E) \le y(X) \le f(X)$.
- Hence, we have found a feasible for l.h.s. of Eqn. (15.12), $y^* \le 0$, $y^* \in P_f$, so $y^*(E) \le f(X)$ for all X.

Examples More on B_f Exchange Capacity **Min-Norm Point and SFM** Lovi

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- So $y^*(E) \leq \min \{f(X) | X \subseteq V\}.$

xamples More on B_f Exchange Capacity **Min-Norm Point and SFM**

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- Hence, we have found a feasible for l.h.s. of Eqn. (15.12), $y^* \leq 0$, $y^* \in P_f$, so $y^*(E) \leq f(X)$ for all X.
- $\bullet \ \operatorname{So} \ y^*(E) \leq \min \left\{ f(X) | X \subseteq V \right\}.$
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- Also, for any $y \in P_f$ with $y \le 0$ and for any $X \subseteq E$, we have $y(E) \le y(X) \le f(X)$.
- Hence, we have found a feasible for l.h.s. of Eqn. (15.12), $y^* \leq 0$, $y^* \in P_f$, so $y^*(E) \leq f(X)$ for all X.
- So $y^*(E) \le \min \{f(X) | X \subseteq V\}.$
- Considering Eqn. (15.18), we have found sets A_- and A_0 with tightness in Eqn. (15.12), meaning $y^*(E) = f(A_-) = f(A_0)$.
- Hence, y^* is a maximizer of l.h.s. of Eqn. (15.12), and A_- and A_0 are minimizers of f.

... proof of Thm. 15.7.1 cont.

• Now, for any $X \subset A_-$, we have

$$f(X) \ge x^*(X) > x^*(A_-) = f(A_-)$$
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• Hence, A_{-} must be the unique minimal minimizer of f, and A_{0} is the unique maximal minimizer of f.



Supp Examples More on B_f Exchange Capacity **Min-Norm Point and SFM** Lovász extension

Min-Norm Point and SFM

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- This is currently the best practical algorithm for general purpose submodular function minimization.
- But its underlying lower-bound complexity is unknown, although in practice its estimated empirical complexity runs anywhere from $O(n^3)$ to $O(n^{4.5})$ or so (see Jegelka, Lin, Bilmes (NIPS 2011)).

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- In fact, with x^* the min-norm point, and A_- and A_0 as defined above, we have the following theorem:

Theorem 15.7.2

Let $A \subseteq E$ be any minimizer of submodular f, and let x^* be the minimum-norm point. Then A has the form:

$$A = A_{-} \cup \bigcup_{a \in A_{m}} \operatorname{dep}(x^{*}, a)$$
 (15.24)

for some set $A_m \subseteq A_0 \setminus A_-$.

Examples More on B_f Exchange Capacity Min-Norm Point and SFM Lovász

Min-norm point and other minimizers of f

proof of Thm. 15.7.2.

• If A is a minimizer, then $A_- \subseteq A \subseteq A_0$, and $f(A) = y^*(E)$ is the minimum valuation of f.



Examples More on B_f Exchange Capacity Min-Norm Point and SFM Lovász ex ...

Min-norm point and other minimizers of f

- If A is a minimizer, then $A_- \subseteq A \subseteq A_0$, and $f(A) = y^*(E)$ is the minimum valuation of f.
- But $x^* \in P_f$, so $x^*(A) \le f(A)$ and $f(A) = x^*(A_-) \le x^*(A)$ (or alternatively, just note that $x^*(A_0 \setminus A) = 0$).



Examples More on B_f Exchange Capacity **Min-Norm Point and SFM** Lovász extension

Min-norm point and other minimizers of f

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- Hence, $x^*(A) = x^*(A_-) = f(A)$ so that A is also a tight set for x^* .



Examples More on B_f Exchange Capacity Min-Norm Point and SFM Lovász extension

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- Hence, $x^*(A) = x^*(A_-) = f(A)$ so that A is also a tight set for x^* .
- For any $a \in A$, A is a tight set containing a, and $dep(x^*, a)$ is the minimal tight containing a.



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- For any $a \in A$, A is a tight set containing a, and $dep(x^*, a)$ is the minimal tight containing a.
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- Hence, $x^*(A) = x^*(A_-) = f(A)$ so that A is also a tight set for x^* .
- For any $a \in A$, A is a tight set containing a, and $dep(x^*, a)$ is the minimal tight containing a.
- Hence, for any $a \in A$, $dep(x^*, a) \subseteq A$.
- This means that $\bigcup_{a \in A} \operatorname{dep}(x^*, a) = A$.
- Since $A_- \subseteq A \subseteq A_0$, then $\exists A_m \subseteq A \setminus A_-$ such that $A = A_- \cup \bigcup_{a \in A_-} \operatorname{dep}(x^*, a)$.



On a unique minimizer f

• Note that if f(e|A) > 0, $\forall A \subseteq E$ and $e \in E \setminus A$, then we have $A_- = A_0$ (there is one unique minimizer).

On a unique minimizer f

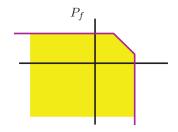
- Note that if f(e|A) > 0, $\forall A \subseteq E$ and $e \in E \setminus A$, then we have $A_- = A_0$ (there is one unique minimizer).
- On the other hand, if $A_- = A_0$, it does not imply f(e|A) > 0 for all $A \subseteq E \setminus \{e\}$.

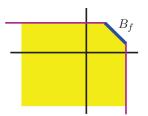
On a unique minimizer f

- Note that if f(e|A) > 0, $\forall A \subseteq E$ and $e \in E \setminus A$, then we have $A_{-}=A_{0}$ (there is one unique minimizer).
- On the other hand, if $A_- = A_0$, it does not imply f(e|A) > 0 for all $A \subseteq E \setminus \{e\}.$
- If $A_- = A_0$ then certainly $f(e|A_0) > 0$ for $e \in E \setminus A_0$ and $-f(e|A_0 \setminus \{e\}) > 0$ for all $e \in A_0$.

Multiple Polytopes associated with f







$$P_f^+ = P_f \cap \{ x \in \mathbb{R}^E : x \ge 0 \}$$
 (15.5)

$$P_f = \left\{ x \in \mathbb{R}^E : x(S) \le f(S), \forall S \subseteq E \right\}$$
 (15.6)

$$B_f = P_f \cap \{x \in \mathbb{R}^E : x(E) = f(E)\}$$
 (15.7)

Polymatroidal polyhedron and greedy

 Thus, restating the above results into a single complete theorem, we have a result very similar to what we saw for matroids (i.e., Theorem ??)

Theorem 15.8.1

If $f: 2^E \to \mathbb{R}_+$ is given, and P is a polytope in \mathbb{R}_+^E of the form $P = \left\{ x \in \mathbb{R}_+^E : x(A) \le f(A), \forall A \subseteq E \right\}$, then the greedy solution to the problem $\max(wx: x \in P)$ is $\forall w$ optimum iff f is monotone non-decreasing submodular (i.e., iff P is a polymatroid).

ullet Consider the following optimization. Given $w \in \mathbb{R}^E$,

maximize
$$w^{\mathsf{T}}x$$
 (15.25a)
subject to $x \in P_f$ (15.25b)

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- The greedy algorithm will solve this, and the proof almost identical.

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- Due to Theorem ??, any $x \in P_f$ with $x \notin B_f$ is dominated by $x \le y \in B_f$ which can only increase $w^{\mathsf{T}}x \le w^{\mathsf{T}}y$.

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- The greedy algorithm will solve this, and the proof almost identical.
- Due to Theorem **??**, any $x \in P_f$ with $x \notin B_f$ is dominated by $x \le y \in B_f$ which can only increase $w^{\mathsf{T}}x \le w^{\mathsf{T}}y$.
- ullet Hence, the problem is equivalent to: given $w \in \mathbb{R}_+^E$,

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• Moreover, we can have $w \in \mathbb{R}^E$ if we insist on $x \in B_f$.

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• We may consider this optimization problem a function $\tilde{f}: \mathbb{R}^E \to \mathbb{R}$ of $w \in \mathbb{R}^E$, defined as:

$$\tilde{f}(w) = \max(wx : x \in P_f) \tag{15.28}$$

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• Hence, for any w, from the above theorem, we can compute the value of this function using the greedy algorithm (after of course checking for $w \in \mathbb{R}_+^E$).

• That is, given a submodular function f, a $w \in \mathbb{R}^E$, and defining $E_i = \{e_1, e_2, \dots, e_i\}$ and where we choose the element order (e_1, e_2, \dots, e_m) based on decreasing w,so that $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$, we have $\tilde{f}(w)$

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$$= \sum_{i=1}^{m} w(e_i) f(e_i | E_{i-1})$$
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$$= \sum_{i=1}^{m} w(e_i)(f(E_i) - f(E_{i-1}))$$
(15.31)

• That is, given a submodular function f, a $w \in \mathbb{R}^E$, and defining $E_i = \{e_1, e_2, \dots, e_i\}$ and where we choose the element order (e_1, e_2, \dots, e_m) based on decreasing w,so that $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$, we have

$$\tilde{f}(w) = \max(wx : x \in P_f) \tag{15.29}$$

$$= \sum_{i=1}^{m} w(e_i) f(e_i | E_{i-1})$$
 (15.30)

$$= \sum_{i=1}^{m} w(e_i)(f(E_i) - f(E_{i-1}))$$
(15.31)

$$= w(e_m)f(E_m) + \sum_{i=1}^{m-1} (w(e_i) - w(e_{i+1}))f(E_i)$$
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A continuous extension of f

• That is, given a submodular function f, a $w \in \mathbb{R}^E$, and defining $E_i = \{e_1, e_2, \dots, e_i\}$ and where we choose the element order (e_1, e_2, \dots, e_m) based on decreasing w,so that $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$, we have

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• We say that $\emptyset \triangleq E_0 \subset E_1 \subset E_2 \subset \cdots \subset E_m = E$ forms a chain based on w.

• Definition of the continuous extension, once again, for reference:

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• From convex analysis, we know $f(w) = \max(wx : x \in P)$ is always convex in w for any set $P \subseteq R^E$, since it is the maximum of a set of linear functions (true even when f is not submodular or P is not a convex set).

 \bullet Recall, for any such $w \in \mathbb{R}^E$, we have

$$\begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{pmatrix} = \underbrace{\begin{pmatrix} w_1 - w_2 \end{pmatrix}}_{\lambda_1} \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \underbrace{\begin{pmatrix} w_2 - w_3 \end{pmatrix}}_{\lambda_2} \begin{pmatrix} 1 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \underbrace{\begin{pmatrix} w_1 - w_2 \end{pmatrix}}_{\lambda_m} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 0 \end{pmatrix} + \underbrace{\begin{pmatrix} w_1 - w_2 \end{pmatrix}}_{\lambda_m} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 0 \end{pmatrix} + \underbrace{\begin{pmatrix} w_1 - w_2 \end{pmatrix}}_{\lambda_m} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 1 \end{pmatrix}$$
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• If we take w in decreasing order, then each coefficient of the vectors is non-negative (except possibly the last one, $\lambda_m = w_m$).

ullet Define sets E_i based on this decreasing order of w as follows, for $i=0,\dots,n$

$$E_i \stackrel{\text{def}}{=} \{e_1, e_2, \dots, e_i\}$$
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Note that

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Lovász extension

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 Hence, from the previous and current slide, we have $w = \sum_{i=1}^{m} \lambda_i \mathbf{1}_{E_i}$

• From the continuous \tilde{f} , we can recover f(A) for any $A \subseteq V$.

- \bullet From the continuous $\widetilde{f},$ we can recover f(A) for any $A\subseteq V.$
- Take $w = \mathbf{1}_A$ for some $A \subseteq E$, so w is vertex of the hypercube.

From \overline{f} back to f, even when f is not submodular

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- This means

$$w = (w(e_1), w(e_2), \dots, w(e_m)) = (\underbrace{1, 1, 1, \dots, 1}_{|A| \text{ times}}, \underbrace{0, 0, \dots, 0}_{m-|A| \text{ times}})$$
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so that $1_A(i) = 1$ if $i \leq |A|$, and $1_A(i) = 0$ otherwise.

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From \tilde{f} back to f

• We can view $\tilde{f}:[0,1]^E\to\mathbb{R}$ defined on the hypercube, with f defined as \tilde{f} evaluated on the hypercube extreme points (vertices).

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- To summarize, with $\tilde{f}(A) = \sum_{i=1}^{m} \lambda_i f(E_i)$, we have

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 \bullet ... and when f is submodular, we also have have

$$\tilde{f}(\mathbf{1}_A) = \max{\{\mathbf{1}_A x : x \in P_f\}}.$$
 (15.42)

ullet Thus, for any $f:2^E \to \mathbb{R}$, even non-submodular f, we can define an extension in this way, with

$$\tilde{f}(w) = \sum_{i=1}^{m} \lambda_i f(E_i)$$
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with the $E_i=\{e_1,\ldots,e_i\}$'s defined based on sorted descending order of w as in $w(e_1)\geq w(e_2)\geq \cdots \geq w(e_m)$, and where

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• Note that $w = \sum_{i=1}^m \lambda_i \mathbf{1}_{E_i}$ is an interpolation of certain vertices of the hypercube, and that $f(w) = \sum_{i=1}^m \lambda_i f(E_i)$ is the corresponding interpolation of the values of f at sets corresponding to each hypercube vertex.

Weighted gains vs. weighted functions

• Again sorting E descending in w, the extension summarized:

$$\tilde{f}(w) = \sum_{i=1}^{m} w(e_i) f(e_i | E_{i-1})$$
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$$= \sum_{i=1}^{m} w(e_i)(f(E_i) - f(E_{i-1}))$$
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$$= w(e_m)f(E_m) + \sum_{i=1}^{m-1} (w(e_i) - w(e_{i+1}))f(E_i)$$
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• So $\tilde{f}(w)$ seen either as sum of weighted gain evaluatiosn (Eqn. (15.45), or as sum of weighted function evaluations (Eqn. (15.48)).

The Lovász extension of $f:2^E \to \mathbb{R}$

• Lovász showed that if a function $\tilde{f}(w)$ defined as in Eqn. (15.43) is convex, then f must be submodular.

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- Note, also possible to define this when $f(\emptyset) \neq 0$ (but doesn't really add any generality).

Lovász Extension, Submodularity and Convexity

Theorem 15.8.1

A function $f:2^E\to\mathbb{R}$ is submodular iff its Lovász extension \tilde{f} of f is convex.

Proof.

• We've already seen that if f is submodular, its extension can be written via Eqn.(15.43) due to the greedy algorithm, and therefore is also equivalent to $\tilde{f}(w) = \max\{wx : x \in P_f\}$, and thus is convex.

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- Conversely, suppose the Lovász extension $\tilde{f}(w) = \sum_i \lambda_i f(E_i)$ of some function $f: 2^E \to \mathbb{R}$ is a convex function.
- We note that, based on the extension definition, in particular the definition of the $\{\lambda_i\}_i$, we have that $\tilde{f}(\alpha w) = \alpha \tilde{f}(w)$ for any $\alpha \in \mathbb{R}_+$. I.e., f is a positively homogeneous convex function.

...proof of Thm. 15.8.1 cont.

• Earlier, we saw that $\tilde{f}(\mathbf{1}_A) = f(A)$ for all $A \subseteq E$.

... proof of Thm. 15.8.1 cont.

- Earlier, we saw that $\tilde{f}(\mathbf{1}_A) = f(A)$ for all $A \subseteq E$.
- Now, given $A, B \subseteq E$, we will show that

$$\tilde{f}(\mathbf{1}_A + \mathbf{1}_B) = \tilde{f}(\mathbf{1}_{A \cup B} + \mathbf{1}_{A \cap B})$$
 (15.49)
= $f(A \cup B) + f(A \cap B)$. (15.50)

...proof of Thm. 15.8.1 cont.

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• Let $C = A \cap B$, order E based on decreasing $w = \mathbf{1}_A + \mathbf{1}_B$ so that

$$w = (w(e_1), w(e_2), \dots, w(e_m))$$
(15.51)

$$= (\underbrace{2, 2, \dots, 2}_{i \in C}, \underbrace{1, 1, \dots, 1}_{i \in A \triangle B}, \underbrace{0, 0, \dots, 0}_{i \in E \setminus (A \cup B)})$$
(15.52)

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• Then, considering $\tilde{f}(w) = \sum_i \lambda_i f(E_i)$, we have $\lambda_{|C|} = 1$, $\lambda_{|A \cup B|} = 1$, and $\lambda_i = 0$ for $i \notin \{|C|, |A \cup B|\}$.

... proof of Thm. 15.8.1 cont.

- Earlier, we saw that $\tilde{f}(\mathbf{1}_A) = f(A)$ for all $A \subseteq E$.
- Now, given $A, B \subseteq E$, we will show that

$$\tilde{f}(\mathbf{1}_A + \mathbf{1}_B) = \tilde{f}(\mathbf{1}_{A \cup B} + \mathbf{1}_{A \cap B}) \tag{15.49}$$

$$= f(A \cup B) + f(A \cap B).$$
 (15.50)

• Let $C = A \cap B$, order E based on decreasing $w = \mathbf{1}_A + \mathbf{1}_B$ so that

$$w = (w(e_1), w(e_2), \dots, w(e_m))$$
(15.51)

$$= (\underbrace{2, 2, \dots, 2}_{i \in C}, \underbrace{1, 1, \dots, 1}_{i \in A \triangle B}, \underbrace{0, 0, \dots, 0}_{i \in E \setminus (A \cup B)})$$
(15.52)

- Then, considering $\tilde{f}(w) = \sum_i \lambda_i f(E_i)$, we have $\lambda_{|C|} = 1$, $\lambda_{|A \cup B|} = 1$, and $\lambda_i = 0$ for $i \notin \{|C|, |A \cup B|\}$.
- But then $E_{|C|} = A \cap B$ and $E_{|A \cup B|} = A \cup B$. Therefore, $\tilde{f}(w) = f(A \cap B) + f(A \cup B)$.

Lovász Extension, Submodularity and Convexity

... proof of Thm. 15.8.1 cont.

• Also, since \tilde{f} is convex (by assumption) and positively homogeneous, we have for any $A, B \subseteq E$,

$$0.5[f(A \cap B) + f(A \cup B)]$$

(15.56)



Lovász Extension, Submodularity and Convexity

... proof of Thm. 15.8.1 cont.

• Also, since \tilde{f} is convex (by assumption) and positively homogeneous, we have for any $A, B \subseteq E$,

$$0.5[f(A \cap B) + f(A \cup B)] = 0.5[\tilde{f}(\mathbf{1}_A + \mathbf{1}_B)]$$
 (15.53)

(15.56)

Lovász Extension, Submodularity and Convexity

... proof of Thm. 15.8.1 cont.

• Also, since \tilde{f} is convex (by assumption) and positively homogeneous, we have for any $A, B \subseteq E$,

$$0.5[f(A \cap B) + f(A \cup B)] = 0.5[\tilde{f}(\mathbf{1}_A + \mathbf{1}_B)]$$
 (15.53)

$$= \tilde{f}(0.5\mathbf{1}_A + 0.5\mathbf{1}_B) \tag{15.54}$$

(15.56)



Lovász Extension, Submodularity and Convexity

... proof of Thm. 15.8.1 cont.

• Also, since \tilde{f} is convex (by assumption) and positively homogeneous, we have for any $A, B \subseteq E$,

$$0.5[f(A \cap B) + f(A \cup B)] = 0.5[\tilde{f}(\mathbf{1}_A + \mathbf{1}_B)]$$
 (15.53)

$$= \tilde{f}(0.5\mathbf{1}_A + 0.5\mathbf{1}_B) \tag{15.54}$$

$$\leq 0.5\tilde{f}(\mathbf{1}_A) + 0.5\tilde{f}(\mathbf{1}_B)$$
 (15.55)

Lovász Extension, Submodularity and Convexity

... proof of Thm. 15.8.1 cont.

• Also, since \tilde{f} is convex (by assumption) and positively homogeneous, we have for any $A, B \subseteq E$,

$$0.5[f(A \cap B) + f(A \cup B)] = 0.5[\tilde{f}(\mathbf{1}_A + \mathbf{1}_B)]$$
 (15.53)

$$= \tilde{f}(0.5\mathbf{1}_A + 0.5\mathbf{1}_B) \tag{15.54}$$

$$\leq 0.5\tilde{f}(\mathbf{1}_A) + 0.5\tilde{f}(\mathbf{1}_B)$$
 (15.55)

$$= 0.5(f(A) + f(B)) \tag{15.56}$$

Lovász Extension, Submodularity and Convexity

... proof of Thm. 15.8.1 cont.

• Also, since \tilde{f} is convex (by assumption) and positively homogeneous, we have for any $A, B \subseteq E$,

$$0.5[f(A \cap B) + f(A \cup B)] = 0.5[\tilde{f}(\mathbf{1}_A + \mathbf{1}_B)]$$
 (15.53)

$$= \tilde{f}(0.5\mathbf{1}_A + 0.5\mathbf{1}_B) \tag{15.54}$$

$$\leq 0.5\tilde{f}(\mathbf{1}_A) + 0.5\tilde{f}(\mathbf{1}_B)$$
 (15.55)

$$= 0.5(f(A) + f(B)) \tag{15.56}$$

• Thus, we have shown that for any $A, B \subseteq E$,

$$f(A \cup B) + f(A \cap B) \le f(A) + f(B)$$
 (15.57)

so f must be submodular.



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SUBMODULAR FUNCTIONS, MATROIDS, AND CERTAIN POLYHEDRA*

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I.

The viewpoint of the subject of matroids, and related areas of lattice theory, has always been, in one way or another, abstraction of algebraic dependence or, equivalently, abstraction of the incidence relations in geometric representations of algebra. Often one of the