

Submodular Functions, Optimization, and Applications to Machine Learning

— Fall Quarter, Lecture 3 —

http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563_spring_2018/

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$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$$

$$-f(A) + 2f(C) + f(B) \quad -f(A) + f(C) + f(B) \quad -f(A \cap B)$$



Cumulative Outstanding Reading

- Read chapter 1 from Fujishige's book.

Class Road Map - EE563

- L1(9/30): Motivation, Applications, Definitions, Properties
- L2(10/5): Sums concave(modular), uses (diversity/costs, feature selection), information theory
- L3(10/7): Monge, More Definitions, Graph and Combinatorial Examples, Matrix Rank, Properties
- L4(10/12):
- L5(10/14):
- L6(10/19):
- L7(10/21):
- L8(10/26):
- L9(10/28):
- L10(11/2):
- L11(11/4):
- L12(11/9):
- L-(11/11): Veterans Day, Holiday
- L13(11/16):
- L14(11/18):
- L15(11/23):
- L16(11/25):
- L17(11/30):
- L18(12/2):
- L19(12/7):
- L20(12/9): maximization.

Last day of instruction, Fri. Dec 11th. Finals Week: Dec 12-18, 2020

Two Equivalent Submodular Definitions

Definition 3.2.1 (submodular concave)

A function $f : 2^V \rightarrow \mathbb{R}$ is **submodular** if for any $A, B \subseteq V$, we have that:

$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B) \quad (3.7)$$

An alternate and (as we will soon see) equivalent definition is:

Definition 3.2.2 (diminishing returns)

A function $f : 2^V \rightarrow \mathbb{R}$ is **submodular** if for any $A \subseteq B \subseteq V$, and $v \in V \setminus B$, we have that:

$$f(A \cup \{v\}) - f(A) \geq f(B \cup \{v\}) - f(B) \quad (3.8)$$

- The incremental “value”, “gain”, or “cost” of v decreases (diminishes) as the context in which v is considered grows from A to B .
- Gain notation: Define $f(v|A) \triangleq f(A + v) - f(A)$. Then function f is submodular if $f(v|A) \geq f(v|B)$ for all $A \subseteq B \subseteq V \setminus \{v\}$, $v \in V$.

Two Equivalent Supermodular Definitions

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Definition 3.2.2 (supermodular (improving returns))

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- Incremental “value”, “gain”, or “cost” of v increases (improves) as the context in which v is considered grows from A to B .
- A function f is submodular iff $-f$ is supermodular.
- If f both submodular and supermodular, then f is said to be **modular**, and $f(A) = c + \sum_{a \in A} \bar{f}(a)$ for some \bar{f} (often $c = 0$).

Monge Matrices

- $m \times n$ matrices $C = [c_{ij}]_{ij}$ are called Monge matrices if they satisfy the **Monge property**, namely:

$$c_{ij} + c_{rs} \leq c_{is} + c_{rj} \quad (3.1)$$

for all $1 \leq i < r \leq m$ and $1 \leq j < s \leq n$.

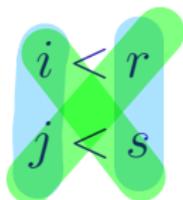
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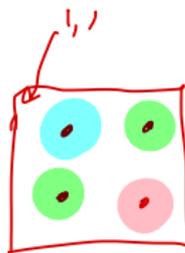
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- Lined up indices

$$i < r$$

$$j < s$$



$$(3.2)$$

$$(3.3)$$

- Equivalently, for all $1 \leq i, r \leq m$, $1 \leq s, j \leq n$,

$$c_{\min(i,r), \min(s,j)} + c_{\max(i,r), \max(s,j)} \leq c_{is} + c_{rj} \quad (3.4)$$

Monge Matrices Visuals

- Consider a non-negative matrix $D = (d_{i,j})$ of order $m \times n$ and form matrix $C = (c_{i,j})$ with $c_{i,j}$ th entry, $1 \leq i \leq m$, $1 \leq j \leq n$:

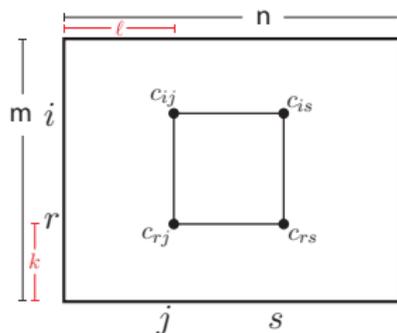
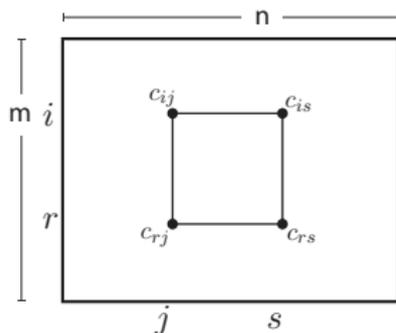
$$c_{ij} = \sum_{k=i}^m \sum_{\ell=1}^j d_{k,\ell} \quad (3.5)$$

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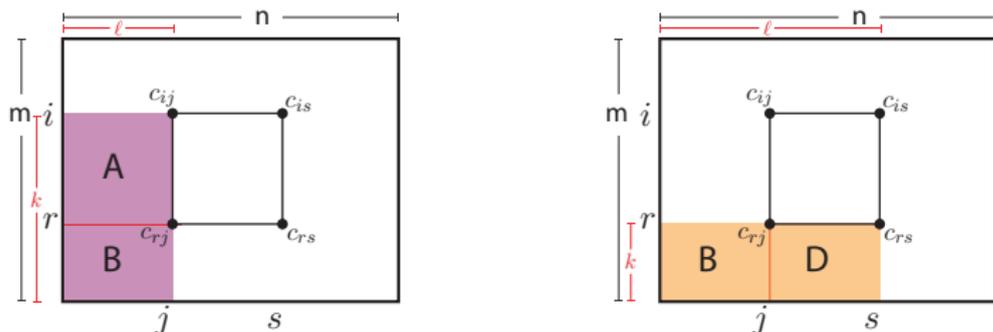


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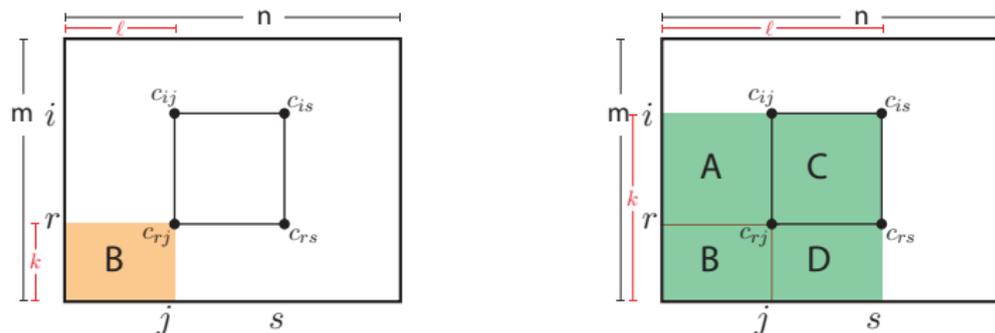
$$c_{ij} = A + B, \quad c_{rs} = B + D, \quad c_{rj} = B, \quad c_{is} = A + B + C + D.$$

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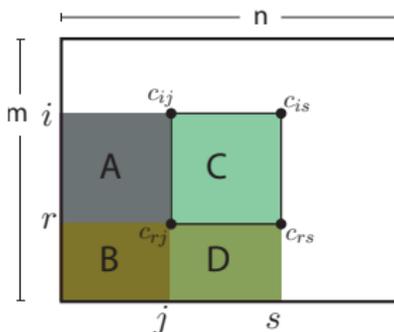
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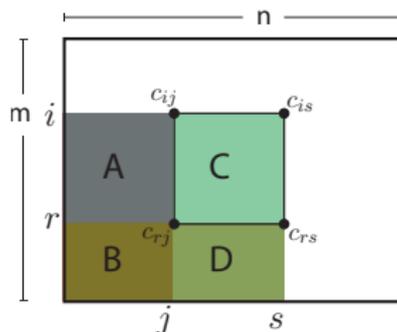
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$$c_{ij} = A + B, \quad c_{rs} = B + D, \quad c_{rj} = B, \quad c_{is} = A + B + C + D.$$

- Then, $c_{ij} + c_{rs} < c_{is} + c_{rj}$. *if $C > 0$.*

Monge Matrices, where useful

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- Example, **Hitchcock transportation problem**: Given $m \times n$ cost matrix $C = [c_{ij}]_{ij}$, a non-negative supply vector $a \in \mathbb{R}_+^m$, a non-negative demand vector $b \in \mathbb{R}_+^n$ with $\sum_{i=1}^m a(i) = \sum_{j=1}^n b_j$, we wish to optimally solve the following linear program:

$$\begin{array}{ll} \text{minimize} & \sum_{i=1}^m \sum_{j=1}^n c_{ij} x_{ij} \\ X \in \mathbb{R}^{m \times n} & \end{array} \quad (3.6)$$

$$\text{subject to} \quad \sum_{i=1}^m x_{ij} = b_j \quad \forall j = 1, \dots, n \quad (3.7)$$

$$\sum_{j=1}^n x_{ij} = a_i \quad \forall i = 1, \dots, m \quad (3.8)$$

$$x_{i,j} \geq 0 \quad \forall i, j \quad (3.9)$$

Monge Matrices, Hitchcock transportation

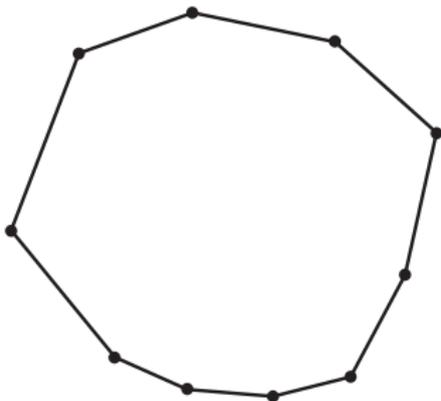
C

Producers, Sources, or Supply	a_1 2	0	1	3	3
	a_2 1	1	4	7	10
	a_3 5	0	4	9	14
		3	2	1	2
		b_1	b_2	b_3	b_4
		Consumers, Sinks, or Demand			

- Solving the linear program can be done easily and optimally using the “North-West Corner Rule” (a 2D greedy-like approach starting at top-left and moving down or right) in only $O(m + n)$ if the matrix C is Monge!

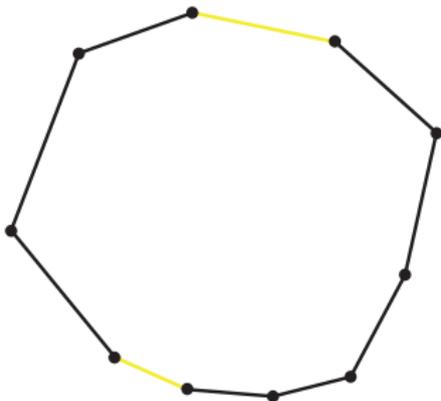
Monge Matrices and Convex Polygons

- Can generate a Monge matrix from a convex polygon - delete two segments, then separately number vertices on each chain. Distances c_{ij} satisfy Monge property (or quadrangle inequality).



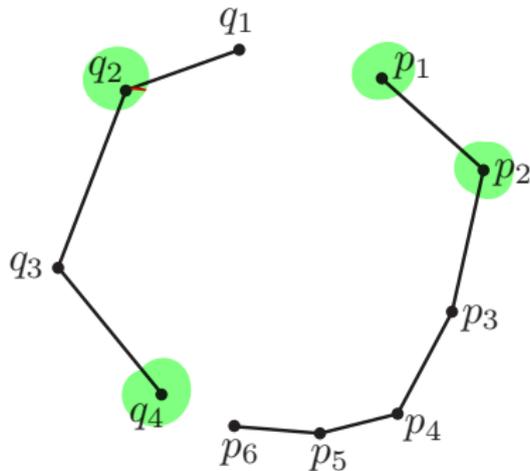
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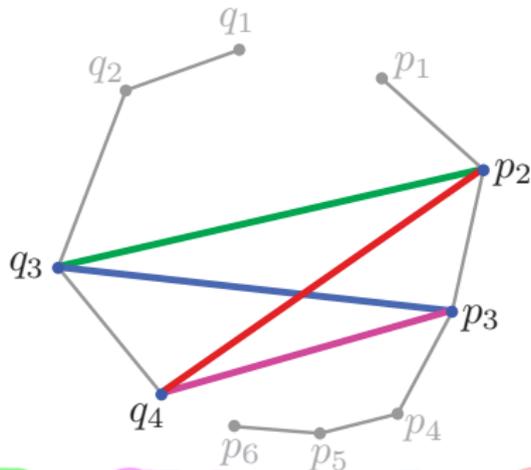
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$$d(q_3, p_2) + d(q_4, p_3) \leq d(q_4, p_2) + d(q_3, p_3) \quad (3.10)$$

To transport unit quantities from locations q_3 and q_4 to locations p_2 and p_3 ; to minimize total distance traveled, routes from q_3 and q_4 must not intersect.

Monge Matrices and Submodularity

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- We may define submodularity as: for all $x, y \in \{0, 1, \dots, K\}^V$, we have

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V = {v1, v2}

$$c_{12} + c_{21} \geq c_{11} + c_{22} \quad K=1$$

$$f(x) + f(y) \geq f(x \vee y) + f(x \wedge y) \quad (3.11)$$

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- With $|V| = 2$, and $K + 1$ the side-dimension of the matrix, we get a Monge property (on square matrices).
- Non square: $f : \{0, 1, \dots, K_1\} \times \{0, 1, \dots, K_2\} \rightarrow \mathbb{R}$. $\Rightarrow c_{ij}$

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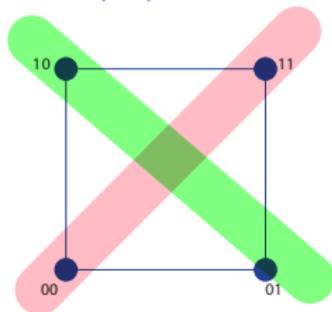
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The Submodular Square, and Hypercube Vertices

We can test submodularity via values on vertices of hypercube.

Example: with $|V| = n = 2$, this is
easy:

$$K=2$$

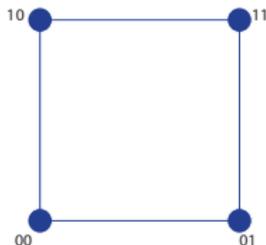


2D
hypercube

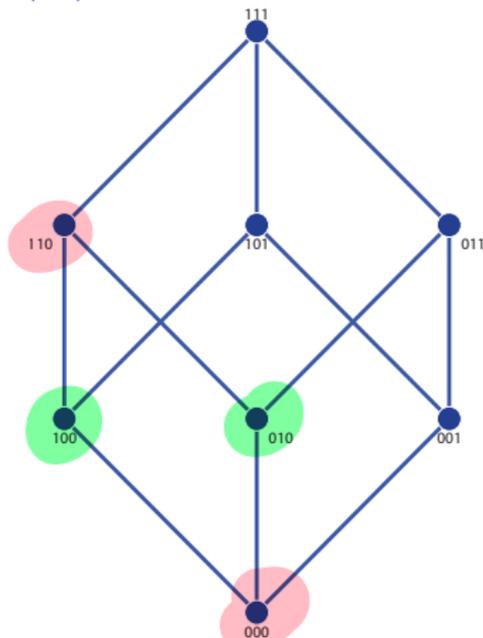
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With $|V| = n = 3$, a bit harder.

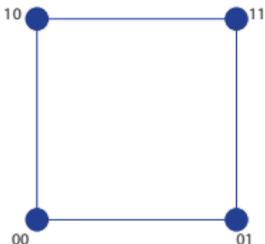


$$\begin{aligned}
 & f(100) + f(010) \\
 & \geq f((100) \vee (010)) \\
 & \quad + f((100) \wedge (010)) \\
 & = f(110) + f(000)
 \end{aligned}$$

The Submodular Square, and Hypercube Vertices

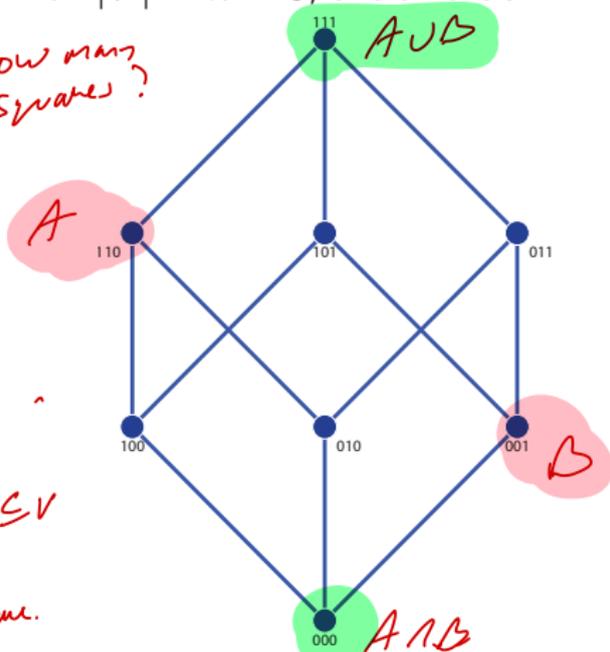
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$$100 \vee 011 = 111$$

How many squares?



For each $A, B \subseteq V$

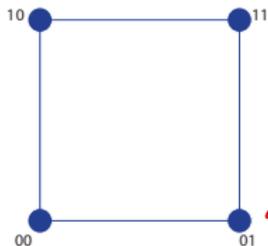
Each inequality is for square.

How many inequalities of form $f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$?

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$A \cup B$

$A \cap B$

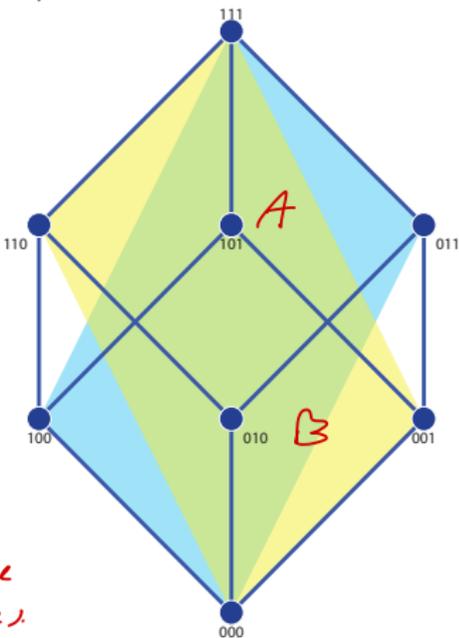
$$f(x+i) + f(x+j) \geq f(x+i+j) + f(x)$$

A
 B
 $A \cup B$

\therefore to verify submodularity when $|V|=3$, need to check at most 9 inequalities

claim: need only check 6 inequalities, the 6 cube faces.

With $|V| = n = 3$, a bit harder.



9 unique squares.

How many inequalities of form $f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$?

Subadditive Definitions

Definition 3.4.1 (subadditive)

A function $f : 2^V \rightarrow \mathbb{R}$ is subadditive if for any $A, B \subseteq V$, we have that:

$$f(A) + f(B) \geq f(A \cup B) \quad (3.12)$$

This means that the “whole” is less than the sum of the parts.

Two Equivalent Supermodular Definitions

Definition 3.4.1 (supermodular)

A function $f : 2^V \rightarrow \mathbb{R}$ is **supermodular** if for any $A, B \subseteq V$, we have that:

$$f(A) + f(B) \leq f(A \cup B) + f(A \cap B) \quad (3.7)$$

Definition 3.4.2 (supermodular (improving returns))

A function $f : 2^V \rightarrow \mathbb{R}$ is **supermodular** if for any $A \subseteq B \subset V$, and $v \in V \setminus B$, we have that:

$$f(A \cup \{v\}) - f(A) \leq f(B \cup \{v\}) - f(B) \quad (3.8)$$

- Incremental “value”, “gain”, or “cost” of v increases (improves) as the context in which v is considered grows from A to B .
- A function f is submodular iff $-f$ is supermodular.
- If f both submodular and supermodular, then f is said to be modular, and $f(A) = c + \sum_{a \in A} \bar{f}(a)$ for some \bar{f} (often $c = 0$).

Superadditive Definitions

Definition 3.4.2 (superadditive)

A function $f : 2^V \rightarrow \mathbb{R}$ is superadditive if for any $A, B \subseteq V$, we have that:

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- In general, submodular and subadditive (and supermodular and superadditive) are different properties.
- Ex: Let $0 < k < |V|$, and consider $f : 2^V \rightarrow \mathbb{R}_+$ where:

$$f(A) = \begin{cases} 1 & \text{if } |A| \leq k \\ 0 & \text{else} \end{cases} \quad (3.14)$$

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- Ex: Let $0 < k < |V|$, and consider $f : 2^V \rightarrow \mathbb{R}_+$ where:

$$f(A) = \begin{cases} 1 & \text{if } |A| \leq k \\ 0 & \text{else} \end{cases} \quad (3.14)$$

- This function is subadditive but not submodular.

$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$$

Modular Definitions

Definition 3.4.3 (modular)

A function that is both submodular and supermodular is called **modular**

If f is a modular function, then for any $A, B \subseteq V$, we have

$$f(A) + f(B) = f(A \cap B) + f(A \cup B) \quad (3.15)$$

In modular functions, elements do not interact (or cooperate, or compete, or influence each other), and have value based only on singleton values.

Proposition 3.4.4

If f is modular, it may be written as

$$f(A) = f(\emptyset) + \sum_{a \in A} \left(f(\{a\}) - f(\emptyset) \right) = c + \sum_{a \in A} f'(a) \quad (3.16)$$

which has only $|V| + 1$ parameters.

normalize $\Rightarrow c = 0$
 \therefore modular function vector $\in \mathbb{R}^V$

Modular Definitions

Proof.

We inductively construct the value for $A = \{a_1, a_2, \dots, a_k\}$.

For $k = 2$,

$$f(a_1) + f(a_2) = f(a_1, a_2) + f(\emptyset) \quad (3.17)$$

$$\text{implies } f(a_1, a_2) = f(a_1) - f(\emptyset) + f(a_2) - f(\emptyset) + f(\emptyset) \quad (3.18)$$

then for $k = 3$,

$$f(a_1, a_2) + f(a_3) = f(a_1, a_2, a_3) + f(\emptyset) \quad (3.19)$$

$$\text{implies } f(a_1, a_2, a_3) = f(a_1, a_2) - f(\emptyset) + f(a_3) - f(\emptyset) + f(\emptyset) \quad (3.20)$$

$$= f(\emptyset) + \sum_{i=1}^3 (f(a_i) - f(\emptyset)) \quad (3.21)$$

and so on ...



Complement function

Given a function $f : 2^V \rightarrow \mathbb{R}$, we can find a complement function $\bar{f} : 2^V \rightarrow \mathbb{R}$ as $\bar{f}(A) = f(V \setminus A)$ for any A .

Proposition 3.4.5

\bar{f} is submodular iff f is submodular.

Proof.

$$\bar{f}(A) + \bar{f}(B) \geq \bar{f}(A \cup B) + \bar{f}(A \cap B) \quad (3.22)$$

follows from

$$f(V \setminus A) + f(V \setminus B) \geq f(V \setminus (A \cup B)) + f(V \setminus (A \cap B)) \quad (3.23)$$

which is true because $V \setminus (A \cup B) = (V \setminus A) \cap (V \setminus B)$ and $V \setminus (A \cap B) = (V \setminus A) \cup (V \setminus B)$ (De Morgan's laws for sets). □

Undirected Graphs

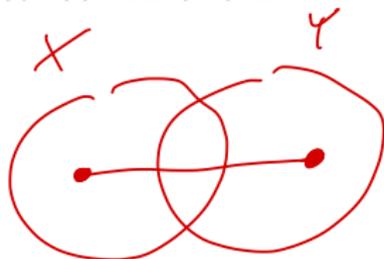
- Let $G = (V, E)$ be a graph with vertices $V = V(G)$ and edges $E = E(G) \subseteq V \times V$.

Undirected Graphs

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- If G is undirected, define

$$E(X, Y) \triangleq \{\{x, y\} \in E(G) : x \in X \setminus Y, y \in Y \setminus X\} \quad (3.24)$$

as the edges strictly between X and Y .



Undirected Graphs

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- Nodes define cuts. Define the **cut function** $\delta(X) = E(X, V \setminus X)$, set of edges with exactly one vertex in X .

Undirected Graphs

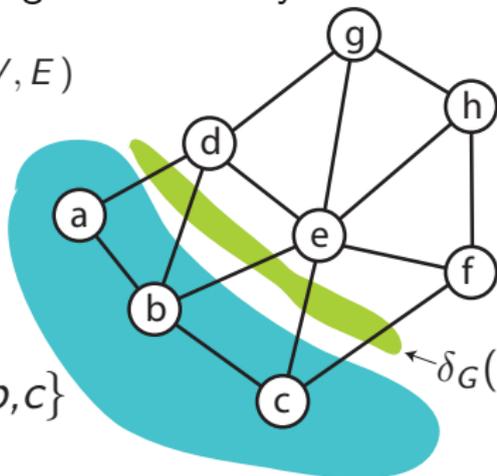
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- Nodes define cuts. Define the **cut function** $\delta(X) = E(X, V \setminus X)$, set of edges with exactly one vertex in X .

$G = (V, E)$



$S = \{a, b, c\}$

$$\begin{aligned} \delta_G(S) &= \{\{u, v\} \in E : u \in S, v \in V \setminus S\} \\ &= \{\{a, d\}, \{b, d\}, \{b, e\}, \{c, e\}, \{c, f\}\} \end{aligned}$$

Directed graphs, and cuts and flows

- If G is directed, define

$$E^+(X, Y) \triangleq \{(x, y) \in E(G) : x \in X \setminus Y, y \in Y \setminus X\} \quad (3.25)$$

as the edges directed strictly from X towards Y .

Directed graphs, and cuts and flows

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$$\delta^+(X) \triangleq E^+(X, V \setminus X) \quad (3.26)$$

and edges entering X (**in-flow**) as

$$\delta^-(X) \triangleq E^+(V \setminus X, X) \quad (3.27)$$

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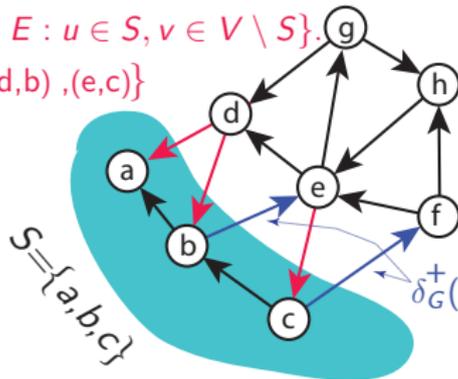
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and edges entering X (**in-flow**) as

$$\delta^-(X) \triangleq E^+(V \setminus X, X) \quad (3.27)$$

$$\begin{aligned} \delta_G^-(S) &= \{(v, u) \in E : u \in S, v \in V \setminus S\} \\ &= \{(d, a), (d, b), (e, c)\} \end{aligned}$$



$$\begin{aligned} \delta_G^+(S) &= \{(u, v) \in E : u \in S, v \in V \setminus S\} \\ &= \{(b, e), (c, f)\} \end{aligned}$$

The Neighbor function in undirected graphs

- Given a set $X \subseteq V$, the neighbor function of X is defined as

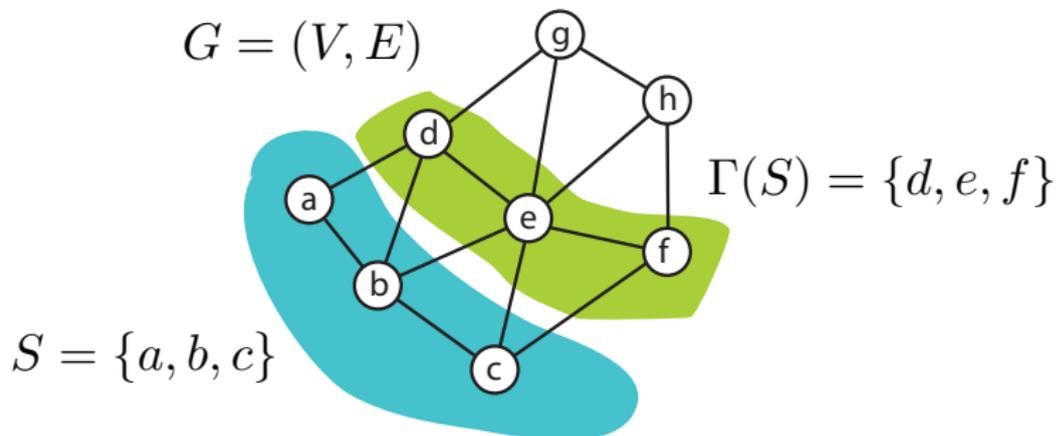
$$\Gamma(X) \triangleq \{v \in V(G) \setminus X : E(X, \{v\}) \neq \emptyset\} \quad (3.28)$$

The Neighbor function in undirected graphs

- Given a set $X \subseteq V$, the neighbor function of X is defined as

$$\Gamma(X) \triangleq \{v \in V(G) \setminus X : E(X, \{v\}) \neq \emptyset\} \quad (3.28)$$

- Example:



Directed Cut function: property

Lemma 3.5.1

For a digraph $G = (V, E)$ and any $X, Y \subseteq V$: we have

$$\begin{aligned} |\delta^+(X)| + |\delta^+(Y)| \\ = |\delta^+(X \cap Y)| + |\delta^+(X \cup Y)| + |E^+(X, Y)| + |E^+(Y, X)| \end{aligned} \quad (3.29)$$

and

$$\begin{aligned} |\delta^-(X)| + |\delta^-(Y)| \\ = |\delta^-(X \cap Y)| + |\delta^-(X \cup Y)| + |E^-(X, Y)| + |E^-(Y, X)| \end{aligned} \quad (3.30)$$

◦. $f^+(x) = |\delta^+(x)|$ is submodular
 $f^-(x) = |\delta^-(x)|$ is submodular.

Directed Cut function: proof of property

Proof.

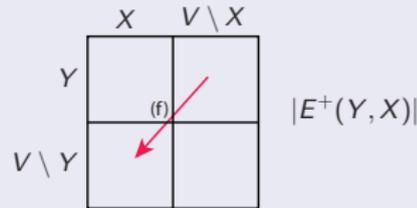
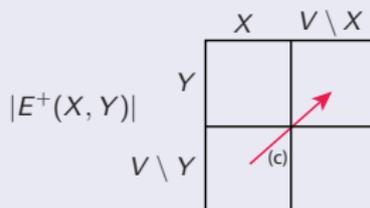
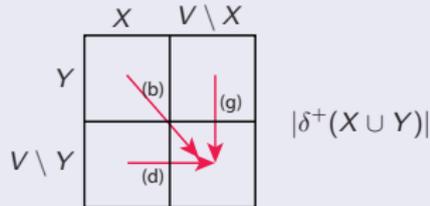
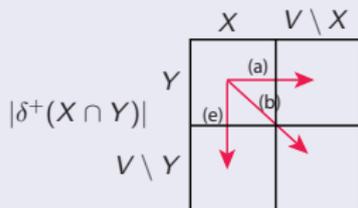
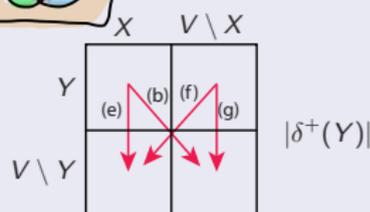
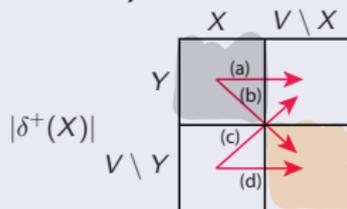
We can prove Eq. (3.29) using a geometric counting argument (proof for $|\delta^-(X)|$ case is similar)



$$w(\delta^+(X)) = f(X)$$

$$h(X) = f(\delta^+(X))$$

$$|A| = w(A)$$



Q: Why is $(c) = |E^+(X, Y)|$?

Directed cut/flow functions: submodular

Lemma 3.5.2

For a digraph $G = (V, E)$ and any $X, Y \subseteq V$: both functions $|\delta^+(X)|$ and $|\delta^-(X)|$ are submodular.

Proof.

$|E^+(X, Y)| \geq 0$ and $|E^-(X, Y)| \geq 0$. □

More generally, in the non-negative weighted edge case, both in-flow and out-flow are submodular on subsets of the vertices.

Undirected Cut/Flow & the Neighbor function: submodular

Lemma 3.5.3

For an undirected graph $G = (V, E)$ and any $X, Y \subseteq V$: we have that both the undirected cut (or flow) function $|\delta(X)|$ and the neighbor function $|\Gamma(X)|$ are submodular. I.e.,

$$|\delta(X)| + |\delta(Y)| = |\delta(X \cap Y)| + |\delta(X \cup Y)| + 2|E(X, Y)| \quad (3.31)$$

and

$$|\Gamma(X)| + |\Gamma(Y)| \geq |\Gamma(X \cap Y)| + |\Gamma(X \cup Y)| \quad (3.32)$$

Proof.

- Eq. (3.31) follows from Eq. (3.29): we replace each undirected edge $\{u, v\}$ with two oppositely-directed directed edges (u, v) and (v, u) . Then we use same counting argument.

$$|\delta(X)| = \frac{|\delta^+(X)| + |\delta^-(X)|}{2}$$



...

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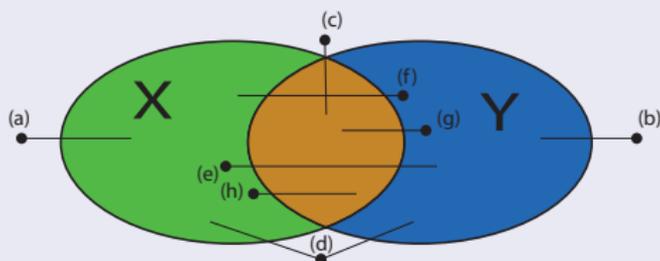
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- Eq. (3.32) follows as shown in the following page.

...

cont.



Graphically, we can count and see that

$$\Gamma(X) = (a) + (c) + (f) + (g) + (d) \quad (3.33)$$

$$\Gamma(Y) = (b) + (c) + (e) + (h) + (d) \quad (3.34)$$

$$\Gamma(X \cup Y) = (a) + (b) + (c) + (d) \quad (3.35)$$

$$\Gamma(X \cap Y) = (c) + (g) + (h) \quad (3.36)$$

so

$$\begin{aligned} |\Gamma(X)| + |\Gamma(Y)| &= (a) + (b) + 2(c) + 2(d) + (e) + (f) + (g) + (h) \\ &\geq (a) + (b) + 2(c) + (d) + (g) + (h) = |\Gamma(X \cup Y)| + |\Gamma(X \cap Y)| \end{aligned} \quad (3.37)$$

Undirected Neighbor functions

Therefore, the undirected cut function $|\delta(A)|$ and the neighbor function $|\Gamma(A)|$ of a graph G are both submodular.

Undirected cut/flow is submodular: alternate proof

- Another simple proof shows that $|\delta(X)|$ is submodular.

Undirected cut/flow is submodular: alternate proof

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- Define a graph $G_{uv} = (\{u, v\}, \{e\}, w)$ with two nodes u, v and one edge $e = \{u, v\}$ with non-negative weight $w(e) \in \mathbb{R}_+$.

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- Define a graph $G_{uv} = (\{u, v\}, \{e\}, w)$ with two nodes u, v and one edge $e = \{u, v\}$ with non-negative weight $w(e) \in \mathbb{R}_+$.
- Weighted cut function over those two nodes: $w(\delta_{u,v}(\cdot))$ has valuation:

$$w(\delta_{u,v}(\emptyset)) = w(\delta_{u,v}(\{u, v\})) = 0 \quad (3.38)$$

and

$$w(\delta_{u,v}(\{u\})) = w(\delta_{u,v}(\{v\})) = w \geq 0 \quad (3.39)$$

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$$w(\delta_{u,v}(\{u\})) = w(\delta_{u,v}(\{v\})) = w \geq 0 \quad (3.39)$$

- Thus, $w(\delta_{u,v}(\cdot))$ is submodular since $w(e) \geq 0$ and

$$w(\delta_{u,v}(\{u\})) + w(\delta_{u,v}(\{v\})) \geq w(\delta_{u,v}(\{u, v\})) + w(\delta_{u,v}(\emptyset)) \quad (3.40)$$

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- General non-negative weighted graph $G = (V, E, w)$, define $w(\delta(\cdot))$:

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$$w(\delta_{u,v}(\emptyset)) = w(\delta_{u,v}(\{u, v\})) = 0 \quad (3.38)$$

and

$f(x) = g(x \cap S)$

$$w(\delta_{u,v}(\{u\})) = w(\delta_{u,v}(\{v\})) = w \geq 0 \quad (3.39)$$

- Thus, $w(\delta_{u,v}(\cdot))$ is submodular since $w(e) \geq 0$ and

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- This is easily shown to be submodular using properties we will soon see (namely, submodularity closed under summation and restriction).

Other graph functions that are submodular/supermodular

These come from Narayanan's book 1997. Let G be an undirected graph.

- Let $V(X)$ be the vertices adjacent to some edge in $X \subseteq E(G)$, then $|V(X)|$ (the vertex function) is **submodular**.

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- Let $E(S)$ be the edges with both vertices in $S \subseteq V(G)$. Then $|E(S)|$ (the interior edge function) is **supermodular**.

$$g(S) = \sum_{i,j \in S} w_{ij}$$

Other graph functions that are submodular/supermodular

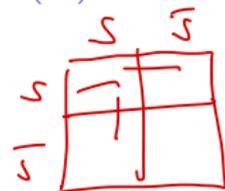
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- Let $E(S)$ be the edges with both vertices in $S \subseteq V(G)$. Then $|E(S)|$ (the interior edge function) is **supermodular**.
- Let $I(S)$ be the edges with at least one vertex in $S \subseteq V(G)$. Then $|I(S)|$ (the incidence function) is **submodular**.

$$g(A) = \sum_{i,j \in A} w_{i,j}$$

$$h(A) = \sum_{i,j \in V} w_{i,j} - g(A)$$

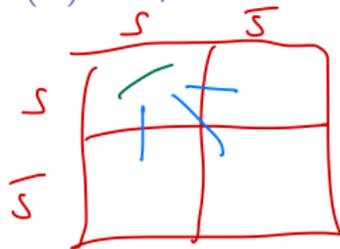
$$|I(S)| = h(V \setminus A)$$



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- Recall $|\delta(S)|$, is the number of edges with exactly one vertex in $S \subseteq V(G)$ is submodular (cut function). Thus, we have $I(S) = E(S) \cup \delta(S)$ and $E(S) \cap \delta(S) = \emptyset$, and thus that $|I(S)| = |E(S)| + |\delta(S)|$.



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- Recall $|\delta(S)|$, is the number of edges with exactly one vertex in $S \subseteq V(G)$ is submodular (cut function). Thus, we have $I(S) = E(S) \cup \delta(S)$ and $E(S) \cap \delta(S) = \emptyset$, and thus that $|I(S)| = |E(S)| + |\delta(S)|$. So we can get a submodular function by summing a submodular and a supermodular function. **If you had to guess, is this always the case?**

Other graph functions that are submodular/supermodular

These come from Narayanan's book 1997. Let G be an undirected graph.

- Let $V(X)$ be the vertices adjacent to some edge in $X \subseteq E(G)$, then $|V(X)|$ (the vertex function) is **submodular**.
- Let $E(S)$ be the edges with both vertices in $S \subseteq V(G)$. Then $|E(S)|$ (the interior edge function) is **supermodular**.
- Let $I(S)$ be the edges with at least one vertex in $S \subseteq V(G)$. Then $|I(S)|$ (the incidence function) is **submodular**.
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- Consider $f(A) = |\delta^+(A)| - |\delta^+(V \setminus A)|$. Guess, submodular, supermodular, modular, or neither? **Exercise: determine which one and prove it.**

Number of connected components in a graph via edges

- Recall, $f : 2^V \rightarrow \mathbb{R}$ is submodular, then so is $\bar{f} : 2^V \rightarrow \mathbb{R}$ defined as $\bar{f}(S) = f(V \setminus S)$.

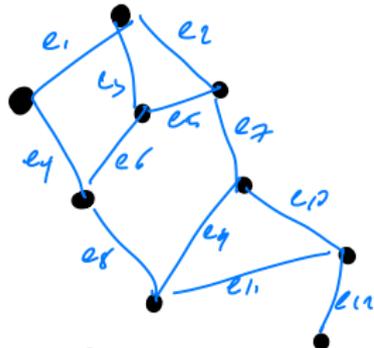
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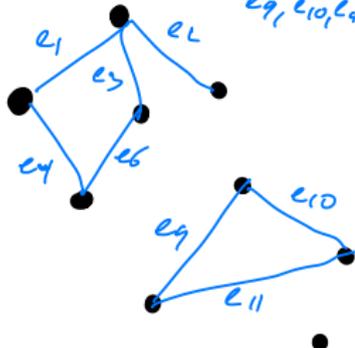
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- Given a graph $G = (V, E)$, for each $A \subseteq E(G)$, let $c(A)$ denote the number of connected components of the (spanning) subgraph $(V(G), A)$, with $c : 2^E \rightarrow \mathbb{R}_+$. Thus, $c(\emptyset) = |V|$ and $c(E) \geq 1$.

$$G = (V, E)$$



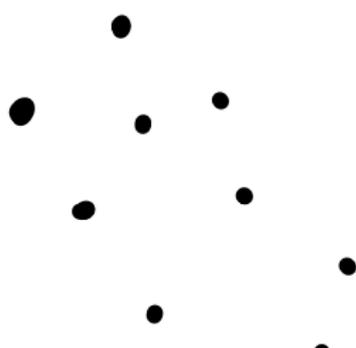
$$c(E) = 1$$

$$A = \{e_1, e_2, e_3, e_4, e_5, e_6, e_7, e_8, e_9, e_{10}, e_{11}\}$$



$$c(A) = 3$$

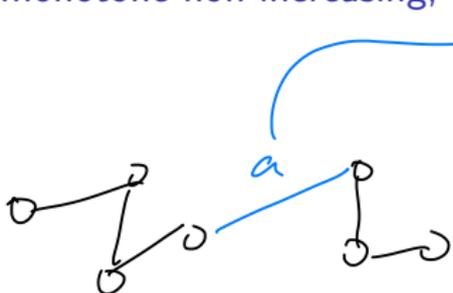
$$A = \emptyset$$



$$c(\emptyset) = 9$$

Number of connected components in a graph via edges

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- Then $c(A)$ is supermodular, i.e.,

$$c(A + a) - c(A) \leq c(B + a) - c(B) \leq 0 \quad (3.42)$$

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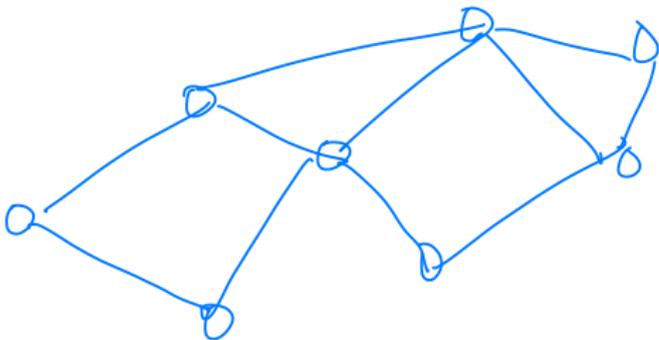
- Intuition: an edge is “more” (no less) able to bridge separate components (and reduce the number of connected components) when edge is added in a smaller context than when added in a larger context.
- $\bar{c}(A) = c(E \setminus A)$ is number of connected components in G when we remove A ; supermodular monotone non-decreasing but not normalized.

Graph Strength

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- Let $G = (V, E, w)$ with $w : E \rightarrow \mathbb{R}_+$ be a weighted graph with non-negative weights.
- For $(u, v) = e \in E$, let $w(e)$ be a measure of the strength of the connection between vertices u and v (strength meaning the difficulty of cutting the edge e).

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- Then $w(A)$ for $A \subseteq E$ is a modular function

$$w(A) = \sum_{e \in A} w_e \quad (3.43)$$

so that $w(E(G[S]))$ is the “internal strength” of the vertex set S .

Notation: S is a set of nodes, $G[S]$ is the vertex-induced subgraph of G induced by vertices S , $E(G[S])$ are the edges contained within this induced subgraph, and $w(E(G[S]))$ is the weight of these edges. $w(E(G[S])) = \sum_{i,j \in S} w(i,j)$.

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$$\begin{aligned} & \Rightarrow \text{submodular} \\ & \forall \lambda \geq 0 \end{aligned} \quad \text{strength}(G, w) = \min_{A \subseteq E(G): \bar{c}(A) > 1} \frac{w(A)}{\bar{c}(A) - 1} \quad (3.44)$$

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- Since submodularity, problems have strongly-poly-time solutions.

Submodularity, Quadratic Structures, and Cuts

Lemma 3.5.4

Let $\mathbf{M} \in \mathbb{R}^{n \times n}$ be a symmetric matrix and $m \in \mathbb{R}^n$ be a vector. Then $f : 2^V \rightarrow \mathbb{R}$ defined as

$$f(X) = m^\top \mathbf{1}_X + \frac{1}{2} \mathbf{1}_X^\top \mathbf{M} \mathbf{1}_X \quad (3.45)$$

is submodular iff the off-diagonal elements of M are non-positive.

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- f is a modular function $m^\top \mathbf{1}_A = m(A)$ added to a weighted submodular function, hence f is submodular.

Submodularity, Quadratic Structures, and Cuts

Proof of Lemma 3.5.4 cont.

- Conversely, suppose f is submodular.



Submodularity, Quadratic Structures, and Cuts

Proof of Lemma 3.5.4 cont.

- Conversely, suppose f is submodular.
- Then $\forall u, v \in V$, $f(\{u\}) + f(\{v\}) \geq f(\{u, v\}) + f(\emptyset)$ and $f(\emptyset) = 0$.



Submodularity, Quadratic Structures, and Cuts

Proof of Lemma 3.5.4 cont.

- Conversely, suppose f is submodular.
- Then $\forall u, v \in V$, $f(\{u\}) + f(\{v\}) \geq f(\{u, v\}) + f(\emptyset)$ and $f(\emptyset) = 0$.
- This requires:

$$0 \leq f(\{u\}) + f(\{v\}) - f(\{u, v\}) \quad (3.46)$$

$$= m(u) + \frac{1}{2}M_{u,u} + m(v) + \frac{1}{2}M_{v,v} \quad (3.47)$$

$$- \left(m(u) + m(v) + \frac{1}{2}M_{u,u} + M_{u,v} + \frac{1}{2}M_{v,v} \right) \quad (3.48)$$

$$= -M_{u,v} \quad (3.49)$$

So that $\forall u, v \in V$, $M_{u,v} \leq 0$.



Set Cover and Maximum Coverage

just Special cases of Submodular Optimization

- We are given a finite set U of m elements and a set of subsets $\mathcal{U} = \{U_1, U_2, \dots, U_n\}$ of n subsets of U , so that $U_i \subseteq U$ and $\bigcup_i U_i = U$.

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- The goal of **minimum set cover** is to choose the smallest subset $A \subseteq [n] \triangleq \{1, \dots, n\}$ such that $\bigcup_{a \in A} U_a = U$.

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- **Maximum k cover**: The goal in **maximum coverage** is, given an integer $k \leq n$, select k subsets, say $\{a_1, a_2, \dots, a_k\}$ with $a_i \in [n]$ such that $|\bigcup_{i=1}^k U_{a_i}|$ is maximized.

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- $f : 2^{[n]} \rightarrow \mathbb{Z}_+$ where for $A \subseteq [n]$, $f(A) = |\bigcup_{a \in A} U_a|$ is the **set cover function** and is submodular.
- Weighted set cover: $f(A) = w(\bigcup_{a \in A} U_a)$ where $w : U \rightarrow \mathbb{R}_+$.
- Both Set cover and maximum coverage are well known to be NP-hard, but have a fast greedy approximation algorithm, and hence are instances of submodular optimization.

Vertex and Edge Covers

Also instances of submodular optimization

Definition 3.5.5 (vertex cover)

A *vertex cover* (a “vertex-based cover of edges”) in graph $G = (V, E)$ is a set $S \subseteq V(G)$ of vertices such that every edge in G is incident to at least one vertex in S .

- Let $I(S)$ be the number of edges incident to vertex set S . Then we wish to find the smallest set $S \subseteq V$ subject to $I(S) = |E|$.

Definition 3.5.6 (edge cover)

A *edge cover* (an “edge-based cover of vertices”) in graph $G = (V, E)$ is a set $F \subseteq E(G)$ of edges such that every vertex in G is incident to at least one edge in F .

- Let $|V|(F)$ be the number of vertices incident to edge set F . Then we wish to find the smallest set $F \subseteq E$ subject to $|V|(F) = |V|$.

Graph Cut Problems

Also submodular optimization

- Minimum cut: Given a graph $G = (V, E)$, find a set of vertices $S \subseteq V$ that minimize the cut (set of edges) between S and $V \setminus S$.

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- Maximum cut: Given a graph $G = (V, E)$, find a set of vertices $S \subseteq V$ that maximize the cut (set of edges) between S and $V \setminus S$.
- Let $\delta : 2^V \rightarrow \mathbb{R}_+$ be the cut function, namely for any given set of nodes $X \subseteq V$, $|\delta(X)|$ measures the number of edges between nodes X and $V \setminus X$ — i.e., $\delta(x) = E(X, V \setminus X)$.

Graph Cut Problems

Also submodular optimization

- Minimum cut: Given a graph $G = (V, E)$, find a set of vertices $S \subseteq V$ that minimize the cut (set of edges) between S and $V \setminus S$.
- Maximum cut: Given a graph $G = (V, E)$, find a set of vertices $S \subseteq V$ that maximize the cut (set of edges) between S and $V \setminus S$.
- Let $\delta : 2^V \rightarrow \mathbb{R}_+$ be the cut function, namely for any given set of nodes $X \subseteq V$, $|\delta(X)|$ measures the number of edges between nodes X and $V \setminus X$ — i.e., $\delta(x) = E(X, V \setminus X)$.
- **Weighted versions, where rather than count, we sum the (non-negative) weights of the edges of a cut, $f(X) = w(\delta(X))$.**

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- Weighted versions, where rather than count, we sum the (non-negative) weights of the edges of a cut, $f(X) = w(\delta(X))$.
- Hence, Minimum cut and Maximum cut are also special cases of submodular optimization.

Matrix Rank functions

- Let V , with $|V| = m$ be an index set of a set of vectors in \mathbb{R}^n for some n (unrelated to m). Thus, $\forall v \in V, \exists x_v \in \mathbb{R}^n$.

Matrix Rank functions

- Let V , with $|V| = m$ be an index set of a set of vectors in \mathbb{R}^n for some n (unrelated to m). Thus, $\forall v \in V, \exists x_v \in \mathbb{R}^n$.
- For a given set $\{v, v_1, v_2, \dots, v_k\}$, it might or might not be possible to find $(\alpha_i)_i$ such that:

$$x_v = \sum_{i=1}^k \alpha_i x_{v_i} \quad (3.50)$$

If not, then x_v is **linearly independent** of x_{v_1}, \dots, x_{v_k} .

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- Let $r(S)$ for $S \subseteq V$ be the rank of the set of vectors S . Then $r(\cdot)$ is a submodular function, and in fact is called a **matric matroid rank** function.

Example: Rank function of a matrix

- Given $n \times m$ matrix $\mathbf{X} = (x_1, x_2, \dots, x_m)$ with $x_i \in \mathbb{R}^n$ for all i . There are m length- n column vectors $\{x_i\}_i$

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- For any $A \subseteq V$, let $r(A)$ be the rank of the column vectors indexed by A .

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- $r(A)$ is the dimensionality of the vector space spanned by the set of vectors $\{x_a\}_{a \in A}$.
- Thus, $r(V)$ is the rank of the matrix \mathbf{X} .

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Example: Rank function of a matrix

Consider the following 4×8 matrix, so $V = \{1, 2, 3, 4, 5, 6, 7, 8\}$.

$$\begin{array}{c}
 \begin{array}{cccccccc}
 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\
 1 & \left(\begin{array}{cccccccc}
 0 & 2 & 2 & 3 & 0 & 1 & 3 & 1 \\
 0 & 3 & 0 & 4 & 0 & 0 & 2 & 4 \\
 0 & 0 & 0 & 0 & 3 & 0 & 0 & 5 \\
 2 & 0 & 0 & 0 & 0 & 0 & 0 & 5
 \end{array} \right) \\
 2 \\
 3 \\
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 \end{array}
 =
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 \left(\begin{array}{cccccccc}
 | & | & | & | & | & | & | & | & | \\
 x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 & x_8 \\
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- Let $A = \{1, 2, 3\}$, $B = \{3, 4, 5\}$, $C = \{6, 7\}$, $A_r = \{1\}$, $B_r = \{5\}$.
- Then $r(A) = 3$, $r(B) = 3$, $r(C) = 2$.
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 2 & & 3 & 0 & 4 & 0 & 0 & 2 & 4 \\
 3 & & 0 & 0 & 0 & 3 & 0 & 0 & 5 \\
 4 & & 0 & 0 & 0 & 0 & 0 & 0 & 5 \\
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 = \\
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 & & | & | & | & | & | & | & | \\
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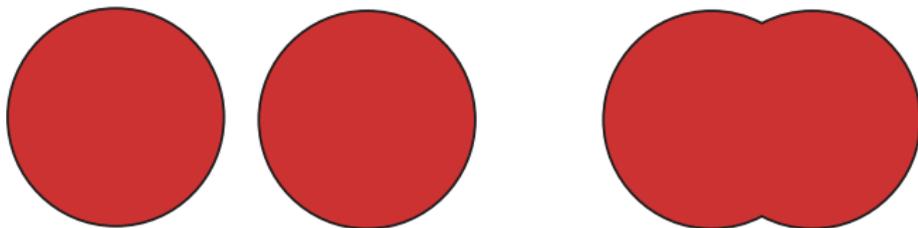
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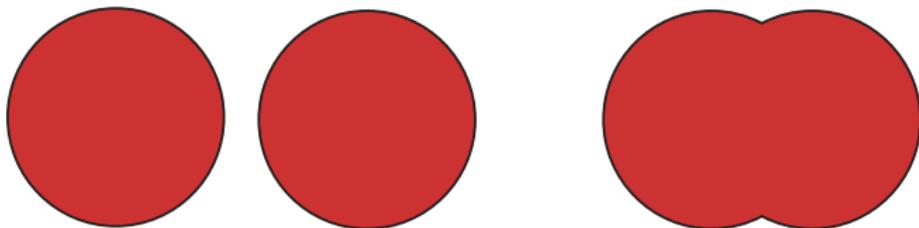
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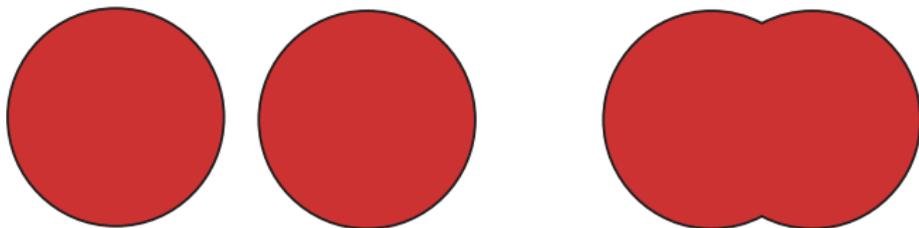


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- Any function where the above inequality is true for all $A, B \subseteq V$ is called **subadditive**.

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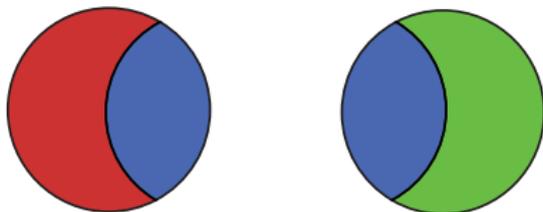
- But $r(A \cup B)$ counts the dimensions spanned by C only once.

$$r(A \cup B) = r(A_r) + r(C) + r(B_r) \quad (3.52)$$

Rank functions of a matrix

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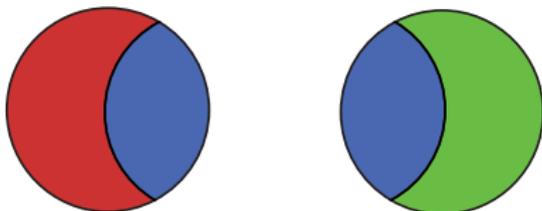
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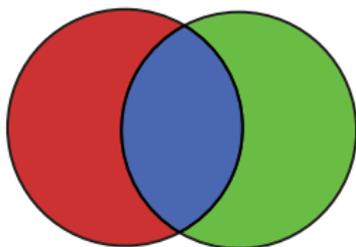
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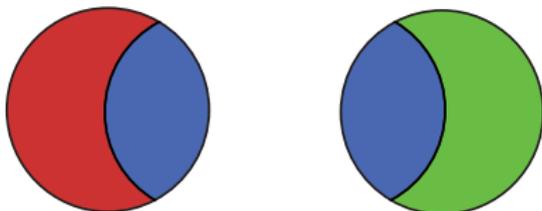
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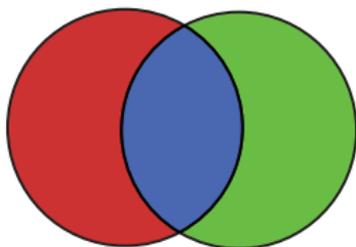
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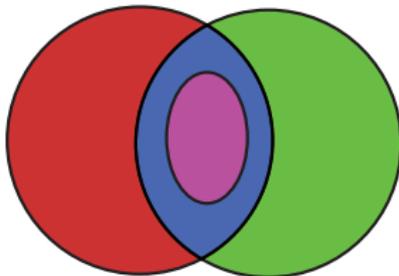


- Thus, we have **subadditivity**: $r(A) + r(B) \geq r(A \cup B)$. Can we add more to the r.h.s. and still have an inequality? Yes.

Rank function of a matrix

- Note, $r(A \cap B) \leq r(C)$. Why? Vectors indexed by $A \cap B$ (i.e., the **common index** set) span no more than the dimensions **commonly spanned** by A and B (namely, those spanned by the professed C).

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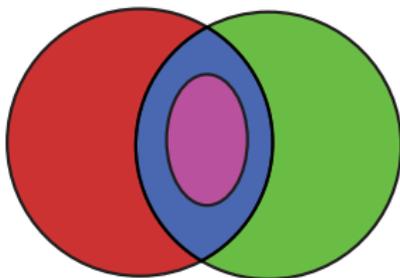


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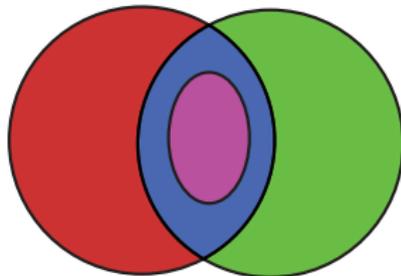
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- Common span (blue) is “more” (no less) than span of common index (magenta).

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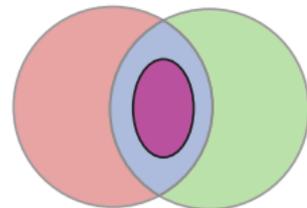
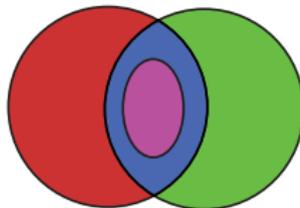
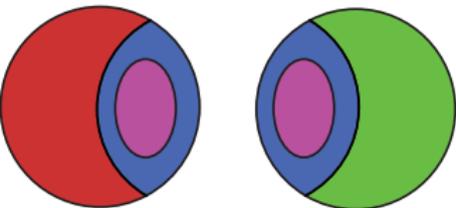


In short:

- Common span (blue) is “more” (no less) than span of common index (magenta).
- More generally, common information (blue) is “more” (no less) than information within common index (magenta).

The Venn and Art of Submodularity

$$\begin{array}{c}
 \begin{array}{cc}
 \begin{array}{|c|c|c|c|} \hline \color{purple}{\square} & \color{blue}{\square} & \color{white}{\square} & \color{red}{\square} \\ \hline \end{array} &
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- Then, defining $f : 2^S \rightarrow \mathbb{R}_+$ as follows,

$$f(X) = r(\cup_{s \in X} X_s) \quad (3.53)$$

we have that f is submodular, and is known to be a **polymatroid rank function**.

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- We can think of S as a set of sets of vectors from the matrix rank example, and for each $s \in S$, let X_s being a set of vector indices.
- Then, defining $f : 2^S \rightarrow \mathbb{R}_+$ as follows,

$$f(X) = r(\cup_{s \in X} X_s) \quad (3.53)$$

we have that f is submodular, and is known to be a **polymatroid rank function**.

- In general (as we will see) **polymatroid rank functions** are submodular, normalized $f(\emptyset) = 0$, and monotone non-decreasing ($f(A) \leq f(B)$ whenever $A \subseteq B$).

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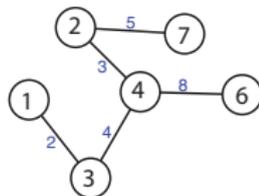
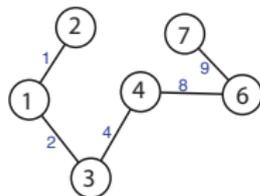
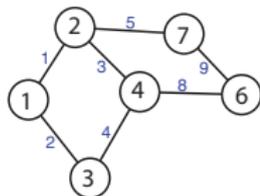
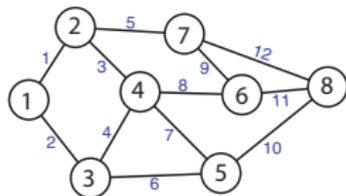
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- We use the term **non-decreasing** rather than **increasing**, the latter of which is strict (also so that a constant function isn't "increasing").

Spanning trees

- Let E be a set of edges of some graph $G = (V, E)$, and let $r(S)$ for $S \subseteq E$ be the maximum size (in terms of number of **edges**) spanning forest in the graph induced by edges S .

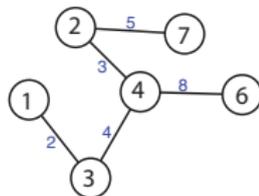
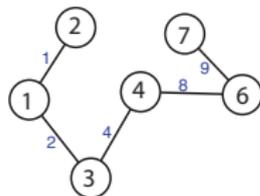
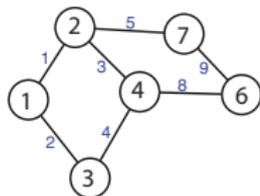
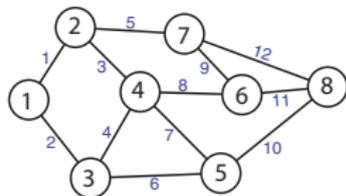
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- Then $r(S)$ is submodular, and is another matrix rank function corresponding to the incidence matrix of the graph.

Summing Submodular Functions

Given E , let $f_1, f_2 : 2^E \rightarrow \mathbb{R}$ be two submodular functions. Then

$$f : 2^E \rightarrow \mathbb{R} \text{ with } f(A) = f_1(A) + f_2(A) \quad (3.58)$$

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I.e., it holds for each component of f in each term in the inequality. In fact, any **conic combination** (i.e., non-negative linear combination) of submodular functions is submodular, as in $f(A) = \alpha_1 f_1(A) + \alpha_2 f_2(A)$ for $\alpha_1, \alpha_2 \geq 0$.

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That is, the modular component with $m(A) + m(B) = m(A \cup B) + m(A \cap B)$ never destroys the inequality. Note of course that if m is modular then so is $-m$.

Restricting Submodular functions

Given E , let $f : 2^E \rightarrow \mathbb{R}$ be a submodular functions. And let $S \subseteq E$ be an arbitrary fixed set. Then

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If $v \notin S$, then both differences on each side are zero. If $v \in S$, then we can consider this

$$f(A' + v) - f(A') \geq f(B' + v) - f(B') \quad (3.68)$$

with $A' = A \cap S$ and $B' = B \cap S$. Since $A' \subseteq B'$, this holds due to submodularity of f . □

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Given V , let $\mathcal{C} = \{C_1, C_2, \dots, C_k\}$ be a set of subsets of V , and for each $C \in \mathcal{C}$, let $f_C : 2^V \rightarrow \mathbb{R}$ be a submodular function. Then

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is submodular. This property is critical for image processing and graphical models. For example, let \mathcal{C} be all pairs of the form $\{\{u, v\} : u, v \in V\}$, or let it be all pairs corresponding to the edges of some undirected graphical model.

Max - normalized

Given V , let $c \in \mathbb{R}_+^V$ be a given fixed vector. Then $f : 2^V \rightarrow \mathbb{R}_+$, where

$$f(A) = \max_{j \in A} c_j \quad (3.71)$$

is submodular and normalized (we take $f(\emptyset) = 0$).

Proof.

Consider

$$\max_{j \in A} c_j + \max_{j \in B} c_j \geq \max_{j \in A \cup B} c_j + \max_{j \in A \cap B} c_j \quad (3.72)$$

which follows since we have that

$$\max(\max_{j \in A} c_j, \max_{j \in B} c_j) = \max_{j \in A \cup B} c_j \quad (3.73)$$

and

$$\min(\max_{j \in A} c_j, \max_{j \in B} c_j) \geq \max_{j \in A \cap B} c_j \quad (3.74)$$



Max

Given V , let $c \in \mathbb{R}^V$ be a given fixed vector (not necessarily non-negative). Then $f : 2^V \rightarrow \mathbb{R}$, where

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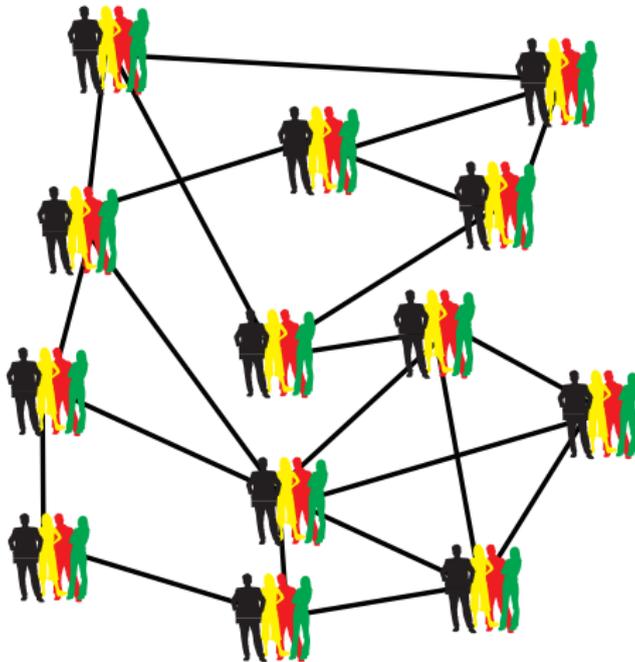
is submodular, where we take $f(\emptyset) \leq \min_j c_j$ (so the function need not be normalized).

Proof.

The proof is identical to the normalized case. □

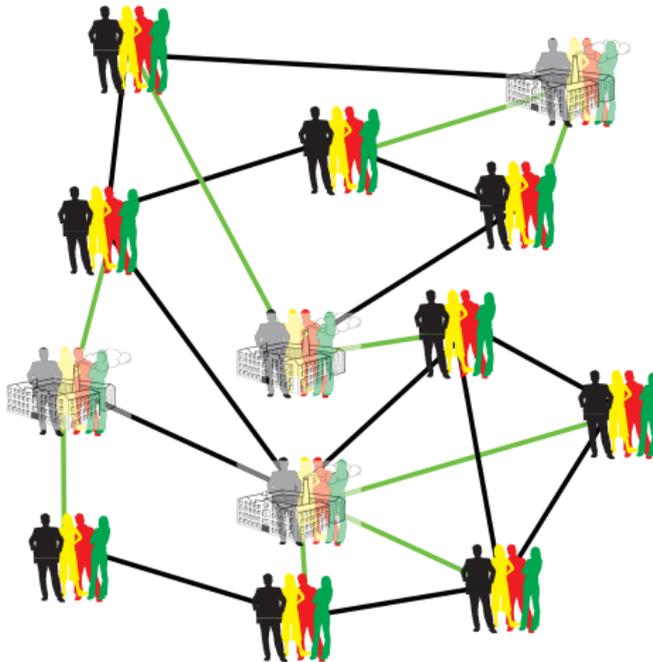
Facility/Plant Location (uncapacitated)

- Core problem in operations research, early motivation for submodularity.
- Goal: as efficiently as possible, place “facilities” (factories) at certain locations to satisfy sites (at all locations) having various demands.



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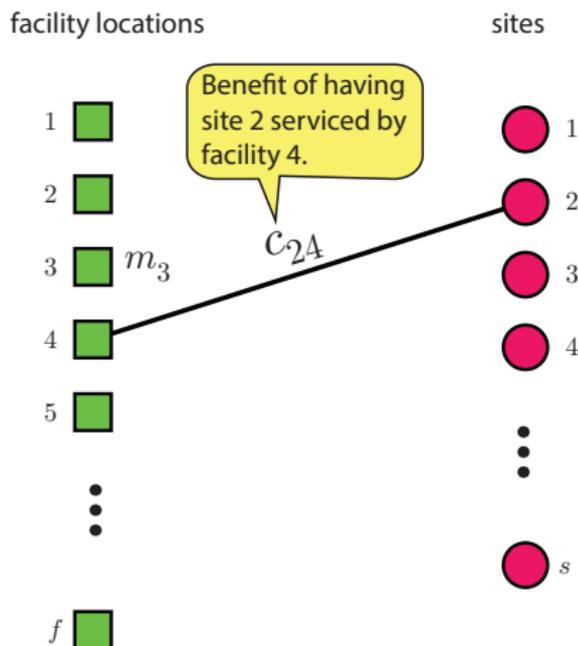
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- Goal: as efficiently as possible, place “facilities” (factories) at certain locations to satisfy sites (at all locations) having various demands.
- We can model this with a weighted bipartite graph $G = (F, S, E, c)$ where F is set of possible factory/plant locations, S is set of sites needing service, E are edges indicating (factory,site) service possibility pairs, and $c : E \rightarrow \mathbb{R}_+$ is the benefit of a given pair.
- Facility location function has form:

$$f(A) = \sum_{i \in S} \max_{j \in A} c_{ij}. \quad (3.76)$$



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- Goal is to find a set A that maximizes $f(A)$ (the benefit) placing a bound on the number of plants A (e.g., $|A| \leq k$).

Facility Location

Given V, E , let $c \in \mathbb{R}^{V \times E}$ be a given $|V| \times |E|$ matrix. Then

$$f : 2^E \rightarrow \mathbb{R}, \text{ where } f(A) = \sum_{i \in V} \max_{j \in A} c_{ij} \quad (3.78)$$

is submodular.

Proof.

We can write $f(A)$ as $f(A) = \sum_{i \in V} f_i(A)$ where $f_i(A) = \max_{j \in A} c_{ij}$ is submodular (max of a i^{th} row vector), so f can be written as a sum of submodular functions. □

Thus, the facility location function (which only adds a modular function to the above) is submodular.

Log Determinant

- Let Σ be an $n \times n$ positive definite matrix. Let $V = \{1, 2, \dots, n\} \equiv [n]$ be an index set, and for $A \subseteq V$, let Σ_A be the (square) submatrix of Σ obtained by including only entries in the rows/columns given by A .

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Proof of submodularity of the logdet function.

Suppose $X \in \mathbf{R}^n$ is multivariate Gaussian random variable, that is

$$x \in p(x) = \frac{1}{\sqrt{|2\pi\Sigma|}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right) \quad (3.80)$$

...

Log Determinant

...cont.

Then the (differential) entropy of the r.v. X is given by

$$h(X) = \log \sqrt{|2\pi e \Sigma|} = \log \sqrt{(2\pi e)^n |\Sigma|} \quad (3.81)$$

and in particular, for a variable subset A ,

$$f(A) = h(X_A) = \log \sqrt{(2\pi e)^{|A|} |\Sigma_A|} \quad (3.82)$$

Entropy is submodular (further conditioning reduces entropy), and moreover

$$f(A) = h(X_A) = m(A) + \frac{1}{2} \log |\Sigma_A| \quad (3.83)$$

where $m(A)$ is a modular function. □

Note: still submodular in the semi-definite case as well.

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- max is submodular $f(A) = \max_{j \in A} c_j$, as is facility location $f(A) = \sum_{u \in U} \max_{a \in A} s_{a,u}$.

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