

# Submodular Functions, Optimization, and Applications to Machine Learning

— Spring Quarter, Lecture 11 —

[http://j.ee.washington.edu/~bilmes/classes/ee596b\\_spring\\_2014/](http://j.ee.washington.edu/~bilmes/classes/ee596b_spring_2014/)

Prof. Jeff Bilmes

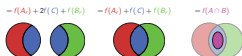
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May 7th, 2014



$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$$



# Cumulative Outstanding Reading

- Read chapters 1 and 2, and sections 3.1-3.2 from Fujishige's book.
- Good references for today: Schrijver-2003, Oxley-1992/2011, Welsh-1973, Goemans-2010, Cunningham-1984, Edmonds-1969.

# Announcements, Assignments, and Reminders

- Weekly Office Hours: Wednesdays, 5:00-5:50, or by skype or google hangout (email me).

# Class Road Map - IT-I

- L1 (3/31): Motivation, Applications, & Basic Definitions
- L2: (4/2): Applications, Basic Definitions, Properties
- L3: More examples and properties (e.g., closure properties), and examples, spanning trees
- L4: proofs of equivalent definitions, independence, start matroids
- L5: matroids, basic definitions and examples
- L6: More on matroids, System of Distinct Reps, Transversals, Transversal Matroid, Matroid and representation
- L7: Dual Matroids, other matroid properties, Combinatorial Geometries
- L8: Combinatorial Geometries, matroids and greedy, Polyhedra, Matroid Polytopes,
- L9: From Matroid Polytopes to Polymatroids.
- L10: Polymatroids and Submodularity
- L11: More properties of polymatroids, SFM special cases
- L12:
- L13:
- L14:
- L15:
- L16:
- L17:
- L18:
- L19:
- L20:

Finals Week: June 9th-13th, 2014.

# A polymatroid function's polyhedron is a polymatroid.

## Theorem 11.2.4

Let  $f$  be a polymatroid function defined on subsets of  $E$ . For any  $x \in \mathbb{R}_+^E$ , and any  $P_f^+$ -basis  $y^x \in \mathbb{R}_+^E$  of  $x$ , the component sum of  $y^x$  is

$$\begin{aligned} y^x(E) = \text{rank}(x) &= \max \left( y(E) : y \leq x, y \in P_f^+ \right) \\ &= \min (x(A) + f(E \setminus A) : A \subseteq E) \end{aligned} \quad (11.34)$$

As a consequence,  $P_f^+$  is a polymatroid, since r.h.s. is constant w.r.t.  $y^x$ .

By taking  $B = \text{supp}(x)$  (so elements  $E \setminus B$  are zero in  $x$ ), and for  $b \in B$ ,  $x(b)$  is big enough, the r.h.s. min has solution  $A^* = E \setminus B$ . We recover submodular function from the polymatroid polyhedron via the following:

$$f(B) = \max \left\{ y(B) : y \in P_f^+ \right\} \quad (11.35)$$

In fact, we will ultimately see a number of important consequences of this theorem (other than just that  $P_f^+$  is a polymatroid)

## Join $\vee$ and meet $\wedge$ for $x, y \in \mathbb{R}_+^E$

- For  $x, y \in \mathbb{R}_+^E$ , define vectors  $x \wedge y \in \mathbb{R}_+^E$  and  $x \vee y \in \mathbb{R}_+^E$  such that, for all  $e \in E$

$$(x \vee y)(e) = \max(x(e), y(e)) \quad (11.18)$$

$$(x \wedge y)(e) = \min(x(e), y(e)) \quad (11.19)$$

Hence,

$$x \vee y \triangleq \left( \max(x(e_1), y(e_1)), \max(x(e_2), y(e_2)), \dots, \max(x(e_n), y(e_n)) \right)$$

and similarly

$$x \wedge y \triangleq \left( \min(x(e_1), y(e_1)), \min(x(e_2), y(e_2)), \dots, \min(x(e_n), y(e_n)) \right)$$

- From this, we can define things like an lattices, and other constructs.

# Vector rank, $\text{rank}(x)$ , is submodular

- Recall that the matroid rank function is submodular.
- The vector rank function  $\text{rank}(x)$  also satisfies a form of submodularity.

## Theorem 11.2.1 (vector rank and submodularity)

*Let  $P$  be a polymatroid polytope. The vector rank function  $\text{rank} : \mathbb{R}_+^E \rightarrow \mathbb{R}$  with  $\text{rank}(x) = \max(y(E) : y \leq x, y \in P)$  satisfies, for all  $u, v \in \mathbb{R}_+^E$*

$$\text{rank}(u) + \text{rank}(v) \geq \text{rank}(u \vee v) + \text{rank}(u \wedge v) \quad (11.18)$$

# A polymatroid is a polymatroid function's polytope

- So, when  $f$  is a polymatroid function,  $P_f^+$  is a polymatroid.
- Is it the case that, conversely, for any polymatroid  $P$ , there is an associated polymatroidal function  $f$  such that  $P = P_f^+$ ?

## Theorem 11.2.1

*For any polymatroid  $P$  (compact subset of  $\mathbb{R}_+^E$ , zero containing, down-monotone, and  $\forall x \in \mathbb{R}_+^E$  any maximal independent subvector  $y \leq x$  has same component sum  $y(E) = \text{rank}(x)$ ), there is a polymatroid function  $f : 2^E \rightarrow \mathbb{R}$  (normalized, monotone non-decreasing, submodular) such that  $P = P_f^+$  where  $P_f^+ = \{x \in \mathbb{R}^E : x \geq 0, x(A) \leq f(A), \forall A \subseteq E\}$ .*



# First, a bit on $\mathcal{D}(y)$

Recall the definition of the set of tight sets at  $y \in P_f^+$ :

$$\mathcal{D}(y) \triangleq \{A : A \subseteq E, y(A) = f(A)\} \quad (11.18)$$

## Theorem 11.2.1

*For any  $y \in P_f^+$ , with  $f$  a polymatroid function, then  $\mathcal{D}(y)$  is closed under union and intersection.*

## Proof.

We have already proven this as part of Theorem 9.4.5 □

Also recall the definition of  $\text{sat}(y)$ , the maximal set of tight elements relative to  $y \in \mathbb{R}_+^E$ .

$$\text{sat}(y) \stackrel{\text{def}}{=} \bigcup \{T : T \in \mathcal{D}(y)\} \quad (11.19)$$

# A word on terminology & notation

- Recall how a matroid is sometimes given as  $(E, r)$  where  $r$  is the rank function.

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- Recall how a matroid is sometimes given as  $(E, r)$  where  $r$  is the rank function.
- We mention also that the term “polymatroid” is sometimes not used for the polytope itself, but instead but for the pair  $(E, f)$ ,
- But now we see that  $(E, f)$  is equivalent to a polymatroid polytope, so this is sensible.

$(E, P)$

# Where are we going with this?

- Consider the right hand side of Theorem 9.4.5:

$$\min (x(A) + f(E \setminus A) : A \subseteq E)$$



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- We are going to study this problem, and approaches that address it, as part of our ultimate goal which is to present strategies for submodular function minimization (that we will ultimately get to, in near future lectures).
- As a bit of a hint on what's to come, recall that we can write it as:  
 $x(E) + \min (f(A) - x(A) : A \subseteq E)$  where  $f$  is a polymatroid function.

# Another Interesting Fact: Matroids from polymatroid functions

## Theorem 11.3.1

Given integral polymatroid function  $f$ , let  $(E, \mathcal{F})$  be a set system with ground set  $E$  and set of subsets  $\mathcal{F}$  such that

$$\forall F \in \mathcal{F}, \quad \forall \emptyset \subset S \subseteq F, |S| \leq f(S) \quad (11.1)$$

Then  $M = (E, \mathcal{F})$  is a matroid.

Proof.

Exercise



And its rank function is **Exercise**.



# Matroid instance of Theorem 9.4.5

- Considering Theorem 9.4.5, the matroid case is now a special case, where we have that:

## Corollary 11.3.2

We have that:

$$\max \{y(E) : y \in P_{ind. set}(M), y \leq x\} = \min \{r_M(A) + x(E \setminus A) : A \subseteq E\} \quad (11.2)$$

where  $r_M$  is the matroid rank function of some matroid.

# Most violated inequality problem in matroid polytope case

- Consider

$$P_r^+ = \{x \in \mathbb{R}^E : x \geq 0, x(A) \leq r_M(A), \forall A \subseteq E\} \quad (11.3)$$

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- The **most violated inequality** when  $x$  is considered w.r.t.  $P_r^+$  corresponds to the set  $A$  that maximizes  $x(A) - r_M(A)$ , i.e.,  $\max \{x(A) - r_M(A) : A \subseteq E\}$ .

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- This corresponds to  $\min \{r_M(A) + x(E \setminus A) : A \subseteq E\}$  since  $x$  is modular and  $x(E \setminus A) = x(E) - x(A)$ .
- More importantly,  $\min \{r_M(A) + x(E \setminus A) : A \subseteq E\}$  a form of submodular function minimization, namely  $\min \{r_M(A) - x(A) : A \subseteq E\}$  for a submodular function consisting of a difference of matroid rank and modular (so no longer necessarily monotone, nor positive).

# Problem to Solve

In particular, we will solve the following problem:

- Given a matroid  $M = (E, \mathcal{I})$  along with an independence testing oracle (i.e., for any  $A \subseteq E$ , tells us if  $A \in \mathcal{I}$  or not), and a vector  $x \in \mathcal{R}_+^E$ ;



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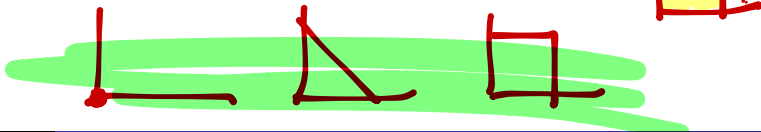
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- find: a maximizing  $y \in P_{\text{ind. set}}$  with  $y \leq x$ , and moreover (as a byproduct of the algorithm), express  $y$  as a convex combination of incidence vectors of independent sets in  $M$ , and also return a set  $A \subseteq E$  that satisfies  $y(E) = r_M(A) + x(E \setminus A)$ . *Of course, by Theorem 9.4.5, for any such  $y$  we must have that  $y(E) \leq r(A) + x(E \setminus A)$ .*

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- This will also run in polynomial time.

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- and the way these additions are done is via solutions to a max-flow problem in an associated flow-graph (which we'll describe).
- Each update will, of course, ensure that  $y \in P_{\text{ind. set}}$ , but also we'll keep  $y \leq x$ .
- It's going to take us a few lectures to fully develop this algorithm, so please keep in mind of the overall goal.

# Bipartite Matching

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- Given  $A \subseteq E$ , an **alternating path**  $S$  (relative to  $A$ ) is an (undirected) path of unique edges that are alternatively in  $A$  and not in  $A$ . I.e., if  $S = (e_1, e_2, \dots, e_s)$  is an alternating path, then  $S_{1/2} \stackrel{\text{def}}{=} S \setminus A$  where  $S_{1/2}$  is either the odd or the even elements of  $S$ .

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- An  $A \subseteq E$  is an **augmenting path** if it is an alternating path between two unmatched vertices.

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**Algorithm 8.1:** Alternating Path Bipartite Matching

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- 1 Let  $A$  be an arbitrary (including empty) matching in  $G = (V, F, E)$  ;
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## Algorithm 8.1: Alternating Path Bipartite Matching

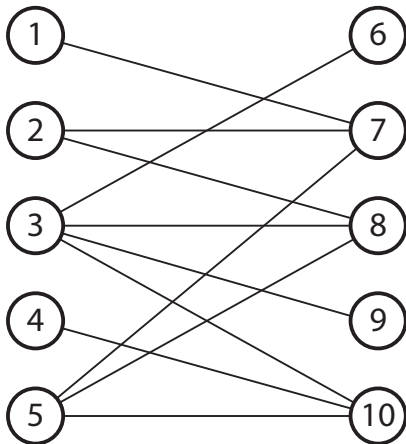
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- This can easily be made to run in  $O(m^2n)$ , where  $|V| = m$ ,  $|F| = n$ ,  $m \leq n$ , but it can be made to run much faster as well (see Schrijver-2003).

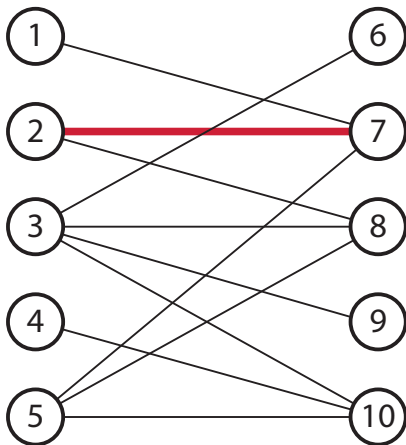
# Bipartite Matching Example

Consider the following bipartite graph  $G = (V, F, E)$  with  $|V| = |F| = 5$ . Any edge is an augmenting path since it will adjoin two unmatched vertices.



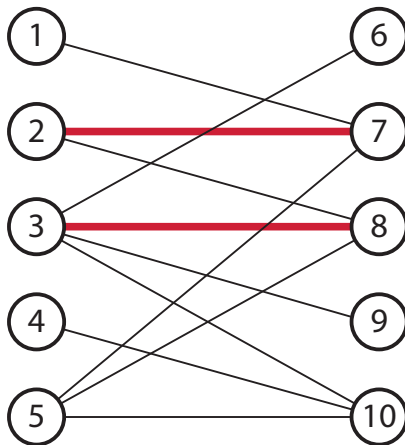
# Bipartite Matching Example

Any edge, not intersecting nodes adjacent to current matching is an augmenting path.



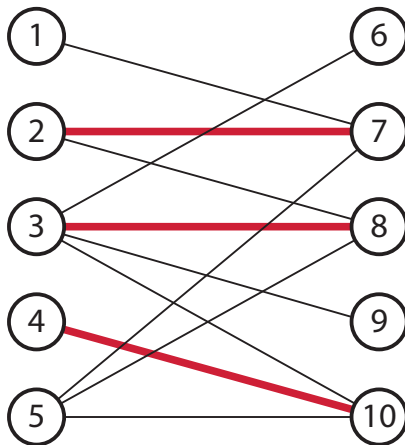
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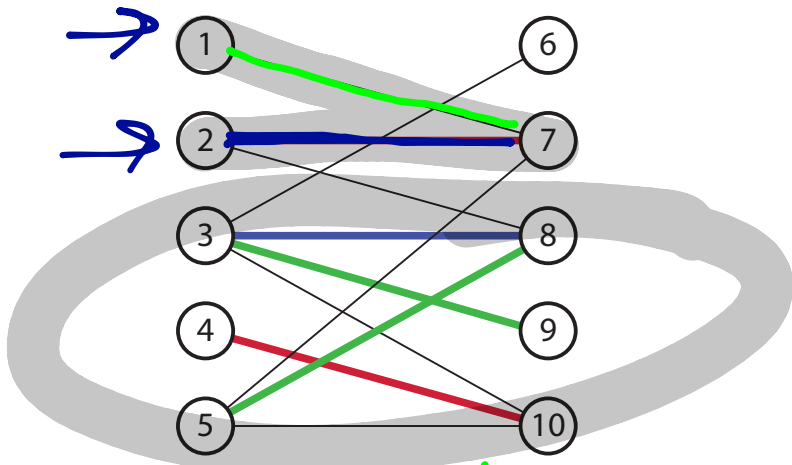
# Bipartite Matching Example

No possible further single edge addition at this point. We need a multi-edge augmenting path if it exists.



# Bipartite Matching Example

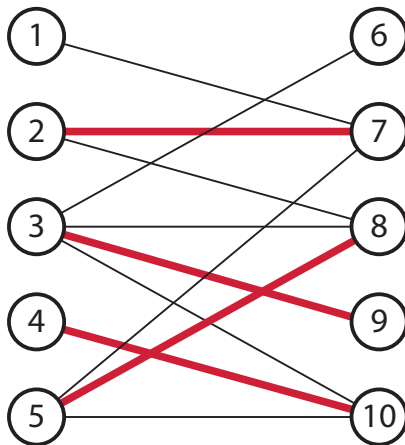
Augmenting path is green and blue edges (blue is already in matching, green is new).





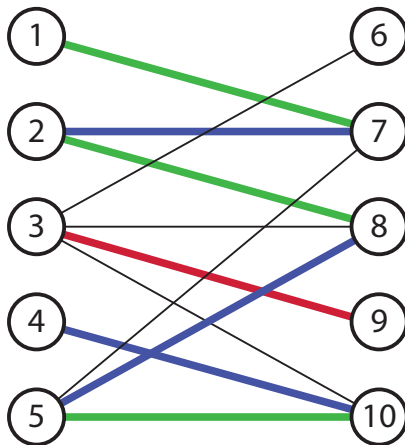
# Bipartite Matching Example

Removing blue from matching and adding green leads to higher cardinality matching.



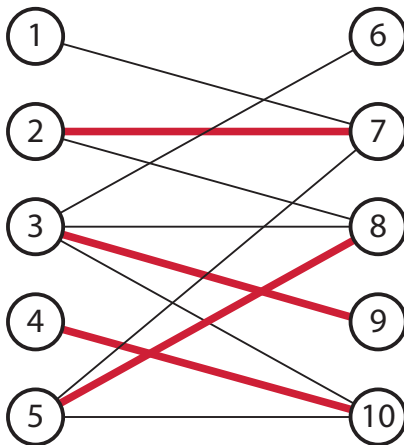
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At this point, resulting alternating path is not augmenting, since it is not between two unmatched vertices (and no augmenting path is possible).



# Bipartite Matching Example

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At this point, matching is maximum cardinality.



# Review

- The next slide is from lecture 7 and the one after from lecture 5.

# Matroid Intersection

- Let  $M_1 = (V, \mathcal{I}_1)$  and  $M_2 = (V, \mathcal{I}_2)$  be two matroids. Consider their common independent sets  $\mathcal{I}_1 \cap \mathcal{I}_2$ .
- While  $(V, \mathcal{I}_1 \cap \mathcal{I}_2)$  is typically not a matroid (**Exercise: show graphical example.**), we might be interested in finding the maximum size common independent set. That is, find  $\max |X|$  such that both  $X \in \mathcal{I}_1$  and  $X \in \mathcal{I}_2$ .

## Theorem 11.5.5

Let  $M_1$  and  $M_2$  be given as above, with rank functions  $r_1$  and  $r_2$ . Then the size of the maximum size set in  $\mathcal{I}_1 \cap \mathcal{I}_2$  is given by

$$(r_1 * r_2)(V) \triangleq \min_{X \subseteq V} (r_1(X) + r_2(V \setminus X)) \quad (11.7)$$

This is an instance of the **convolution of two submodular functions**,  $f_1$  and  $f_2$  that, evaluated at  $Y \subseteq V$ , is written as:

$$(f_1 * f_2)(Y) = \min_{X \subseteq Y} (f_1(X) + f_2(Y \setminus X)) \quad (11.8)$$

# Partition Matroid

- Let  $V$  be our ground set.
- Let  $V = V_1 \cup V_2 \cup \dots \cup V_\ell$  be a partition of  $V$  into blocks or disjoint sets (disjoint union). Define a set of subsets of  $V$  as

$$\mathcal{I} = \{X \subseteq V : |X \cap V_i| \leq k_i \text{ for all } i = 1, \dots, \ell\}. \quad (11.3)$$

where  $k_1, \dots, k_\ell$  are fixed parameters,  $k_i \geq 0$ . Then  $M = (V, \mathcal{I})$  is a matroid.

- Note that a  $k$ -uniform matroid is a trivial example of a partition matroid with  $\ell = 1$ ,  $V_1 = V$ , and  $k_1 = k$ .
- We'll show that property (I3') in Def ?? holds. If  $X, Y \in \mathcal{I}$  with  $|Y| > |X|$ , then there must be at least one  $i$  with  $|Y \cap V_i| > |X \cap V_i|$ . Therefore, adding one element  $e \in V_i \cap (Y \setminus X)$  to  $X$  won't break independence.

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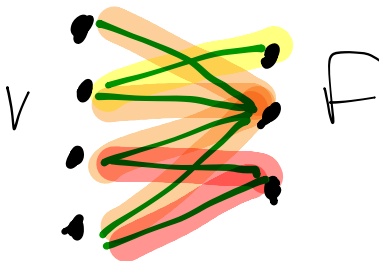
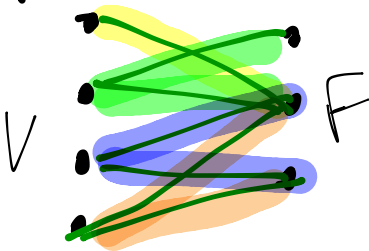
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- Independence in each matroid corresponds to:

Partition based on left vertices.

partition of  $E$  corresponding to right vertices



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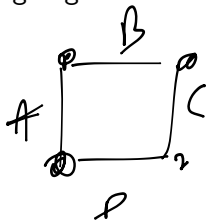
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- Therefore, a matching in  $G$  is simultaneously independent in both  $M_V$  and  $M_F$  and finding the maximum matching is finding the maximum cardinality set independent in both matroids.
- For the bipartite graph case, therefore, this can be solved in polynomial time.

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- This is again a matroid intersection problem.

# Matroid Intersection and TSP

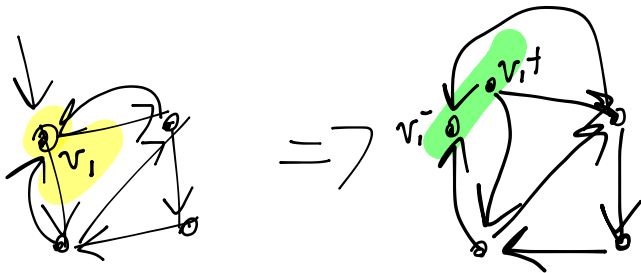
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- Then a Hamiltonian cycle exists iff there is an  $n$ -element intersection of  $M_1$ ,  $M_2$ , and  $M_3$ .



# Matroid Intersection and TSP

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# Matroid Intersection and TSP


- Since TSP is NP-complete, we obviously can't solve matroid intersections of 3 more matroids, unless  $P=NP$ .
- But bipartite graph example gives us hope for 2 matroids, and also ideas for an algorithm ...

# Recall from Lecture 5: Matroids by circuits

A set is independent if and only if it contains no circuit. Therefore, it is not surprising that circuits can also characterize a matroid.

## Theorem 11.5.1

*Matroid (by circuits) Let  $E$  be a set and  $\mathcal{C}$  be a collection of nonempty subsets of  $E$ , such that no two sets in  $\mathcal{C}$  are contained in each other. Then the following are equivalent.*

- ① (C1)  $\mathcal{C}$  is the collection of circuits of a matroid;
- ② (C2) if  $C, C' \in \mathcal{C}$ , and  $x \in C \cap C'$ , then  $(C \cup C') \setminus \{x\}$  contains a set in  $\mathcal{C}$ ;  

- ③ (C3) if  $C, C' \in \mathcal{C}$ , and  $x \in C \cap C'$ , and  $y \in C \setminus C'$ , then  $(C \cup C') \setminus \{x\}$  contains a set in  $\mathcal{C}$  containing  $y$ ;

# Fundamental circuits in matroids

## Lemma 11.5.2

*Let  $I \in \mathcal{I}(M)$ , and  $e \in E$ , then  $I \cup \{e\}$  contains at most one circuit in  $M$ .*

Proof.



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In general, let  $C(I, e)$  be the unique circuit associated with  $I \cup \{e\}$  (commonly called the **fundamental circuit** in  $M$  w.r.t.  $I$  and  $e$ ).



# Matroid Intersection Algorithm Idea

- Consider two matroids  $M_1 = (V, \mathcal{I}_1)$  and  $M_2 = (V, \mathcal{I}_2)$  and start with any  $I \in \mathcal{I}_1 \cap \mathcal{I}_2$ .

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  - Then  $\text{span}_1(I) = \text{span}_1(I - v_2 + v_3)$ .
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- If  $I + v_1 \notin \mathcal{I}_2$ ,  $\exists C_2(I, v_1)$  a circuit in  $M_2$ , and choosing  $v_2 \in C_2(I, v_1)$  s.t.  $v_2 \neq v_1$  leads to  $I + v_1 - v_2$  which (because  $\text{span}_2(I) = \text{span}_2(I + v_1 - v_2)$ ) is again independent in  $M_2$ .  
 $I + v_1 - v_2$  is also independent in  $M_1$ .
- Next choose a  $v_3 \in \text{span}_1(I) - \text{span}_1(I - v_2)$  to recover what was lost in  $I \cup \{v_1\}$  when we removed  $v_2$  from it.
- Then  $\text{span}_1(I) = \text{span}_1(I - v_2 + v_3)$ .
- Moreover, since  $I + v_1 \in \mathcal{I}_1$ ,  $v_1 \notin \text{span}_1(I)$ , so  
 $\text{span}_1(I + v_1) = \text{span}_1(I + v_1 - v_2 + v_3)$ .

# Matroid Intersection Algorithm Idea

- Consider two matroids  $M_1 = (V, \mathcal{I}_1)$  and  $M_2 = (V, \mathcal{I}_2)$  and start with any  $I \in \mathcal{I}_1 \cap \mathcal{I}_2$ .
- Consider some  $v_1 \notin \text{span}_1(I)$ , so that  $I + v_1 \in \mathcal{I}_1$ .
- If  $I + v_1 \in \mathcal{I}_2$ , then  $v_1$  is “augmenting”, and we can augment  $I$  to  $I + v_1$  and still be independent in both  $M_1$  and  $M_2$ .
- If  $I + v_1 \notin \mathcal{I}_2$ ,  $\exists C_2(I, v_1)$  a circuit in  $M_2$ , and choosing  $v_2 \in C_2(I, v_1)$  s.t.  $v_2 \neq v_1$  leads to  $I + v_1 - v_2$  which (because  $\text{span}_2(I) = \text{span}_2(I + v_1 - v_2)$ ) is again independent in  $M_2$ .  
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- Then  $\text{span}_1(I) = \text{span}_1(I - v_2 + v_3)$ .
- Moreover, since  $I + v_1 \in \mathcal{I}_1$ ,  $v_1 \notin \text{span}_1(I)$ , so  $\text{span}_1(I + v_1) = \text{span}_1(I + v_1 - v_2 + v_3)$ .
- But  $I + v_1 - v_2 + v_3$  might not be independent in  $M_2$  again, so we need to find an  $v_4 \in C_2(I + v_1 - v_2, v_3)$  to remove, and so on.



# Matroid Intersection Algorithm Idea

- Hopefully (eventually) we'll find an odd length sequence  $S = (v_1, v_2, \dots, v_s)$  such that we will be independent in both  $M_1$  and  $M_2$  and thus be one greater in size than  $I$ .

# Matroid Intersection Algorithm Idea

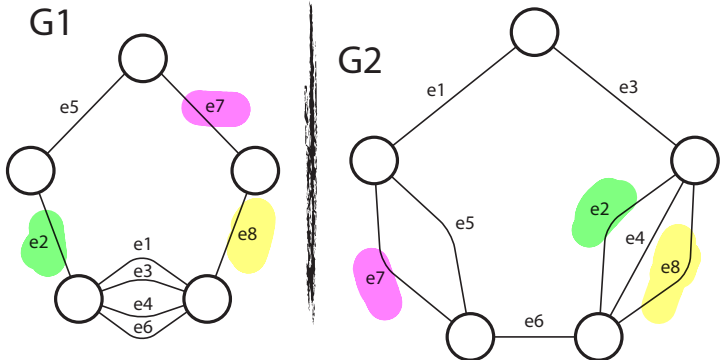
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- We will have  $v_i \notin I$  for  $i$  odd (will be shown in blue), and will have  $v_i \in I$  for  $i$  even (will be shown in green), while  $v \in I \setminus S$  will be shown in red.

# Matroid Intersection Algorithm Idea

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- We then replace  $I$  with  $I \oplus S$  (quite analogous to the bipartite matching case), and start again.

# Graphic Matroid Intersection Example

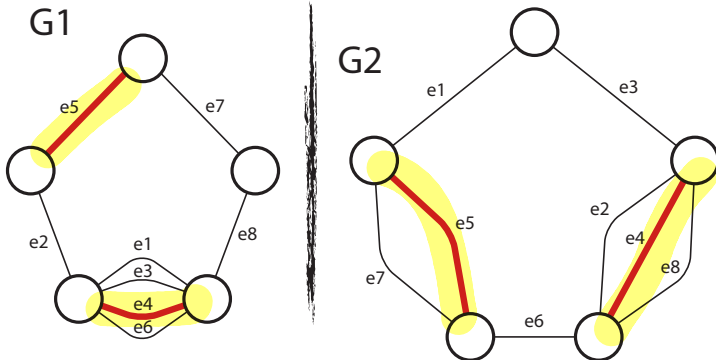
Consider the following two graph  $G_1 = (V_1, E)$  and  $G_2 = (V_2, E)$  and corresponding matroids  $M_1 = (E, \mathcal{I}_1)$  and  $M_2 = (E, \mathcal{I}_2)$ . Any edge is independent in both (an augmenting “sequence”) since a single edge can't create a circuit starting at  $I = \emptyset$ . We start with  $e_4$ .





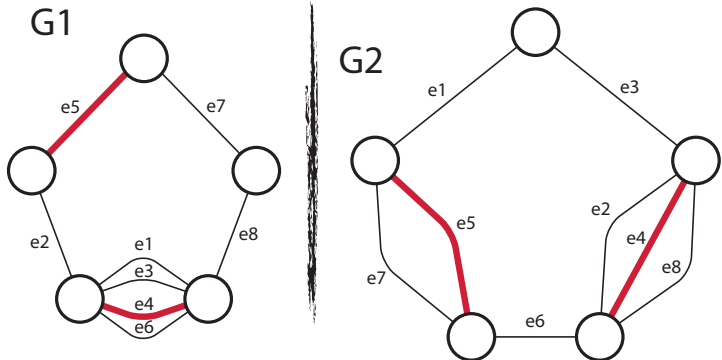
# Graphic Matroid Intersection Example

$e_5 \in E - \text{span}_1(\{e_4\})$ . Then, after  $I \leftarrow I + e_5$ , (i.e., when  $I = \{e_4, e_5\}$ ) we're still independent in  $M_2$ , but no further single edge additions possible w/o creating a circuit (why?).



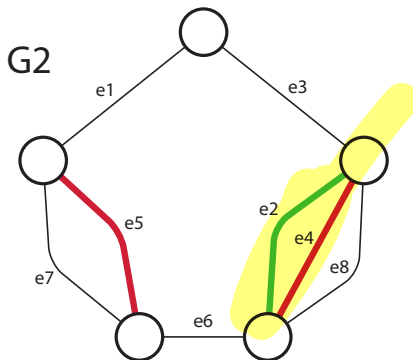
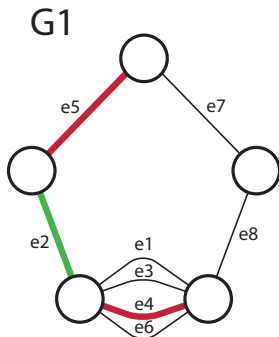
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# Graphic Matroid Intersection Example

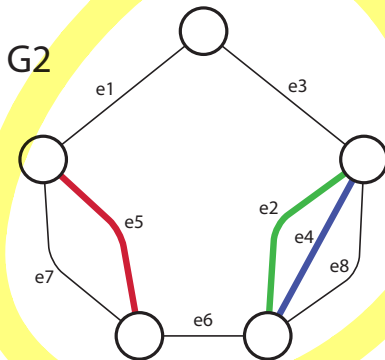
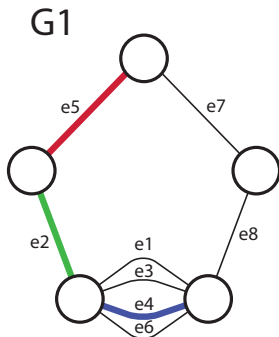
Augmenting sequence is green and blue edges (blue is already in  $I$ , green is new). We choose  $e_2 \in E - \text{span}_1(I)$ , but now  $I + e_2$  is not independent in  $M_2$ .





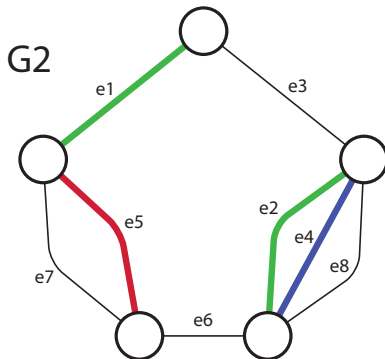
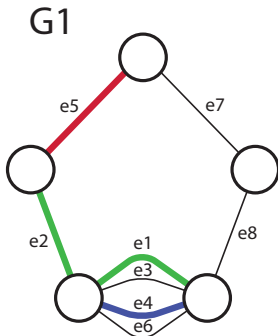
# Graphic Matroid Intersection Example

So there must exist  $C_2(I, e_2)$ . We choose  $e_4 \in C_2(I, e_2)$  to remove.



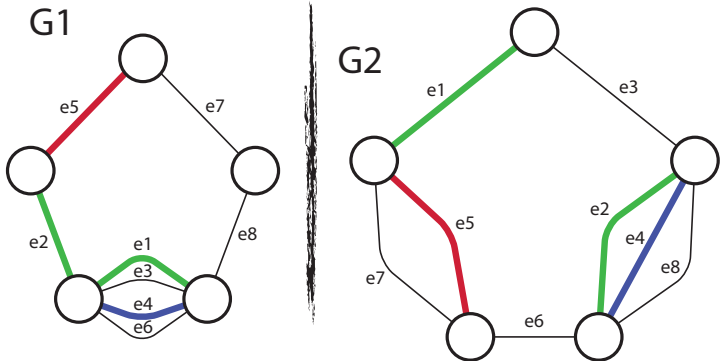
# Graphic Matroid Intersection Example

Next, we choose  $e_1 \in \text{span}_1(I) - \text{span}_1(I - e_4)$  to add.



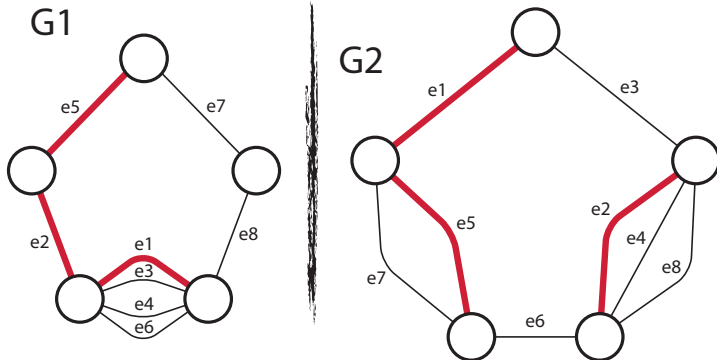
# Graphic Matroid Intersection Example

Next, we choose  $e_1 \in \text{span}_1(I) - \text{span}_1(I - e_4)$  to add. In this case, we not only have  $\text{span}_1(I + e_2) = \text{span}_1(I + e_2 - e_4 + e_1)$ , but we also have that  $(I + e_2 - e_4) + e_1 \in \mathcal{I}_2$ .



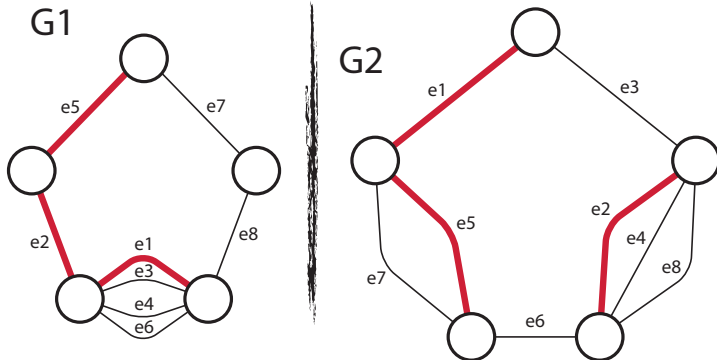
# Graphic Matroid Intersection Example

Removing blue and adding green leads to higher cardinality independent set in both matroids. This corresponds to doing  $I \leftarrow I \ominus S$  where  $S = (e_2, e_4, e_1)$  and  $I = \{e_4, e_5\}$ .



# Graphic Matroid Intersection Example

At this point, are any further augmenting sequences possible? **Exercise.**



# Alternating and Augmenting Sequences

- Let  $I$  be an **intersection** of two matroids  $M_1 = (E, \mathcal{I}_1)$  and  $M_2 = (E, \mathcal{I}_2)$  (i.e.,  $I \in \mathcal{I}_1 \cap \mathcal{I}_2$ ).

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- Let  $S = (e_1, e_2, \dots, e_s)$  be a sequence of distinct elements, where  $e_i \in E - I$  for  $i$  odd, and  $e_i \in I$  for  $i$  even, and let  $S_i = (e_1, e_2, \dots, e_i)$ . We say that  $S$  is an **alternating sequence** w.r.t.  $I$  if the following are true.

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  - 1  $I + e_1 \in \mathcal{I}_1$



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  - 1  $I + e_1 \in \mathcal{I}_1$
  - 2 For all even  $i$ ,  $\text{span}_2(I \ominus S_i) = \text{span}_2(I)$  which implies that  $I \ominus S_i \in \mathcal{I}_2$ .

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  - ①  $I + e_1 \in \mathcal{I}_1$
  - ② For all even  $i$ ,  $\text{span}_2(I \ominus S_i) = \text{span}_2(I)$  which implies that  $I \ominus S_i \in \mathcal{I}_2$ .
  - ③ For all odd  $i$ ,  $\text{span}_1(I \ominus S_i) = \text{span}_1(I + e_1)$ , and therefore  $I \ominus S_i \in \mathcal{I}_1$ .

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  - ③ For all odd  $i$ ,  $\text{span}_1(I \ominus S_i) = \text{span}_1(I + e_1)$ , and therefore  $I \ominus S_i \in \mathcal{I}_1$ .
- Lastly, if also,  $|S| = s$  is odd, and  $I \ominus S \in \mathcal{I}_2$ , then  $S$  is called an **augmenting sequence** w.r.t.  $I$ .

# Alternating and Augmenting Sequences

- If  $I$  admits an augmenting sequence  $S$ , then the above argument shows that  $I \ominus S$  is independent in  $M_1$ , independent in  $M_2$ , and also we have that  $|I| + 1 = |I \ominus S|$ .

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- Thus, by finding augmenting sequences, we can increase the size of the matroid intersection until we stop. Moreover, we have:

## Proposition 11.5.3

*If there is an augmenting sequence, then the intersection is not maximum.*

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## Proposition 11.5.3

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- We next wish to show that, if the intersection is not maximum, then there is an augmenting sequence.

# Border graphs

- We construct an auxiliary directed bipartite graph (**Border graph**)  $B(I) = (E \setminus I, I, Z)$ , relative to the current  $I$ , that will help us with this problem. The graph has only directed edges from  $E \setminus I$  to  $I$ , or from  $I$  back to  $E \setminus I$ .

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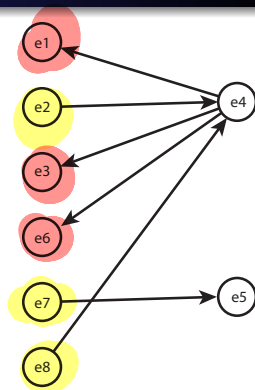
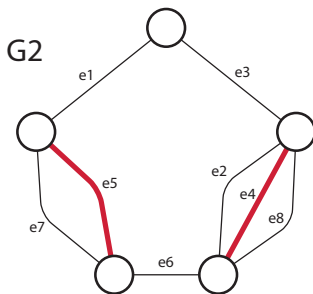
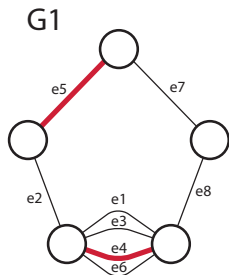
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# Border graphs

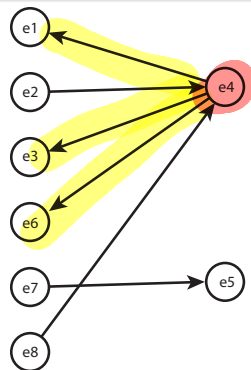
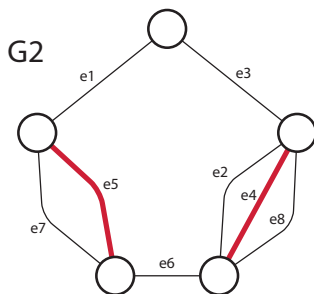
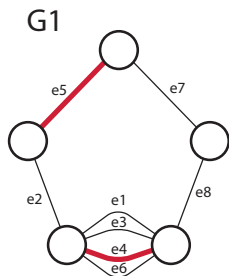
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# Border graph Example



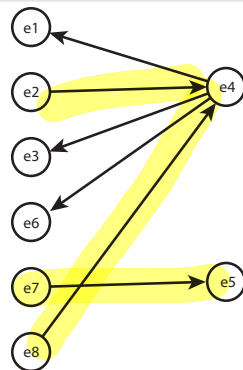
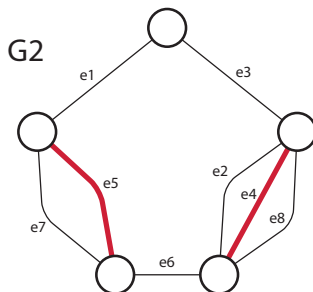
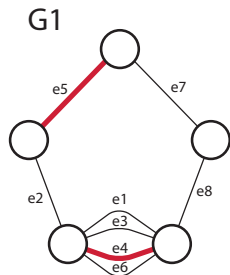
- $\{e_2, e_7, e_8\}$  are sources and  $\{e_1, e_3, e_6\}$  are sinks.  $I = \{e_4, e_5\}$ .  
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# Border graph Example



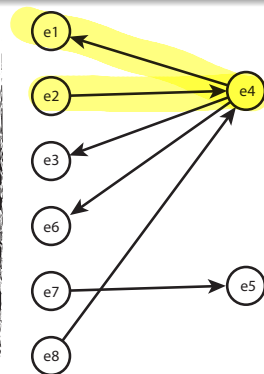
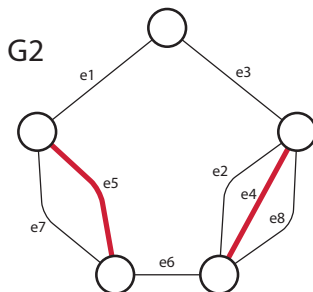
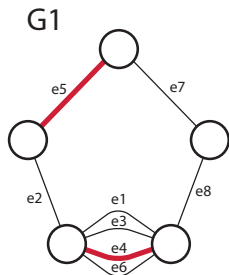
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- $C_1(I, e_1) \setminus \{e_1\} = C_1(I, e_3) \setminus \{e_3\} = C_1(I, e_6) \setminus \{e_6\} = e_4$ .

# Border graph Example



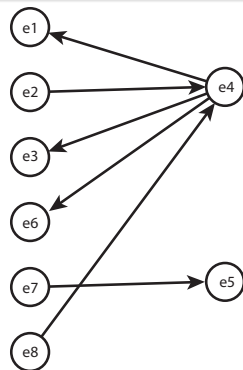
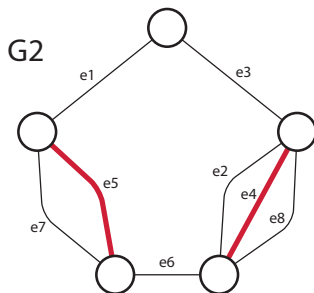
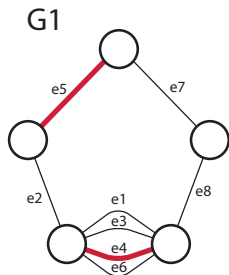
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- Augmenting sequences are  $(e_2, e_4, e_1)$ ,  $(e_2, e_4, e_3)$ , and  $(e_2, e_4, e_6)$ , all dipaths in the Border graph.

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# Identifying Augmenting Sequences

## Lemma 11.5.4

*If  $S$  is a source-sink path in  $B(I)$ , and there is no shorter source-sink path between the same source and sink (i.e., there are no short-cuts), then  $S$  is an augmenting sequence w.r.t.  $I$ .*

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## Lemma 11.5.5

*Let  $I$  and  $J$  be matroid intersections of  $M_1$  and  $M_2$  such that  $|I| + 1 = |J|$ . Then there exists a source-sink path  $S$  in  $B(I)$  where  $S \subseteq I \oplus J$ .*

# Identifying Augmenting Sequences

## Theorem 11.5.6

Let  $I_p$  and  $I_{p+1}$  be intersections of  $M_1$  and  $M_2$  with  $p$  and  $p+1$  elements respectively. Then there exists an augmenting sequence  $S \subseteq I_p \ominus I_{p+1}$  w.r.t.  $I_p$ .

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*For any intersection  $I$ , there exists a maximum cardinality intersection  $I^*$  such that  $\text{span}_1(I) \subseteq \text{span}_1(I^*)$  and  $\text{span}_2(I) \subseteq \text{span}_2(I^*)$ .*

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All this can be made to run in poly time.

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- Moreover, we want partition to be lexicographically maximum, that is  $|I_1|$  is maximum,  $|I_2|$  is maximum given  $|I_1|$ , and so on.

# Matroid Partition Problem

## Theorem 11.6.1

Let  $M_i$  be a collection of  $k$  matroids as described. Then, a set  $I \subseteq E$  can be partitioned into  $k$  subsets  $I_i, i = 1 \dots k$  where  $I_i \in \mathcal{I}_i$  is independent in matroid  $i$ , if and only if, for all  $A \subseteq I$

$$|A| \leq \sum_{i=1}^k r_i(A) \quad (11.4)$$

where  $r_i$  is the rank function of  $M_i$ .

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- But considering vector of all ones  $\mathbf{1} \in \mathbb{R}_+^E$ , this is the same as

$$\frac{1}{k}|A| = \frac{1}{k}\mathbf{1}(A) \leq r(A) \quad \forall A \subseteq E \quad (11.6)$$

# Matroid Partition Problem

- Recall definition of matroid polytope

$$P_r^+ = \{y \in \mathbb{R}_+^E : y(A) \leq r(A) \text{ for all } A \subseteq E\} \quad (11.7)$$

# Matroid Partition Problem

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- Then we see that this special case of the matroid partition problem is just testing if  $\frac{1}{k}\mathbf{1} \in P_r^+$ , a problem of testing the membership in matroid polyhedra.

# Review

- The next two slides from respectively from Lecture 9 and Lecture 8.

# Polymatroidal polyhedron (or a “polymatroid”)

## Definition 11.7.4 (polymatroid)

A **polymatroid** is a compact set  $P \subseteq \mathbb{R}_+^E$  satisfying

- ①  $0 \in P$
  - ② If  $y \leq x \in P$  then  $y \in P$  (called **down monotone**).
  - ③ For every  $x \in \mathbb{R}_+^E$ , any maximal vector  $y \in P$  with  $y \leq x$  (i.e., any  $P$ -basis of  $x$ ), has the same component sum  $y(E)$
- Vectors within  $P$  (i.e., any  $y \in P$ ) are called **independent**, and any vector outside of  $P$  is called **dependent**.
  - Since all  $P$ -bases of  $x$  have the same component sum, if  $\mathcal{B}_x$  is the set of  $P$ -bases of  $x$ , then  $\text{rank}(x) = y(E)$  for any  $y \in \mathcal{B}_x$ .



# Maximum weight independent set via greedy weighted rank

## Theorem 11.7.6

Let  $M = (V, \mathcal{I})$  be a matroid, with rank function  $r$ , then for any weight function  $w \in \mathbb{R}_+^V$ , there exists a chain of sets  $U_1 \subset U_2 \subset \dots \subset U_n \subseteq V$  such that

$$\max \{w(I) | I \in \mathcal{I}\} = \sum_{i=1}^n \lambda_i r(U_i) \quad (11.19)$$

where  $\lambda_i \geq 0$  satisfy

$$w = \sum_{i=1}^n \lambda_i \mathbf{1}_{U_i} \quad (11.20)$$

# Polymatroidal polyhedron and greedy

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# Polymatroidal polyhedron and greedy

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- Recall greedy algorithm: Set  $A = \emptyset$ , and repeatedly choose  $y \in E \setminus A$  such that  $A \cup \{y\} \in \mathcal{I}$  with  $w(y)$  as large as possible, stopping when no such  $y$  exists.

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- For a matroid, we saw that set system  $(E, \mathcal{I})$  is a matroid iff for each weight function  $w \in \mathbb{R}_+^E$ , the greedy algorithm leads to a set  $I \in \mathcal{I}$  of maximum weight  $w(I)$ .

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- Stated succinctly, considering  $\max \{w(I) : I \in \mathcal{I}\}$ , then  $(E, \mathcal{I})$  is a matroid iff greedy works for this maximization.

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- Can we also characterize a **polymatroid** in this way?
- That is, if we consider  $\max \{wx : x \in P_f^+\}$ , where  $P_f^+$  represents the “independent vectors”, is it the case that  $P_f^+$  is a polymatroid iff greedy works for this maximization?

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- That is, if we consider  $\max \{wx : x \in P_f^+\}$ , where  $P_f^+$  represents the “independent vectors”, is it the case that  $P_f^+$  is a polymatroid iff greedy works for this maximization?
- Can we even relax things so that  $w \in \mathbb{R}^E$ ?



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- Let  $k + 1$  be the first point (if any) at which we are non-positive, i.e.,  $w(e_k) > 0$  and  $0 \geq w(e_{k+1})$ .

*That is, we have*

$$w(e_1) \geq w(e_2) \geq \dots \geq w(e_k) > 0 \geq w(e_{k+1}) \geq \dots \geq w(e_m) \quad (11.8)$$

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- Let  $k + 1$  be the first point (if any) at which we are non-positive, i.e.,  $w(e_k) > 0$  and  $0 \geq w(e_{k+1})$ .
- Next define partial accumulated sets  $E_i$ , for  $i = 0 \dots m$ , we have w.r.t. the above sorted order:

$$E_i \stackrel{\text{def}}{=} \{e_1, e_2, \dots, e_i\} \quad (11.9)$$

(note  $E_0 = \emptyset$ ,  $f(E_0) = 0$ , and  $E$  and  $E_i$  is always sorted w.r.t  $w$ ).

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- The greedy solution is the vector  $x \in \mathbb{R}_+^E$  with elements defined as:

$$x(e_1) \stackrel{\text{def}}{=} f(E_1) = f(e_1) = f(e_1|E_0) = f(e_1|\emptyset) \quad (11.10)$$

$$x(e_i) \stackrel{\text{def}}{=} f(E_i) - f(E_{i-1}) = f(e_i|E_{i-1}) \text{ for } i = 2 \dots k \quad (11.11)$$

$$x(e_i) \stackrel{\text{def}}{=} 0 \text{ for } i = k + 1 \dots m = |E| \quad (11.12)$$

## Some Intuition: greedy and gain

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- Hence, for the largest value of  $w$  (namely  $w(e_1)$ ), we use for  $x(e_1)$  the largest possible gain value of  $e_1$  (namely  $f(e_1|\emptyset) \geq f(e_1|A)$  for any  $A \subseteq E \setminus \{e_1\}$ ).



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- For the next largest value of  $w$  (namely  $w(e_2)$ ), we use for  $x(e_2)$  the next largest gain value of  $e_2$  (namely  $f(e_2|e_1)$ ). This still ensures (as we will soon see in Theorem 11.7.1) that the resulting  $x \in P_f$ .

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- This process continues, using the next largest possible gain of  $e_i$  for  $x(e_i)$  while ensuring we do not leave the polytope, given the values we've already chosen for  $x(e_{i'})$  for  $i' < i$ .

# Polymatroidal polyhedron and greedy

## Theorem 11.7.1

*The vector  $x \in \mathbb{R}_+^E$  as previously defined using the greedy algorithm maximizes  $wx$  over  $P_f^+$ .*

## Proof.

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## Proof.

- Consider the LP strong duality equation:

$$\max(w x : x \in P_f^+) = \min\left(\sum_{A \subseteq E} y_A f(A) : y \in \mathbb{R}_+^{2^E}, \sum_{A \subseteq E} y_A \mathbf{1}_A \geq w\right) \quad (11.13)$$

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- Define the following vector  $y \in \mathbb{R}_+^{2^E}$  as

$$y_{E_i} \leftarrow w(e_i) - w(e_{i+1}) \text{ for } i = 1 \dots (m-1), \quad (11.14)$$

$$y_E \leftarrow w(e_m), \text{ and} \quad (11.15)$$

$$y_A \leftarrow 0 \text{ otherwise} \quad (11.16)$$

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- Order  $A = (a_1, a_2, \dots, a_k)$  based on order  $(e_1, e_2, \dots, e_m)$ .

		$a_1$		$a_2$	$a_3$			$a_4$		$a_5$	$\dots$	
$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$	$e_8$	$e_9$	$e_{10}$	$e_{11}$	$\dots$	$e_m$

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# Polymatroidal polyhedron and greedy

## Proof.

- We first will see that greedy  $x \in P_f^+$  (that is  $x(A) \leq f(A), \forall A$ ).
- Order  $A = (a_1, a_2, \dots, a_k)$  based on order  $(e_1, e_2, \dots, e_m)$ .

		$a_1$		$a_2$	$a_3$			$a_4$		$a_5$	$\dots$	
$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$	$e_8$	$e_9$	$e_{10}$	$e_{11}$	$\dots$	$e_m$

- Define  $e^{-1} : E \rightarrow \{1, \dots, m\}$  so that  $e^{-1}(e_i) = i$ .

*This means that  $\forall j \leq k$*

$$\{a_1, a_2, \dots, a_j\} \subseteq \{e_1, e_2, \dots, e_{e^{-1}(a_j)}\} \quad (11.17)$$

*and*

$$\{a_1, a_2, \dots, a_{j-1}\} \subseteq \{e_1, e_2, \dots, e_{e^{-1}(a_j)-1}\} \quad (11.18)$$

*Also recall matlab notation:  $a_{1:j} \equiv \{a_1, a_2, \dots, a_j\}$ .*

*E.g., with  $j = 4$  we get  $e^{-1}(a_4) = 9$ , and*

$$\{a_1, a_2, a_3, a_4\} \subseteq \{e_1, e_2, \dots, e_9\} \quad (11.19)$$



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- Define  $e^{-1} : E \rightarrow \{1, \dots, m\}$  so that  $e^{-1}(e_i) = i$ .
- Then, we have  $x \in P_f^+$  since:

$$f(A) = \sum_{i=1}^k f(a_i | a_{1:i-1}) \quad (11.17)$$

$$\geq \sum_{i=1}^k f(a_i | e_{1:e^{-1}(a_i)-1}) \quad (11.18)$$

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- clearly,  $y \geq 0$ ;
- also, considering  $y$  component wise, for any  $i$ , we have that

$$\sum_{A:e_i \in A} y_A = \sum_{j \geq i} y_{E_j} = \sum_{j=i}^{m-1} (w(e_j) - w(e_{j+1})) + w(e_m) = w(e_i)$$

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- Now optimality for  $x$  and  $y$  follows from strong duality, i.e.:

$$\begin{aligned} wx &= \sum_{e \in E} w(e)x(e) = \sum_{e \in E} w(e)f(e_i | E_{i-1}) = \sum_{i=1}^m w(e_i) \left( f(E_i) - f(E_{i-1}) \right) \\ &= \sum_{i=1}^{n-1} f(E_i) \left( w(e_i) - w(e_{i+1}) \right) + f(E)w(e_m) = \sum_{A \subseteq E} y_A f(A) \end{aligned}$$

...

# Polymatroidal polyhedron and greedy

## Proof.

- The penultimate equality (in Eq. 11.2) follows via **Abel summation**:

$$wx = \sum_{i=1}^m w_i x_i \quad (11.20)$$

$$= \sum_{i=1}^m w_i (f(E_i) - f(E_{i-1})) \quad (11.21)$$

$$= \sum_{i=1}^m w_i f(E_i) - \sum_{i=1}^{m-1} w_{i+1} f(E_i) \quad (11.22)$$

$$= w_m f(E_m) + \sum_{i=1}^{m-1} (w_i - w_{i+1}) f(E_i) \quad (11.23)$$



# Polymatroidal polyhedron and greedy

## Theorem 11.7.1

*Conversely, suppose  $P_f^+$  is a polytope of form  $P_f^+ = \{x \in \mathbb{R}_+^E : x(A) \leq f(A), \forall A \subseteq E\}$ , then the greedy solution to  $\max(w x : x \in P)$  is optimum only if  $f$  is submodular.*

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- Note, then we have  $A \cap B = \{e_1, \dots, e_k\} = E_k$ , and  $A \cup B = E_q$ .

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- Define  $w \in \{0, 1\}^m$  as:

$$w \stackrel{\text{def}}{=} \sum_{i=1}^q \mathbf{1}_{e_i} = \mathbf{1}_{A \cup B} \quad (11.24)$$

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- Suppose optimum solution  $x$  is given by the greedy procedure.

# Polymatroidal polyhedron and greedy

Proof.

- Then

$$\sum_{i=1}^k x_i = f(E_1) + \sum_{i=2}^k (f(E_i) - f(E_{i-1})) = f(E_k) = f(A \cap B) \quad (11.25)$$

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# Polymatroidal polyhedron and greedy

Proof.

- Thus, we have

$$x(B) = \sum_{i \in 1, \dots, k, p+1, \dots, q} x_i = \sum_{i: e_i \in B} x_i = f(A \cup B) + f(A \cap B) - f(A) \quad (11.28)$$

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- But given that the greedy algorithm gives the optimal solution to  $\max\{wx : x \in P_f^+\}$ , we have that  $x \in P_f^+$  and thus  $x(B) \leq f(B)$ .

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- Thus,

$$x(B) = f(A \cup B) + f(A \cap B) - f(A) = \sum_{i: e_i \in B} x_i \leq f(B) \quad (11.29)$$

ensuring the submodularity of  $f$ , since  $A$  and  $B$  are arbitrary.



# Polymatroidal polyhedron and greedy

- Thus, restating the above results into a single complete theorem, we have a result very similar to what we saw for matroids (i.e., Theorem 8.6.1)

## Theorem 11.7.1

*If  $f : 2^E \rightarrow \mathbb{R}_+$  is given, and  $P$  is a polytope in  $\mathbb{R}_+^E$  of the form  $P = \{x \in \mathbb{R}_+^E : x(A) \leq f(A), \forall A \subseteq E\}$ , then the greedy solution to the problem  $\max(w x : x \in P)$  is  $\forall w$  optimum iff  $f$  is monotone non-decreasing submodular (i.e., iff  $P$  is a polymatroid).*

# Multiple Polytopes associated with arbitrary $f$

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*Note that due to constraint  $x(\emptyset) \leq f(\emptyset)$ , we must have  $f(\emptyset) \geq 0$  since if not (i.e., if  $f(\emptyset) < 0$ ), then  $P_f^+$  doesn't exist.*

*Another form of normalization can do is:*

$$f'(A) = \begin{cases} f(A) & \text{if } A \neq \emptyset \\ 0 & \text{if } A = \emptyset \end{cases} \quad (11.30)$$

*This preserves submodularity due to  $f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$ , and if  $A \cap B = \emptyset$  then r.h.s. only gets smaller when  $f(\emptyset) \geq 0$ .*

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- We can define several polytopes:

$$P_f = \{x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E\} \quad (11.30)$$

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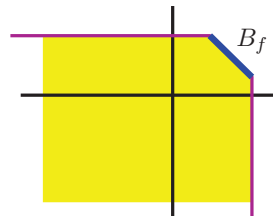
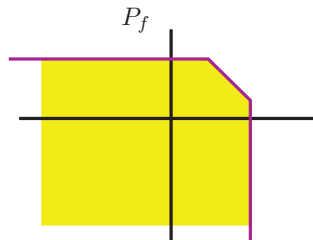
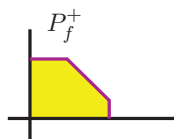
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# Multiple Polytopes associated with $f$

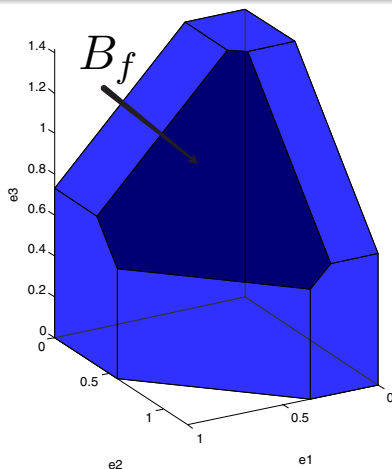
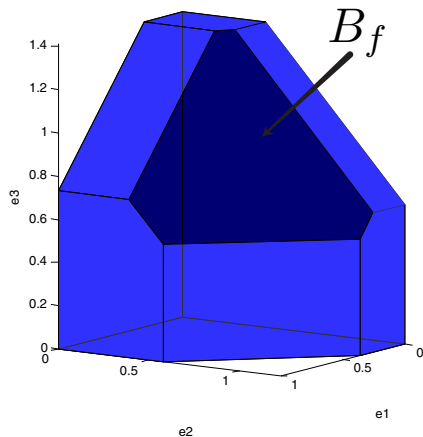


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# Base Polytope in 3D



$$P_f = \{x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E\} \quad (11.36)$$

$$B_f = P_f \cap \{x \in \mathbb{R}^E : x(E) = f(E)\} \quad (11.37)$$

# A polymatroid function's polyhedron is a polymatroid.

## Theorem 11.8.1

*Let  $f$  be a submodular function defined on subsets of  $E$ . For any  $x \in \mathbb{R}^E$ , we have:*

$$\max (y(E) : y \leq x, y \in P_f) = \min (x(A) + f(E \setminus A) : A \subseteq E) \quad (11.38)$$

If we take  $x$  to be zero, we get:

## Corollary 11.8.2

*Let  $f$  be a submodular function defined on subsets of  $E$ .  $x \in \mathbb{R}^E$ , we have:*

$$\max (y(E) : y \leq 0, y \in P_f) = \min (f(A) : A \subseteq E) \quad (11.39)$$

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- Moreover, in polymatroidal case, since the greedy constructed  $x$  has  $x(E) = f(E)$ , we have that the greedy  $x \in B_f$ .
- In fact, we next will see that the greedy  $x$  is a vertex of  $B_f$ .

# Polymatroid extreme points

- The greedy algorithm does more than solve  $\max(wx : x \in P_f^+)$ . We can use it to generate vertices of polymatroidal polytopes.

# Polymatroid extreme points

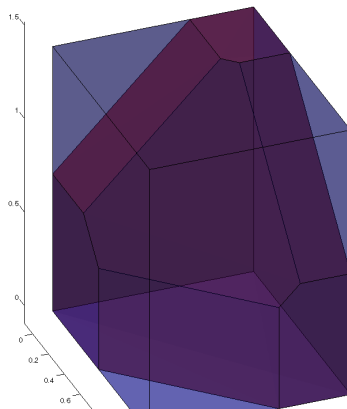
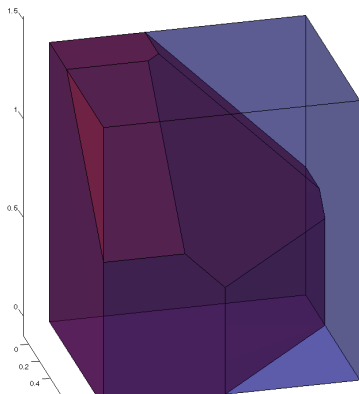
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- We formalize this next:

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$$x(e_1) = f(E_1) = f(e_1) \quad (11.41)$$

$$x(e_j) = f(E_j) - f(E_{j-1}) = f(e_j | E_{j-1}) \text{ for } 2 \leq j \leq i \quad (11.42)$$

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- An **extreme point** of  $P_f$  is a point that is not a convex combination of two other distinct points in  $P_f$ . Equivalently, an extreme point corresponds to setting certain inequalities in the specification of  $P_f$  to be equalities, so that there is a unique single point solution.

# Polymatroid extreme points

## Theorem 11.9.1

*For a given ordering  $E = (e_1, \dots, e_m)$  of  $E$  and a given  $E_i$  and  $x$  generated by  $E_i$  using the greedy procedure, then  $x$  is an extreme point of  $P_f$*

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- We already saw that  $x \in P_f$  (Theorem 11.7.1).
- To show that  $x$  is an extreme point of  $P_f$ , note that it is the unique solution of the following system of equations

$$x(E_j) = f(E_j) \text{ for } 1 \leq j \leq i \leq m \quad (11.44)$$

$$x(e) = 0 \text{ for } e \in E \setminus E_i \quad (11.45)$$

There are  $i \leq m$  equations and  $i \leq m$  unknowns, and simple Gaussian elimination gives us back the  $x$  constructed via the Greedy algorithm!!

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- Also, since  $x \in P_f$ , for each  $i$ , we see that,

$$x(E_j) = f(E_j) \quad \text{for } 1 \leq j \leq i \quad (11.46)$$

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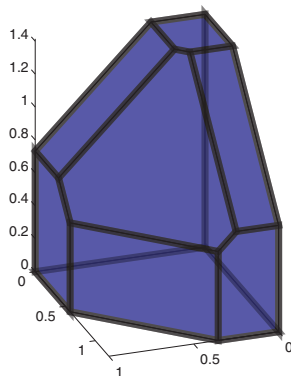
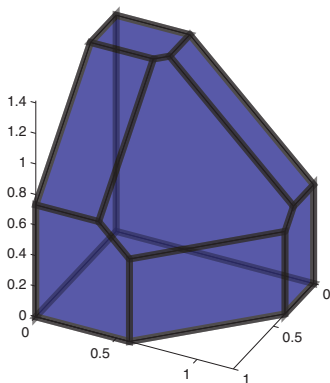
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- Thus, the greedy procedure provides a modular function lower bound on  $f$  that is tight on all points  $E_i$  in the order. This can be useful in its own right.

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some examples





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- Moreover, we have (and will ultimately prove)

## Corollary 11.9.2

*If  $x$  is an extreme point of  $P_f$  and  $B \subseteq E$  is given such that  $\text{supp}(x) = \{e \in E : x(e) \neq 0\} \subseteq B \subseteq \cup(A : x(A) = f(A)) = \text{sat}(x)$ , then  $x$  is generated using greedy by some ordering of  $B$ .*

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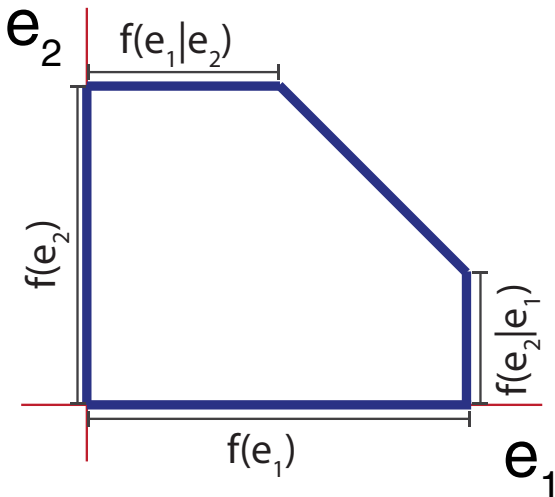
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- Thus,  $\text{cl}(x)$  is a tight set.
- Also,  $\text{supp}(x) = \{e \in E : x(e) \neq 0\}$  is called the support of  $x$ .
- For arbitrary  $x$ ,  $\text{supp}(x)$  is not necessarily tight, but for an extreme point,  $\text{supp}(x)$  is.

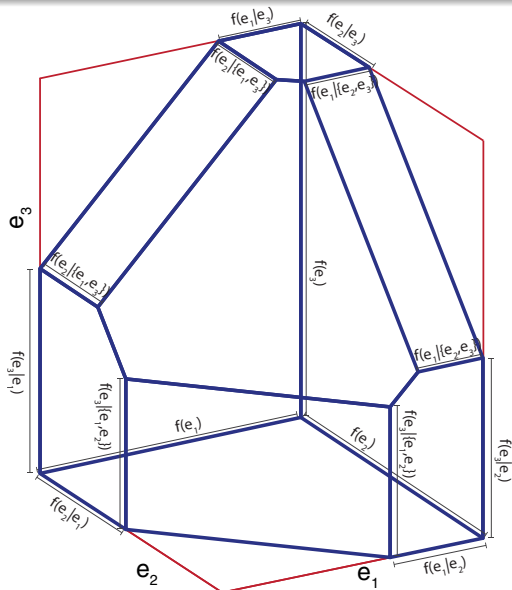
# Polymatroid with labeled edge lengths

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# Intuition: why greedy works with polymatroids

- Given  $w$ , the goal is to find  $x = (x(e_1), x(e_2))$  that maximizes  $x^T w = x(e_1)w(e_1) + x(e_2)w(e_2)$ .
- If  $w(e_2) > w(e_1)$  the upper extreme point indicated maximizes  $x^T w$  over  $x \in P_f^+$ .
- If  $w(e_2) < w(e_1)$  the lower extreme point indicated maximizes  $x^T w$  over  $x \in P_f^+$ .

