

# Submodular Functions, Optimization, and Applications to Machine Learning

— Fall Quarter, Lecture 19 —

[http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563\\_spring\\_2018/](http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563_spring_2018/)

Prof. Jeff Bilmes

University of Washington, Seattle  
Department of Electrical Engineering  
<http://melodi.ee.washington.edu/~bilmes>

Dec 7th, 2020



$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$$

$$-f(A) + 2f(C) + f(B), \quad -f(A) + f(C) + f(B), \quad -f(A \cap B)$$



# Class Road Map - EE563

- L1(9/30): Motivation, Applications, Definitions, Properties
- L2(10/5): Sums concave(modular), uses (diversity/costs, feature selection), information theory
- L3(10/7): Monge, More Definitions, Graph and Combinatorial Examples,
- L4(10/12): Graph & Combinatorial Examples, Matrix Rank, Properties, Other Defs, Independence
- L5(10/14): Properties, Defs of Submodularity, Independence
- L6(10/19): Matroids, Matroid Examples, Matroid Rank,
- L7(10/21): Matroid Rank, More on Partition Matroid, Laminar Matroids, System of Distinct Reps, Transversals
- L8(10/26): Transversal Matroid, Matroid and representation, Dual Matroid
- L9(10/28): Other Matroid Properties, Combinatorial Geometries, Matroid and Greedy, Polyhedra, Matroid Polytopes
- L10(11/2): Matroid Polytopes, Matroids → Polymatroids
- L11(11/4): Matroids → Polymatroids, Polymatroids
- L12(11/9): Polymatroids, Polymatroids and Greedy
- L-(11/11): Veterans Day, Holiday
- L13(11/16): Polymatroids and Greedy, Possible Polytopes, Extreme Points, Cardinality Constrained Maximization
- L14(11/18): Cardinality Constrained Maximization, Curvature
- L15(11/23): Curvature, Submodular Max w. Other Constraints, Start Cont. Extensions
- L16(11/25): Submodular Max w. Other Constraints, Cont. Extensions, Lovász extension
- L17(11/30): Choquet Integration, Non-linear Measure/Aggregation, Definitions/Properties, Examples.
- L18(12/2): Multilinear Extension, Submodular Max/polyhedral, Most Violated Ineq., Matroids Closure/Sat
- L19(12/7): Fund. Circuit/Dep, SFM, L.E. primal, Start SFM via Min-Norm Point
- L20(12/9):
- L21(12/14): final meeting (presentations) maximization.

Last day of instruction, Fri. Dec 11th. Finals Week: Dec 12-18, 2020

# Rest of class

- Homework 4 posted, due Thursday Dec 17th, 2020, 11:55pm.
- Final project paper proposal, was due Sunday Dec 6th, 11:59pm.
- Final project 4-page paper and presentation slides, due Sunday Dec 13th, 11:59pm.
- Final project presentation, Monday Dec 14th, starting at 10:30am.
- Final project: Read and present a recent (past 5 years) paper on submodular/supermodular optimization. Paper should have both a theoretical and practical component. What is due: (1) 4-page paper summary, and (2) 10 minute presentation about the paper, will be giving presentations on Monday 12/14/2020. You must choose your paper before the 14th (this will be HW5), and you must turn in your slides and 4-page paper (this will be HW6).
- Recall, grades will be based on a combination of a final project (40%) and the four homeworks (60%).

# Most violated inequality problem in matroid polytope case

- Consider

$$P_r^+ = \{x \in \mathbb{R}^E : x \geq 0, x(A) \leq r_M(A), \forall A \subseteq E\} \quad (19.19)$$

- Suppose we have any  $x \in \mathbb{R}_+^E$  such that  $x \notin P_r^+$ .
- Hence, there must be a set of  $\mathcal{W} \subseteq 2^V$ , each member of which corresponds to a **violated inequality**, i.e., equations of the form  $x(A) > r_M(A)$  for  $A \in \mathcal{W}$ .
- The **most violated inequality** when  $x$  is considered w.r.t.  $P_r^+$  corresponds to the set  $A$  that maximizes  $x(A) - r_M(A)$ , i.e., the most violated inequality is valued as:

$$\max \{x(A) - r_M(A) : A \in \mathcal{W}\} = \max \{x(A) - r_M(A) : A \subseteq E\} \quad (19.20)$$

- Since  $x$  is modular and  $x(E \setminus A) = x(E) - x(A)$ , we can express this via a min as in;

$$\min \{r_M(A) + x(E \setminus A) : A \subseteq E\} \quad (19.21)$$

# Most violated inequality/polymatroid membership/SFM

- The **most violated inequality** when  $x$  is considered w.r.t.  $P_f^+$  corresponds to the set  $A$  that maximizes  $x(A) - f(A)$ , i.e., the most violated inequality is valued as:

$$\max \{x(A) - f(A) : A \in \mathcal{W}\} = \max \{x(A) - f(A) : A \subseteq E\} \quad (19.19)$$

- Since  $x$  is modular and  $x(E \setminus A) = x(E) - x(A)$ , we can express this via a min as in;

$$\min \{f(A) + x(E \setminus A) : A \subseteq E\} \quad (19.20)$$

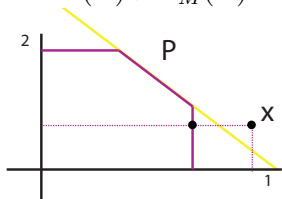
- More importantly,  $\min \{f(A) + x(E \setminus A) : A \subseteq E\}$  is a form of submodular function minimization, namely  $\min \{f(A) - x(A) : A \subseteq E\}$  for a submodular  $f$  and  $x \in \mathbb{R}_+^E$ , consisting of a difference of polymatroid and modular function (so  $f - x$  is no longer necessarily monotone, nor positive).
- We will ultimately answer how general this form of SFM is.

# Most violated inequality/polymatroid membership/SFM

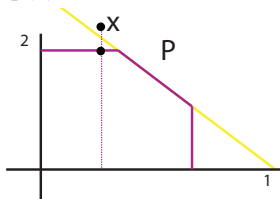
- Consider

$$P_f^+ = \{x \in \mathbb{R}^E : x \geq 0, x(A) \leq f(A), \forall A \subseteq E\} \quad (19.19)$$

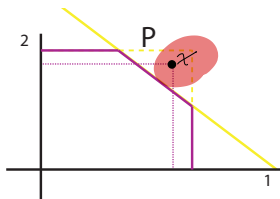
- Suppose we have any  $x \in \mathbb{R}_+^E$  such that  $x \notin P_f^+$ , most violated inequality is based on set  $A$  that solves  $\min \{f(A) - x(A) : A \subseteq E\}$  or  $\min \{f(A) + x(E \setminus A) : A \subseteq E\}$
- Hence, there must be a set of  $\mathcal{W} \subseteq 2^V$ , each member of which corresponds to a **violated inequality**, i.e., equations of the form  $x(A) > r_M(A)$  for  $A \in \mathcal{W}$ .



$$\mathcal{W} = \{\{1\}, \{1, 2\}\}$$



$$\mathcal{W} = \{\{2\}, \{1, 2\}\}$$



$$\mathcal{W} = \{\{1, 2\}\}$$

# Fundamental circuits in matroids

## Lemma 19.2.9

Let  $I \in \mathcal{I}(M)$ , and  $e \in E$ , then  $I \cup \{e\}$  contains at most one circuit in  $M$ .

## Proof.

- Suppose, to the contrary, that there are two distinct circuits  $C_1, C_2$  such that  $(C_1 \cup C_2) \subseteq I \cup \{e\}$ .
- Then  $e \in C_1 \cap C_2$ , and by (C2), there is a circuit  $C_3$  of  $M$  s.t.  $C_3 \subseteq (C_1 \cup C_2) \setminus \{e\} \subseteq I$
- This contradicts the independence of  $I$ .



In general, let  $C(I, e)$  be the unique circuit associated with  $I \cup \{e\}$  (commonly called the **fundamental circuit** in  $M$  w.r.t.  $I$  and  $e$ ).

# Matroids: The Fundamental Circuit

- Define  $C(I, e)$  be the unique circuit associated with  $I \cup \{e\}$  (the **fundamental circuit** in  $M$  w.r.t.  $I$  and  $e$ , if it exists).
- If  $e \in \text{span}(I) \setminus I$ , then  $C(I, e)$  is well defined ( $I + e$  creates one circuit).
- If  $e \in I$ , then  $I + e = I$  doesn't create a circuit. In such cases,  $C(I, e)$  is not really defined.
- In such cases, we define  $C(I, e) = \{e\}$ , and we will soon see why.
- If  $e \notin \text{span}(I)$  (i.e., when  $I + e$  is independent), then we set  $C(I, e) = \emptyset$ .



# The sat function = Polymatroid Closure

- In a matroid, closure (span) of a set  $A$  are all items that  $A$  spans (eq. that depend on  $A$ ).
- We wish to generalize closure to polymatroids.
- Consider  $x \in P_f$  for polymatroid function  $f$ .
- Again, recall, tight sets are closed under union and intersection, and therefore form a distributive lattice.
- That is, we saw in Lecture 11 that for any  $A, B \in \mathcal{D}(x)$ , we have that  $A \cup B \in \mathcal{D}(x)$  and  $A \cap B \in \mathcal{D}(x)$ , which can constitute a join and meet.
- Recall, for a given  $x \in P_f$ , we have defined this tight family as

$$\mathcal{D}(x) = \{A : A \subseteq E, x(A) = f(A)\} \quad (19.20)$$

and

$$\text{sat}(x) \stackrel{\text{def}}{=} \bigcup \{A : A \in \mathcal{D}(x)\} \quad (19.21)$$

# Minimizers of a Submodular Function form a lattice

## Theorem 19.2.10

For arbitrary submodular  $f$ , the minimizers are closed under union and intersection. That is, let  $\mathcal{M} = \operatorname{argmin}_{X \subseteq E} f(X)$  be the set of minimizers of  $f$ . Let  $A, B \in \mathcal{M}$ . Then  $A \cup B \in \mathcal{M}$  and  $A \cap B \in \mathcal{M}$ .

## Proof.

Since  $A$  and  $B$  are minimizers, we have  $f(A) = f(B) \leq f(A \cap B)$  and  $f(A) = f(B) \leq f(A \cup B)$ .

By submodularity, we have



$$f(A) + f(B) \geq f(A \cup B) + f(A \cap B) \quad (19.22)$$

Hence, we must have  $f(A) = f(B) = f(A \cup B) = f(A \cap B)$ . □

Thus, the minimizers of a submodular function form a lattice, and there is a maximal and a minimal minimizer of every submodular function.

# The sat function = Polymatroid Closure

- Matroid closure is generalized by the unique maximal element in  $\mathcal{D}(x)$ , also called the polymatroid closure or sat (**saturation function**).
- For some  $x \in P_f$ , we have defined:

$$\text{cl}(x) \stackrel{\text{def}}{=} \text{sat}(x) \stackrel{\text{def}}{=} \bigcup \{A : A \in \mathcal{D}(x)\} \quad (19.22)$$

$$= \bigcup \{A : A \subseteq E, x(A) = f(A)\} \quad (19.23)$$

$$= \{e : e \in E, \forall \alpha > 0, x + \alpha \mathbf{1}_e \notin P_f\} \quad (19.24)$$

- Hence,  $\text{sat}(x)$  is the maximal (zero-valued) minimizer of the submodular function  $f_x(A) \triangleq f(A) - x(A)$ .
- Eq. (??) says that  $\text{sat}$  consists of elements of  $E$  for point  $x$  that are  $P_f$  saturated (any additional positive movement, in that dimension, leaves  $P_f$ ). We'll revisit this in a few slides.
- First, we see how  $\text{sat}$  generalizes matroid closure.

# The sat function = Polymatroid Closure

Lemma 19.2.10 (Matroid  $\text{sat} : \mathbb{R}_+^E \rightarrow 2^E$  is the same as closure.)

$$\text{For } I \in \mathcal{I}, \text{ we have } \text{sat}(\mathbf{1}_I) = \text{span}(I) \quad (19.26)$$

Proof.

- For  $\mathbf{1}_I(I) = |I| = r(I)$ , so  $I \in \mathcal{D}(\mathbf{1}_I)$  and  $I \subseteq \text{sat}(\mathbf{1}_I)$ . Also,  $I \subseteq \text{span}(I)$ .
- Consider some  $b \in \text{span}(I) \setminus I$ .
- Then  $I \cup \{b\} \in \mathcal{D}(\mathbf{1}_I)$  since  $\mathbf{1}_I(I \cup \{b\}) = |I| = r(I \cup \{b\}) = r(I)$ .
- Thus,  $b \in \text{sat}(\mathbf{1}_I)$ .
- Therefore,  $\text{sat}(\mathbf{1}_I) \supseteq \text{span}(I)$ .

...

# Saturation Capacity

- The max is achieved when

$$\alpha = \hat{c}(x; e) \stackrel{\text{def}}{=} \min \{f(A) - x(A), \forall A \supseteq \{e\}\} \quad (19.43)$$

- $\hat{c}(x; e)$  is known as the **saturation capacity** associated with  $x \in P_f$  and  $e$ .
- Thus we have for  $x \in P_f$ ,

$$\hat{c}(x; e) \stackrel{\text{def}}{=} \min \{f(A) - x(A), \forall A \ni e\} \quad (19.44)$$

$$= \max \{\alpha : \alpha \in \mathbb{R}, x + \alpha \mathbf{1}_e \in P_f\} \quad (19.45)$$

- We immediately see that for  $e \in E \setminus \text{sat}(x)$ , we have that  $\hat{c}(x; e) > 0$ .
- Also, we have that:  $e \in \text{sat}(x) \Leftrightarrow \hat{c}(x; e) = 0$ .
- Note that any  $\alpha$  with  $0 \leq \alpha \leq \hat{c}(x; e)$  we have  $x + \alpha \mathbf{1}_e \in P_f$ .
- We also see that computing  $\hat{c}(x; e)$  is a form of submodular function minimization.



# Dependence Function

*more tools*

- Tight sets can be restricted to contain a particular element.

# Dependence Function

- Tight sets can be restricted to contain a particular element.
- Given  $x \in P_f$ , and  $e \in \text{sat}(x)$ , define

$$\mathcal{D}(x, e) = \{A : e \in A \subseteq E, x(A) = f(A)\} \quad (19.1)$$

$$= \mathcal{D}(x) \cap \{A : A \subseteq E, e \in A\} \quad (19.2)$$

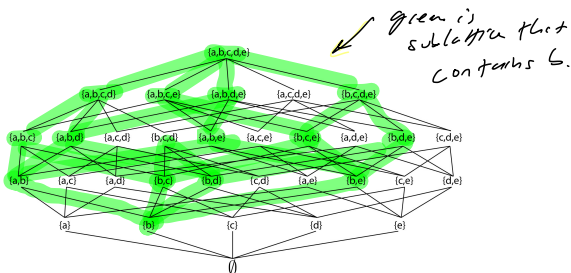
# Dependence Function

- Tight sets can be restricted to contain a particular element.
- Given  $x \in P_f$ , and  $e \in \text{sat}(x)$ , define

$$\mathcal{D}(x, e) = \{A : e \in A \subseteq E, x(A) = f(A)\} \quad (19.1)$$

$$= \mathcal{D}(x) \cap \{A : A \subseteq E, e \in A\} \quad (19.2)$$

- Thus,  $\mathcal{D}(x, e) \subseteq \mathcal{D}(x)$ , and  $\mathcal{D}(x, e)$  is a sublattice of  $\mathcal{D}(x)$ .





# Dependence Function

- Tight sets can be restricted to contain a particular element.
- Given  $x \in P_f$ , and  $e \in \text{sat}(x)$ , define

$$\mathcal{D}(x, e) = \{A : e \in A \subseteq E, x(A) = f(A)\} \quad (19.1)$$

$$= \mathcal{D}(x) \cap \{A : A \subseteq E, e \in A\} \quad (19.2)$$

- Thus,  $\mathcal{D}(x, e) \subseteq \mathcal{D}(x)$ , and  $\mathcal{D}(x, e)$  is a sublattice of  $\mathcal{D}(x)$ .
- Therefore, we can define a unique minimal element of  $\mathcal{D}(x, e)$  denoted as follows:

$$\text{dep}(x, e) = \begin{cases} \bigcap \{A : e \in A \subseteq E, x(A) = f(A)\} & \text{if } e \in \text{sat}(x) \\ \emptyset & \text{else} \end{cases} \quad (19.3)$$

# Dependence Function

- Tight sets can be restricted to contain a particular element.
- Given  $x \in P_f$ , and  $e \in \text{sat}(x)$ , define

$$\mathcal{D}(x, e) = \{A : e \in A \subseteq E, x(A) = f(A)\} \quad (19.1)$$

$$= \mathcal{D}(x) \cap \{A : A \subseteq E, e \in A\} \quad (19.2)$$

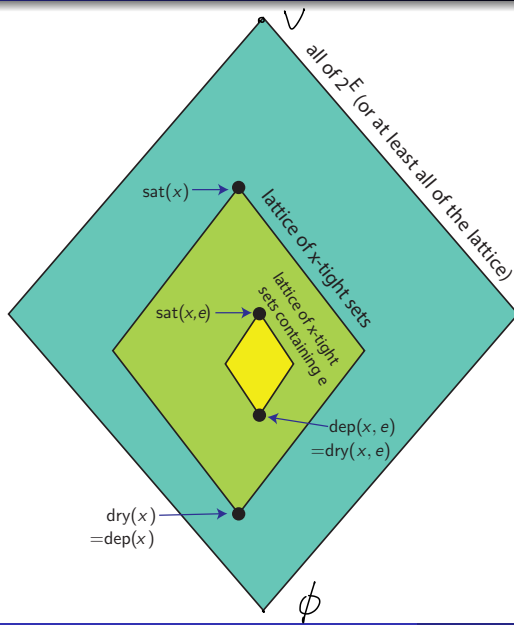
- Thus,  $\mathcal{D}(x, e) \subseteq \mathcal{D}(x)$ , and  $\mathcal{D}(x, e)$  is a sublattice of  $\mathcal{D}(x)$ .
- Therefore, we can define a unique minimal element of  $\mathcal{D}(x, e)$  denoted as follows:

$$\text{dep}(x, e) = \begin{cases} \bigcap \{A : e \in A \subseteq E, x(A) = f(A)\} & \text{if } e \in \text{sat}(x) \\ \emptyset & \text{else} \end{cases} \quad (19.3)$$

- I.e.,  $\text{dep}(x, e)$  is the minimal element in  $\mathcal{D}(x)$  that contains  $e$  (the minimal  $x$ -tight set containing  $e$ ). *The necessary elements for  $e$ -containing tightsets.*

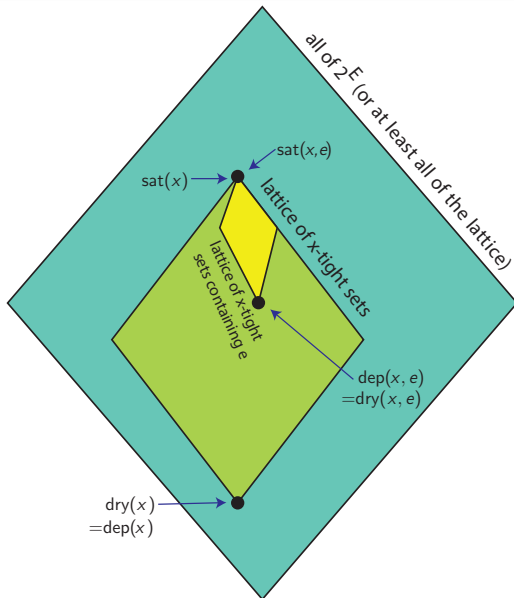
# dep and sat in a lattice

- Given some  $x \in P_f$ ,
- The picture on the right summarizes the relationships between the lattices and sublattices.
- Note,  $\text{dep}(x, e) \supseteq \text{dep}(x) = \bigcap \{A : x(A) = f(A)\}$ .



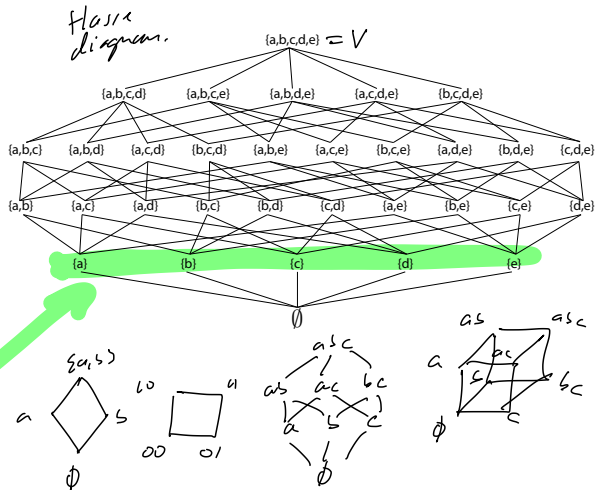
# dep and sat in a lattice

- Given some  $x \in P_f$ ,
- The picture on the right summarizes the relationships between the lattices and sublattices.
- Note,  $\text{dep}(x, e) \supseteq \text{dep}(x) = \bigcap \{A : x(A) = f(A)\}$ .
- In fact,  $\text{sat}(x, e) = \text{sat}(x)$ .  
Why?



# dep and sat in a lattice

- Given some  $x \in P_f$ ,
- The picture on the right summarizes the relationships between the lattices and sublattices.
- Note,  $\text{dep}(x, e) \supseteq \text{dep}(x) = \bigcap \{A : x(A) = f(A)\}$ .
- In fact,  $\text{sat}(x, e) = \text{sat}(x)$ . Why?
- Example lattice on 5 elements.



# dep and sat in a lattice

- Given  $x \in P_f$ , recall distributive lattice of tight sets  
 $\mathcal{D}(x) = \{A : x(A) = f(A)\}$

# dep and sat in a lattice

- Given  $x \in P_f$ , recall distributive lattice of tight sets  
 $\mathcal{D}(x) = \{A : x(A) = f(A)\}$
- We had that  $\text{sat}(x) = \bigcup \{A : A \in \mathcal{D}(x)\}$  is the “1” element of this lattice.

# dep and sat in a lattice

- Given  $x \in P_f$ , recall distributive lattice of tight sets  
 $\mathcal{D}(x) = \{A : x(A) = f(A)\}$
- We had that  $\text{sat}(x) = \bigcup \{A : A \in \mathcal{D}(x)\}$  is the “1” element of this lattice.
- Consider the “0” element of  $\mathcal{D}(x)$ , i.e.,  $\text{dry}(x) \stackrel{\text{def}}{=} \bigcap \{A : A \in \mathcal{D}(x)\}$



# dep and sat in a lattice

- Given  $x \in P_f$ , recall distributive lattice of tight sets  
 $\mathcal{D}(x) = \{A : x(A) = f(A)\}$
- We had that  $\text{sat}(x) = \bigcup \{A : A \in \mathcal{D}(x)\}$  is the “1” element of this lattice.
- Consider the “0” element of  $\mathcal{D}(x)$ , i.e.,  $\text{dry}(x) \stackrel{\text{def}}{=} \bigcap \{A : A \in \mathcal{D}(x)\}$
- We can see  $\text{dry}(x)$  as the elements that are necessary for tightness.

# dep and sat in a lattice

- Given  $x \in P_f$ , recall distributive lattice of tight sets  $\mathcal{D}(x) = \{A : x(A) = f(A)\}$
- We had that  $\text{sat}(x) = \bigcup \{A : A \in \mathcal{D}(x)\}$  is the “1” element of this lattice.
- Consider the “0” element of  $\mathcal{D}(x)$ , i.e.,  $\text{dry}(x) \stackrel{\text{def}}{=} \bigcap \{A : A \in \mathcal{D}(x)\}$
- We can see  $\text{dry}(x)$  as the **elements that are necessary for tightness**.
- That is, we can equivalently define  $\text{dry}(x)$  as

$$\underline{x \in P_f} \quad \text{dry}(x) = \{e' : x(A) < f(A), \forall A \not\supseteq e'\} \quad (19.4)$$

# dep and sat in a lattice

- Given  $x \in P_f$ , recall distributive lattice of tight sets  $\mathcal{D}(x) = \{A : x(A) = f(A)\}$
- We had that  $\text{sat}(x) = \bigcup \{A : A \in \mathcal{D}(x)\}$  is the “1” element of this lattice.
- Consider the “0” element of  $\mathcal{D}(x)$ , i.e.,  $\text{dry}(x) \stackrel{\text{def}}{=} \bigcap \{A : A \in \mathcal{D}(x)\}$
- We can see  $\text{dry}(x)$  as the **elements that are necessary for tightness**.
- That is, we can equivalently define  $\text{dry}(x)$  as

$$\text{dry}(x) = \{e' : x(A) < f(A), \forall A \not\supseteq e'\} \quad (19.4)$$

- This can be read as, for any  $e' \in \text{dry}(x)$ , any set that does not contain  $e'$  is not tight for  $x$  (any set  $A$  that is missing any element of  $\text{dry}(x)$  is not tight).

# dep and sat in a lattice

- Given  $x \in P_f$ , recall distributive lattice of tight sets  $\mathcal{D}(x) = \{A : x(A) = f(A)\}$
- We had that  $\text{sat}(x) = \bigcup \{A : A \in \mathcal{D}(x)\}$  is the “1” element of this lattice.
- Consider the “0” element of  $\mathcal{D}(x)$ , i.e.,  $\text{dry}(x) \stackrel{\text{def}}{=} \bigcap \{A : A \in \mathcal{D}(x)\}$
- We can see  $\text{dry}(x)$  as the **elements that are necessary for tightness**.
- That is, we can equivalently define  $\text{dry}(x)$  as

$$\text{dry}(x) = \{e' : x(A) < f(A), \forall A \not\supseteq e'\} \quad (19.4)$$

- This can be read as, for any  $e' \in \text{dry}(x)$ , any set that does not contain  $e'$  is not tight for  $x$  (any set  $A$  that is missing any element of  $\text{dry}(x)$  is not tight).
- Perhaps, then, a better name for  $\text{dry}$  is  $\text{ntight}(x)$ , for the necessary for tightness (but we'll actually use neither name).

# dep and sat in a lattice

- Given  $x \in P_f$ , recall distributive lattice of tight sets  $\mathcal{D}(x) = \{A : x(A) = f(A)\}$
- We had that  $\text{sat}(x) = \bigcup \{A : A \in \mathcal{D}(x)\}$  is the “1” element of this lattice.
- Consider the “0” element of  $\mathcal{D}(x)$ , i.e.,  $\text{dry}(x) \stackrel{\text{def}}{=} \bigcap \{A : A \in \mathcal{D}(x)\}$
- We can see  $\text{dry}(x)$  as the **elements that are necessary for tightness**.
- That is, we can equivalently define  $\text{dry}(x)$  as

$$\text{dry}(x) = \{e' : x(A) < f(A), \forall A \not\supseteq e'\} \quad (19.4)$$

- This can be read as, for any  $e' \in \text{dry}(x)$ , any set that does not contain  $e'$  is not tight for  $x$  (any set  $A$  that is missing any element of  $\text{dry}(x)$  is not tight).
- Perhaps, then, a better name for  $\text{dry}$  is  $\text{ntight}(x)$ , for the necessary for tightness (but we'll actually use neither name).
- Note that  $\text{dry}$  need not be the empty set. **Exercise: give example.**

# $e$ -containing dep and sat

- Now, given  $x \in P_f$ , and  $e \in \text{sat}(x)$ , recall distributive sub-lattice of  $e$ -containing tight sets  $\mathcal{D}(x, e) = \{A : e \in A, x(A) = f(A)\}$
- We can define the “1” element of this sub-lattice as  $\text{sat}(x, e) \stackrel{\text{def}}{=} \bigcup \{A : A \in \mathcal{D}(x, e)\}$ .
- Analogously, we can define the “0” element of this sub-lattice as  $\text{dry}(x, e) \stackrel{\text{def}}{=} \bigcap \{A : A \in \mathcal{D}(x, e)\} = \text{ntight}(x, e)$ .
- We can see  $\text{dry}(x, e)$  as the elements that are necessary for  $e$ -containing tightness, with  $e \in \text{sat}(x)$ .
- That is, we can view  $\text{dry}(x, e)$  as

$$\text{dry}(x, e) = \text{dry}(x, e) = \{e' : x(A) < f(A), \forall A \ni e', e \in A\} \quad (19.5)$$

- This can be read as, for any  $e' \in \text{dry}(x, e)$ , any  $e$ -containing set that does not contain  $e'$  is not tight for  $x$ . Could call it  $\text{ntight}(x, e)$ , necessary elements for  $e$ -containing tightness.
- But actually,  $\text{dry}(x, e) = \text{dep}(x, e)$ , so we have derived another expression for  $\text{dep}(x, e)$  in Eq. (19.5).

# Dependence Function and Fundamental Matroid Circuit

- Now, let  $(E, \mathcal{I}) = (E, r)$  be a matroid, and let  $I \in \mathcal{I}$  giving  $\mathbf{1}_I \in P_r$ . We have  $\text{sat}(\mathbf{1}_I) = \text{span}(I) = \text{closure}(I)$ .

# Dependence Function and Fundamental Matroid Circuit

- Now, let  $(E, \mathcal{I}) = (E, r)$  be a matroid, and let  $I \in \mathcal{I}$  giving  $\mathbf{1}_I \in P_r$ . We have  $\text{sat}(\mathbf{1}_I) = \text{span}(I) = \text{closure}(I)$ .
- Suppose  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then consider an  $A \ni e$  with  $|I \cap A| = r(A)$ .



# Dependence Function and Fundamental Matroid Circuit

- Now, let  $(E, \mathcal{I}) = (E, r)$  be a matroid, and let  $I \in \mathcal{I}$  giving  $\mathbf{1}_I \in P_r$ . We have  $\text{sat}(\mathbf{1}_I) = \text{span}(I) = \text{closure}(I)$ .
- Suppose  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then consider an  $A \ni e$  with  $|I \cap A| = r(A)$ .
- Then  $I \cap A$  serves as a base for  $A$  (i.e.,  $I \cap A$  spans  $A$ ) and any such  $A$  contains a circuit (i.e., we can add  $e \in A \setminus I$  to  $I \cap A$  w/o increasing rank).

# Dependence Function and Fundamental Matroid Circuit

- Now, let  $(E, \mathcal{I}) = (E, r)$  be a matroid, and let  $I \in \mathcal{I}$  giving  $\mathbf{1}_I \in P_r$ . We have  $\text{sat}(\mathbf{1}_I) = \text{span}(I) = \text{closure}(I)$ .
- Suppose  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then consider an  $A \ni e$  with  $|I \cap A| = r(A)$ .
- Then  $I \cap A$  serves as a base for  $A$  (i.e.,  $I \cap A$  spans  $A$ ) and any such  $A$  contains a circuit (i.e., we can add  $e \in A \setminus I$  to  $I \cap A$  w/o increasing rank).
- Given  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , and consider  $\text{dep}(\mathbf{1}_I, e)$ , with

$$\text{dep}(\mathbf{1}_I, e) = \bigcap \{A : e \in A \subseteq E, \mathbf{1}_I(A) = r(A)\} \quad (19.6)$$

$$= \bigcap \{A : e \in A \subseteq E, |I \cap A| = r(A)\} \quad (19.7)$$

$$= \bigcap \{A : e \in A \subseteq E, r(A) - |I \cap A| = 0\} \quad (19.8)$$

# Dependence Function and Fundamental Matroid Circuit

- Now, let  $(E, \mathcal{I}) = (E, r)$  be a matroid, and let  $I \in \mathcal{I}$  giving  $\mathbf{1}_I \in P_r$ . We have  $\text{sat}(\mathbf{1}_I) = \text{span}(I) = \text{closure}(I)$ .
- Suppose  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then consider an  $A \ni e$  with  $|I \cap A| = r(A)$ .
- Then  $I \cap A$  serves as a base for  $A$  (i.e.,  $I \cap A$  spans  $A$ ) and any such  $A$  contains a circuit (i.e., we can add  $e \in A \setminus I$  to  $I \cap A$  w/o increasing rank).
- Given  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , and consider  $\text{dep}(\mathbf{1}_I, e)$ , with

$$\text{dep}(\mathbf{1}_I, e) = \bigcap \{A : e \in A \subseteq E, \mathbf{1}_I(A) = r(A)\} \quad (19.6)$$

$$= \bigcap \{A : e \in A \subseteq E, |I \cap A| = r(A)\} \quad (19.7)$$

$$= \bigcap \{A : e \in A \subseteq E, r(A) - |I \cap A| = 0\} \quad (19.8)$$

- By SFM lattice,  $\exists$  a unique minimal  $A \ni e$  with  $|I \cap A| = r(A)$ .

# Dependence Function and Fundamental Matroid Circuit

- Now, let  $(E, \mathcal{I}) = (E, r)$  be a matroid, and let  $I \in \mathcal{I}$  giving  $\mathbf{1}_I \in P_r$ . We have  $\text{sat}(\mathbf{1}_I) = \text{span}(I) = \text{closure}(I)$ .
- Suppose  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then consider an  $A \ni e$  with  $|I \cap A| = r(A)$ .
- Then  $I \cap A$  serves as a base for  $A$  (i.e.,  $I \cap A$  spans  $A$ ) and any such  $A$  contains a circuit (i.e., we can add  $e \in A \setminus I$  to  $I \cap A$  w/o increasing rank).
- Given  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , and consider  $\text{dep}(\mathbf{1}_I, e)$ , with

$$\text{dep}(\mathbf{1}_I, e) = \bigcap \{A : e \in A \subseteq E, \mathbf{1}_I(A) = r(A)\} \quad (19.6)$$

$$= \bigcap \{A : e \in A \subseteq E, |I \cap A| = r(A)\} \quad (19.7)$$

$$= \bigcap \{A : e \in A \subseteq E, r(A) - |I \cap A| = 0\} \quad (19.8)$$

- By SFM lattice,  $\exists$  a unique minimal  $A \ni e$  with  $|I \cap A| = r(A)$ .
- Thus,  $\text{dep}(\mathbf{1}_I, e)$  must be a circuit since if it included more than a circuit, it would not be minimal in this sense.

# Dependence Function and Fundamental Matroid Circuit

- Therefore, when  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then  $\text{dep}(\mathbf{1}_I, e) = C(I, e)$  where  $C(I, e)$  is the unique circuit contained in  $I + e$  in a matroid (the **fundamental circuit** of  $e$  and  $I$  that we encountered before).

# Dependence Function and Fundamental Matroid Circuit

- Therefore, when  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then  $\text{dep}(\mathbf{1}_I, e) = C(I, e)$  where  $C(I, e)$  is the unique circuit contained in  $I + e$  in a matroid (the **fundamental circuit** of  $e$  and  $I$  that we encountered before).
- Now, if  $e \in \text{sat}(\mathbf{1}_I) \cap I$  with  $I \in \mathcal{I}$ , we said that  $C(I, e)$  was undefined (since no circuit is created in this case) and so we defined it as  $C(I, e) = \{e\}$

# Dependence Function and Fundamental Matroid Circuit

- Therefore, when  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then  $\text{dep}(\mathbf{1}_I, e) = C(I, e)$  where  $C(I, e)$  is the unique circuit contained in  $I + e$  in a matroid (the **fundamental circuit** of  $e$  and  $I$  that we encountered before).
- Now, if  $e \in \text{sat}(\mathbf{1}_I) \cap I$  with  $I \in \mathcal{I}$ , we said that  $C(I, e)$  was undefined (since no circuit is created in this case) and so we defined it as  $C(I, e) = \{e\}$
- This explains why: for such an  $e$ , we have  $\text{dep}(\mathbf{1}_I, e) = \{e\}$  since all such sets  $A \ni e$  with  $|I \cap A| = r(A)$  contain  $e$ , but in this case no cycle is created, i.e.,  $|I \cap A| \geq |I \cap \{e\}| = r(e) = 1$ .

# Dependence Function and Fundamental Matroid Circuit

- Therefore, when  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then  $\text{dep}(\mathbf{1}_I, e) = C(I, e)$  where  $C(I, e)$  is the unique circuit contained in  $I + e$  in a matroid (the **fundamental circuit** of  $e$  and  $I$  that we encountered before).
- Now, if  $e \in \text{sat}(\mathbf{1}_I) \cap I$  with  $I \in \mathcal{I}$ , we said that  $C(I, e)$  was undefined (since no circuit is created in this case) and so we defined it as  $C(I, e) = \{e\}$
- This explains why: for such an  $e$ , we have  $\text{dep}(\mathbf{1}_I, e) = \{e\}$  since all such sets  $A \ni e$  with  $|I \cap A| = r(A)$  contain  $e$ , but in this case no cycle is created, i.e.,  $|I \cap A| \geq |I \cap \{e\}| = r(e) = 1$ . *Assuming  $e$  is not a loop.*
- We are thus free to take subsets of  $I$  as  $A$ , all of which must contain  $e$ , but all of which have rank equal to size, and min size is 1.



# Dependence Function and Fundamental Matroid Circuit

- Therefore, when  $e \in \text{sat}(\mathbf{1}_I) \setminus I$ , then  $\text{dep}(\mathbf{1}_I, e) = C(I, e)$  where  $C(I, e)$  is the unique circuit contained in  $I + e$  in a matroid (the **fundamental circuit** of  $e$  and  $I$  that we encountered before).
- Now, if  $e \in \text{sat}(\mathbf{1}_I) \cap I$  with  $I \in \mathcal{I}$ , we said that  $C(I, e)$  was undefined (since no circuit is created in this case) and so we defined it as  $C(I, e) = \{e\}$
- This explains why: for such an  $e$ , we have  $\text{dep}(\mathbf{1}_I, e) = \{e\}$  since all such sets  $A \ni e$  with  $|I \cap A| = r(A)$  contain  $e$ , but in this case no cycle is created, i.e.,  $|I \cap A| \geq |I \cap \{e\}| = r(e) = 1$ .
- We are thus free to take subsets of  $I$  as  $A$ , all of which must contain  $e$ , but all of which have rank equal to size, and min size is 1.
- Also note: in general for  $x \in P_f$  and  $e \in \text{sat}(x)$ , we have  $\text{dep}(x, e)$  is tight by definition (i.e.,  $x(\text{dep}(x, e)) = f(\text{dep}(x, e))$ ), the minimum  $e$ -constaining  $x$ -tight set.

# Summary of sat, and dep

- For  $x \in P_f$ ,  $\text{sat}(x)$  (span, closure) is the maximal saturated ( $x$ -tight) set w.r.t.  $x$ . I.e.,  $\text{sat}(x) = \{e : e \in E, \forall \alpha > 0, x + \alpha \mathbf{1}_e \notin P_f\}$ . That is,

$$\text{cl}(x) \stackrel{\text{def}}{=} \text{sat}(x) \triangleq \bigcup \{A : A \in \mathcal{D}(x)\} \quad (19.9)$$

$$= \bigcup \{A : A \subseteq E, x(A) = f(A)\} \quad (19.10)$$

$$= \{e : e \in E, \forall \alpha > 0, x + \alpha \mathbf{1}_e \notin P_f\} \quad (19.11)$$

- For  $e \in \text{sat}(x)$ , we have  $\text{dep}(x, e) \subseteq \text{sat}(x)$  (fundamental circuit) is the minimal (common) saturated ( $x$ -tight) set w.r.t.  $x$  containing  $e$ . I.e.,

$$\text{dep}(x, e) = \begin{cases} \bigcap \{A : e \in A \subseteq E, x(A) = f(A)\} & \text{if } e \in \text{sat}(x) \\ \emptyset & \text{else} \end{cases}$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } x + \alpha(\mathbf{1}_e - \mathbf{1}_{e'}) \in P_f\} \quad (19.12)$$

Note, for  $x \in P_f$ , if  $x + \alpha(\mathbf{1}_e - \mathbf{1}_{e'}) \in P_f$ , then  $x + \alpha'(\mathbf{1}_e - \mathbf{1}_{e'}) \in P_f$  for any  $0 \leq \alpha' < \alpha$ .

# Dependence Function and exchange

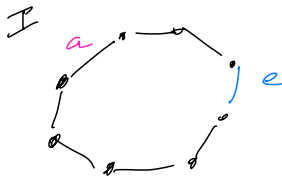
- For  $e \in \text{span}(I) \setminus I$ , we have that  $I + e \notin \mathcal{I}$ . This is a set addition restriction property.

## Dependence Function and exchange

- For  $e \in \text{span}(I) \setminus I$ , we have that  $I + e \notin \mathcal{I}$ . This is a set addition restriction property.
- Analogously, for  $e \in \text{sat}(x)$ , any  $x + \alpha \mathbf{1}_e \notin P_f$  for  $\alpha > 0$ . This is a vector increase restriction property.

# Dependence Function and exchange

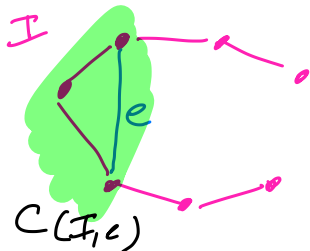
- For  $e \in \text{span}(I) \setminus I$ , we have that  $I + e \notin \mathcal{I}$ . This is a set addition restriction property.
- Analogously, for  $e \in \text{sat}(x)$ , any  $x + \alpha \mathbf{1}_e \notin P_f$  for  $\alpha > 0$ . This is a vector increase restriction property.
- Recall, we have  $C(I, e) \setminus e' \in \mathcal{I}$  for  $e' \in C(I, e)$ . I.e.,  $C(I, e)$  consists of elements that when removed recover independence.



# Dependence Function and exchange

- For  $e \in \text{span}(I) \setminus I$ , we have that  $I + e \notin \mathcal{I}$ . This is a set addition restriction property.
- Analogously, for  $e \in \text{sat}(x)$ , any  $x + \alpha \mathbf{1}_e \notin P_f$  for  $\alpha > 0$ . This is a vector increase restriction property.
- Recall, we have  $C(I, e) \setminus e' \in \mathcal{I}$  for  $e' \in C(I, e)$ . I.e.,  $C(I, e)$  consists of elements that when removed recover independence.
- In other words, given an  $e \in \text{span}(I) \setminus I$ , we have that

$$C(I, e) = \{a \in E : I + e - a \in \mathcal{I}\} \subseteq \mathcal{I} + e \quad (19.13)$$



## Dependence Function and exchange

- For  $e \in \text{span}(I) \setminus I$ , we have that  $I + e \notin \mathcal{I}$ . This is a set addition restriction property.
- Analogously, for  $e \in \text{sat}(x)$ , any  $x + \alpha \mathbf{1}_e \notin P_f$  for  $\alpha > 0$ . This is a vector increase restriction property.
- Recall, we have  $C(I, e) \setminus e' \in \mathcal{I}$  for  $e' \in C(I, e)$ . I.e.,  $C(I, e)$  consists of elements that when removed recover independence.
- In other words, given an  $e \in \text{span}(I) \setminus I$ , we have that

$$C(I, e) = \{a \in E : I + e - a \in \mathcal{I}\} \quad (19.13)$$

- I.e., an addition of  $e$  to  $I$  stays within  $\mathcal{I}$  only if we simultaneously remove one of the elements of  $C(I, e)$ .

## Dependence Function and exchange

- For  $e \in \text{span}(I) \setminus I$ , we have that  $I + e \notin \mathcal{I}$ . This is a set addition restriction property.
- Analogously, for  $e \in \text{sat}(x)$ , any  $x + \alpha \mathbf{1}_e \notin P_f$  for  $\alpha > 0$ . This is a vector increase restriction property.
- Recall, we have  $C(I, e) \setminus e' \in \mathcal{I}$  for  $e' \in C(I, e)$ . I.e.,  $C(I, e)$  consists of elements that when removed recover independence.
- In other words, given an  $e \in \text{span}(I) \setminus I$ , we have that

$$C(I, e) = \{a \in E : I + e - a \in \mathcal{I}\} \quad (19.13)$$

- I.e., an addition of  $e$  to  $I$  stays within  $\mathcal{I}$  only if we simultaneously remove one of the elements of  $C(I, e)$ .
- But, analogous to the circuit case, is there an exchange property for  $\text{dep}(x, e)$  in the form of vector movement restriction?



## Dependence Function and exchange

- For  $e \in \text{span}(I) \setminus I$ , we have that  $I + e \notin \mathcal{I}$ . This is a set addition restriction property.
- Analogously, for  $e \in \text{sat}(x)$ , any  $x + \alpha \mathbf{1}_e \notin P_f$  for  $\alpha > 0$ . This is a vector increase restriction property.
- Recall, we have  $C(I, e) \setminus e' \in \mathcal{I}$  for  $e' \in C(I, e)$ . I.e.,  $C(I, e)$  consists of elements that when removed recover independence.
- In other words, given an  $e \in \text{span}(I) \setminus I$ , we have that

$$C(I, e) = \{a \in E : I + e - a \in \mathcal{I}\} \quad (19.13)$$

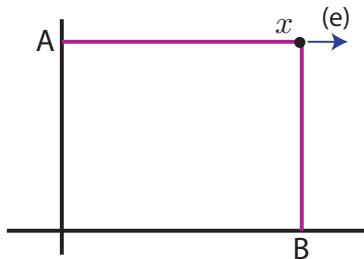
- I.e., an addition of  $e$  to  $I$  stays within  $\mathcal{I}$  only if we simultaneously remove one of the elements of  $C(I, e)$ .
- But, analogous to the circuit case, is there an exchange property for  $\text{dep}(x, e)$  in the form of vector movement restriction?
- We might expect the vector  $\text{dep}(x, e)$  property to take the form: a positive move in the  $e$ -direction stays within  $P_f^+$  only if we simultaneously take a negative move in one of the  $\text{dep}(x, e)$  directions.

# Dependence Function and exchange in 2D

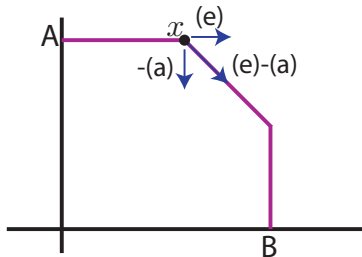
- $\text{dep}(x, e)$  is set of neg. directions we must move if we want to move in pos.  $e$  direction, starting at  $x$  and staying within  $P_f$ .

# Dependence Function and exchange in 2D

- $\text{dep}(x, e)$  is set of neg. directions we must move if we want to move in pos.  $e$  direction, starting at  $x$  and staying within  $P_f$ .
- Viewable in 2D, we have for  $A, B \subseteq E$ ,  $A \cap B = \emptyset$ :



Left:  $e \in B$  and  $A \cap \text{dep}(x, e) = \emptyset$ , and we can't move further in  $(e)$  direction, and moving in any negative  $a \in A$  direction doesn't change that. **No dependence** between  $(e)$  and any element in  $A$ .



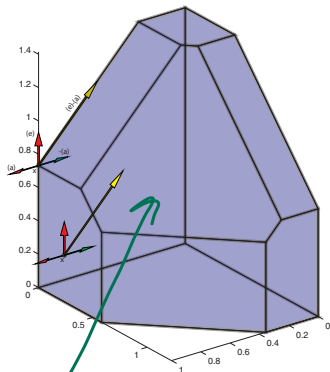
Right:  $A \subseteq \text{dep}(x, e)$ . We can't move further in the  $(e)$  direction, but we can move further in  $(e)$  direction by moving in some negative  $a \in A$  direction. **Dependence** between  $(e)$  and elements in  $A$ .

## Dependence Function and exchange in 3D

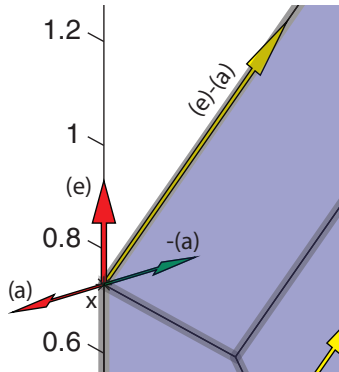
- We can move neither in the (e) nor the (a) direction, but we can move in the (e) direction if we simultaneously move in the  $-(a)$  direction.

# Dependence Function and exchange in 3D

- We can move neither in the (e) nor the (a) direction, but we can move in the (e) direction if we simultaneously move in the -(a) direction.
- In 3D, we have:

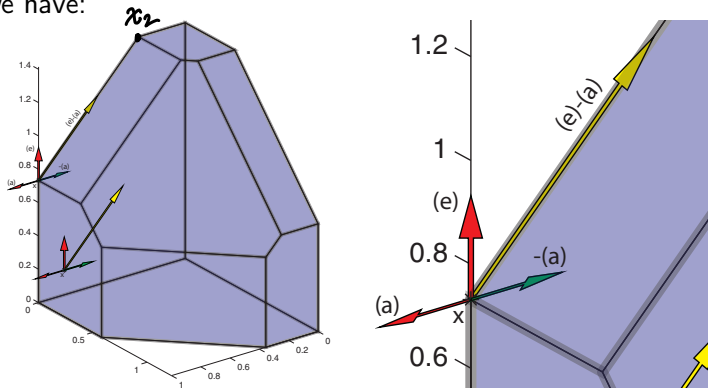


bf



# Dependence Function and exchange in 3D

- We can move neither in the (e) nor the (a) direction, but we can move in the (e) direction if we simultaneously move in the -(a) direction.
- In 3D, we have:

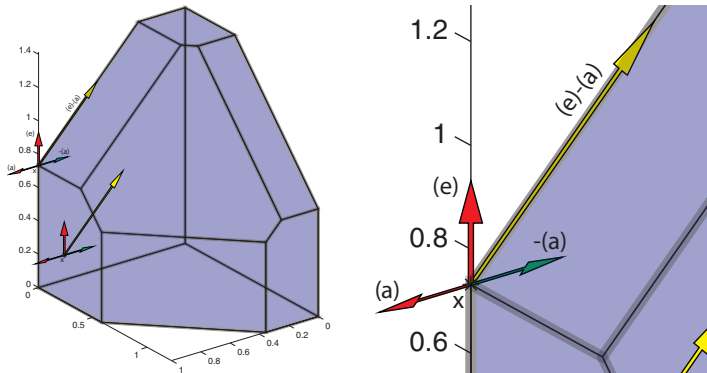


- I.e., for  $e \in \text{sat}(x)$ ,  $a \in \text{sat}(x)$ ,  $a \in \text{dep}(x, e)$ ,  $e \notin \text{dep}(x, a)$ ,

*we do have  $e \in \text{dep}(x_2, a)$   
 $a \notin \text{dep}(x_2, e)$*

# Dependence Function and exchange in 3D

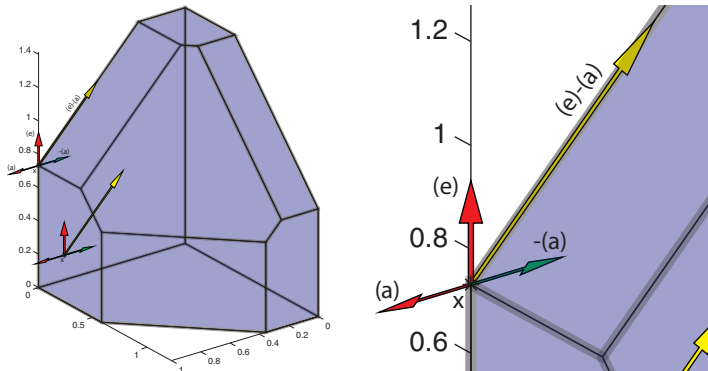
- We can move neither in the (e) nor the (a) direction, but we can move in the (e) direction if we simultaneously move in the -(a) direction.
- In 3D, we have:



- I.e., for  $e \in \text{sat}(x)$ ,  $a \in \text{sat}(x)$ ,  $a \in \text{dep}(x, e)$ ,  $e \notin \text{dep}(x, a)$ , and
 
$$\text{dep}(x, e) = \{a : a \in E, \exists \alpha > 0 : x + \alpha(\mathbf{1}_e - \mathbf{1}_a) \in P_f\} \quad (19.14)$$

# Dependence Function and exchange in 3D

- We can move neither in the (e) nor the (a) direction, but we can move in the (e) direction if we simultaneously move in the -(a) direction.
- In 3D, we have:



- I.e., for  $e \in \text{sat}(x)$ ,  $a \in \text{sat}(x)$ ,  $a \in \text{dep}(x, e)$ ,  $e \notin \text{dep}(x, a)$ , and
 
$$\text{dep}(x, e) = \{a : a \in E, \exists \alpha > 0 : x + \alpha(\mathbf{1}_e - \mathbf{1}_a) \in P_f\} \quad (19.14)$$
- We next show this formally ...



# dep and exchange derived

- The derivation for  $\text{dep}(x, e)$ ,  $x \in P_f$ , involves turning a strict inequality into a non-strict one with a strict explicit slack variable  $\alpha$ :

$$\text{dep}(x, e) = \text{ntight}(x, e) = \tag{19.15}$$

# dep and exchange derived

- The derivation for  $\text{dep}(x, e)$ ,  $x \in P_f$ , involves turning a strict inequality into a non-strict one with a strict explicit slack variable  $\alpha$ :

$$\text{dep}(x, e) = \text{ntight}(x, e) = \tag{19.15}$$

$$= \{e' : x(A) < f(A), \forall A \ni e', e \in A\} \tag{19.16}$$

# dep and exchange derived

- The derivation for  $\text{dep}(x, e)$ ,  $x \in P_f$ , involves turning a strict inequality into a non-strict one with a strict explicit slack variable  $\alpha$ :

$$\text{dep}(x, e) = \text{ntight}(x, e) = \tag{19.15}$$

$$= \{e' : x(A) < f(A), \forall A \ni e', e \in A\} \tag{19.16}$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \leq f(A) - x(A), \forall A \ni e', e \in A\} \tag{19.17}$$

# dep and exchange derived

- The derivation for  $\text{dep}(x, e)$ ,  $x \in P_f$ , involves turning a strict inequality into a non-strict one with a strict explicit slack variable  $\alpha$ :

$$\text{dep}(x, e) = \text{ntight}(x, e) = \tag{19.15}$$

$$= \{e' : x(A) < f(A), \forall A \ni e', e \in A\} \tag{19.16}$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \leq f(A) - x(A), \forall A \ni e', e \in A\} \tag{19.17}$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \mathbf{1}_e(A) \leq f(A) - x(A), \forall A \ni e', e \in A\} \tag{19.18}$$

$\underbrace{\hspace{1.5cm}}_{=\alpha}$

# dep and exchange derived

- The derivation for  $\text{dep}(x, e)$ ,  $x \in P_f$ , involves turning a strict inequality into a non-strict one with a strict explicit slack variable  $\alpha$ :

$$\text{dep}(x, e) = \text{ntight}(x, e) = \quad (19.15)$$

$$= \{e' : x(A) < f(A), \forall A \not\ni e', e \in A\} \quad (19.16)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \leq f(A) - x(A), \forall A \not\ni e', e \in A\} \quad (19.17)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \mathbf{1}_e(A) \leq f(A) - x(A), \forall A \not\ni e', e \in A\} \quad (19.18)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A) - x(A), \forall A \not\ni e', e \in A\} \quad (19.19)$$

$$\mathbf{1}_{e'}(A) = 0$$

# dep and exchange derived

- The derivation for  $\text{dep}(x, e)$ ,  $x \in P_f$ , involves turning a strict inequality into a non-strict one with a strict explicit slack variable  $\alpha$ :

$$\text{dep}(x, e) = \text{ntight}(x, e) = \tag{19.15}$$

$$= \{e' : x(A) < f(A), \forall A \ni e', e \in A\} \tag{19.16}$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \leq f(A) - x(A), \forall A \ni e', e \in A\} \tag{19.17}$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \mathbf{1}_e(A) \leq f(A) - x(A), \forall A \ni e', e \in A\} \tag{19.18}$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A) - x(A), \forall A \ni e', e \in A\} \tag{19.19}$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } x(A) + \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A), \forall A \ni e', e \in A\} \tag{19.20}$$

# dep and exchange derived

- The derivation for  $\text{dep}(x, e)$ ,  $x \in P_f$ , involves turning a strict inequality into a non-strict one with a strict explicit slack variable  $\alpha$ :

$$\text{dep}(x, e) = \text{ntight}(x, e) = \quad (19.15)$$

$$= \{e' : x(A) < f(A), \forall A \ni e', e \in A\} \quad (19.16)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \leq f(A) - x(A), \forall A \ni e', e \in A\} \quad (19.17)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \mathbf{1}_e(A) \leq f(A) - x(A), \forall A \ni e', e \in A\} \quad (19.18)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A) - x(A), \forall A \ni e', e \in A\} \quad (19.19)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } x(A) + \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A), \forall A \ni e', e \in A\} \quad (19.20)$$

- Now,  $\mathbf{1}_e(A) - \mathbf{1}_{e'}(A) = 0$  if either  $\{e, e'\} \subseteq A$ , or  $\{e, e'\} \cap A = \emptyset$ .

# dep and exchange derived

- The derivation for  $\text{dep}(x, e)$ ,  $x \in P_f$ , involves turning a strict inequality into a non-strict one with a strict explicit slack variable  $\alpha$ :

$$\text{dep}(x, e) = \text{ntight}(x, e) = \quad (19.15)$$

$$= \{e' : x(A) < f(A), \forall A \not\ni e', e \in A\} \quad (19.16)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \leq f(A) - x(A), \forall A \not\ni e', e \in A\} \quad (19.17)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha \mathbf{1}_e(A) \leq f(A) - x(A), \forall A \not\ni e', e \in A\} \quad (19.18)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A) - x(A), \forall A \not\ni e', e \in A\} \quad (19.19)$$

$$= \{e' : \exists \alpha > 0, \text{ s.t. } x(A) + \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A), \forall A \not\ni e', e \in A\} \quad (19.20)$$

- Now,  $\mathbf{1}_e(A) - \mathbf{1}_{e'}(A) = 0$  if either  $\{e, e'\} \subseteq A$ , or  $\{e, e'\} \cap A = \emptyset$ .
- Also, if  $e' \in A$  but  $e \notin A$ , then  $x(A) + \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) = x(A) - \alpha \leq f(A)$  since  $x \in P_f$  and  $\alpha > 0$ .



# dep and exchange derived

- thus, we get the same in the above if we remove the constraint  $A \not\supseteq e', e \in A$ , that is we get

$$\text{dep}(x, e) = \{e' : \exists \alpha > 0, \text{ s.t. } x(A) + \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A), \forall A\} \quad (19.21)$$

# dep and exchange derived

- thus, we get the same in the above if we remove the constraint  $A \not\supseteq e', e \in A$ , that is we get

$$\text{dep}(x, e) = \{e' : \exists \alpha > 0, \text{ s.t. } x(A) + \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A), \forall A\} \quad (19.21)$$

- This is then identical to

$$\text{dep}(x, e) = \{e' : \exists \alpha > 0, \text{ s.t. } x + \alpha(\mathbf{1}_e - \mathbf{1}_{e'}) \in P_f\} \quad (19.22)$$

# dep and exchange derived

- thus, we get the same in the above if we remove the constraint  $A \not\ni e', e \in A$ , that is we get

$$\text{dep}(x, e) = \{e' : \exists \alpha > 0, \text{ s.t. } x(A) + \alpha(\mathbf{1}_e(A) - \mathbf{1}_{e'}(A)) \leq f(A), \forall A\} \quad (19.21)$$

- This is then identical to

$$\text{dep}(x, e) = \{e' : \exists \alpha > 0, \text{ s.t. } x + \alpha(\mathbf{1}_e - \mathbf{1}_{e'}) \in P_f\} \quad (19.22)$$

- Compare with original, the minimal element of  $\mathcal{D}(x, e)$ , with  $e \in \text{sat}(x)$ :

$$\text{dep}(x, e) = \begin{cases} \bigcap \{A : e \in A \subseteq E, x(A) = f(A)\} & \text{if } e \in \text{sat}(x) \\ \emptyset & \text{else} \end{cases} \quad (19.23)$$

# Submodular Function Minimization (SFM)

- We now have the tools to discuss unconstrained SFM.

# Submodular Function Minimization (SFM)

- We now have the tools to discuss unconstrained SFM.
- We saw that SFM can be used to solve most violated inequality problems for a given  $x \in P_f$  and, in general, SFM can solve the question “Is  $x \in P_f$ ” by seeing if  $x$  violates any inequality (if the most violated one is negative, solution to SFM, then  $x \in P_f$ ). That is, given  $x \in \mathbb{R}^V$ , compute either:

$$\min_{A \subseteq V} (f(A) - x(A)), \text{ or } \min_{A \subseteq V} (f(A) + x(V \setminus A)). \quad (19.24)$$

# Submodular Function Minimization (SFM)

- We now have the tools to discuss unconstrained SFM.
- We saw that SFM can be used to solve most violated inequality problems for a given  $x \in P_f$  and, in general, SFM can solve the question “Is  $x \in P_f$ ” by seeing if  $x$  violates any inequality (if the most violated one is negative, solution to SFM, then  $x \in P_f$ ). That is, given  $x \in \mathbb{R}^V$ , compute either:

$$\min_{A \subseteq V} (f(A) - x(A)), \text{ or } \min_{A \subseteq V} (f(A) + x(V \setminus A)). \quad (19.24)$$

- Unconstrained SFM,  $\min_{A \subseteq V} f(A)$  solves many other problems as well in combinatorial optimization, machine learning, and other fields. It generally produces sets that are homogeneous in some way as measured by  $f$ .

# SFM application in ML: Low complexity data subsets.

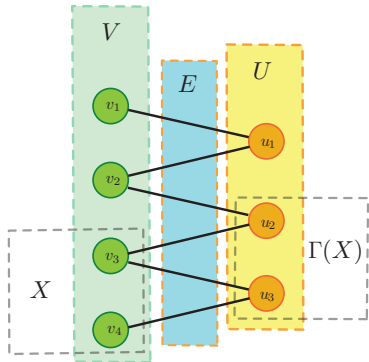
- Find large (or preferable) and low-complexity subsets of datasets *Lin & Bilmes, "An Application of the Submodular Principal Partition to Training Data Subset Selection", NeurIPS workshops 2011*

# SFM application in ML: Low complexity data subsets.

- Find large (or preferable) and low-complexity subsets of datasets *Lin & Bilmes, "An Application of the Submodular Principal Partition to Training Data Subset Selection", NeurIPS workshops 2011*

Given bipartite graph  $G = (V, U, E)$ , nodes  $V$ ,  $U$  and edges  $E$ , where  $V$  is a set of data objects,  $U$  is a set of possible properties of each data object (e.g., objects in images, or words in documents).

- each data object (e.g., objects in images, or words in documents). Neighbor function  $\Gamma(X) \subseteq U$  are the objects in  $X \subseteq V$  and  $f(\Gamma(X))$  is submodular for submodular  $f : 2^U \rightarrow \mathbb{R}_+$ .



Exercises

$$\text{Simple est } f(z) = |z|$$

$$f(\Gamma(X)) = |\Gamma(X)|$$

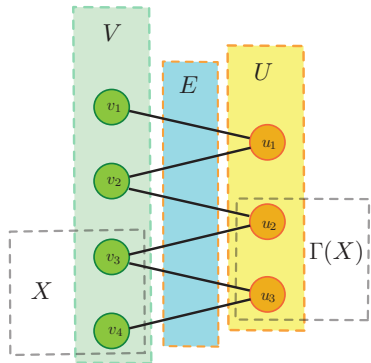


# SFM application in ML: Low complexity data subsets.

- Find large (or preferable) and low-complexity subsets of datasets *Lin & Bilmes, "An Application of the Submodular Principal Partition to Training Data Subset Selection", NeurIPS workshops 2011*

Given bipartite graph  $G = (V, U, E)$ , nodes  $V$ ,  $U$  and edges  $E$ , where  $V$  is a set of data objects,  $U$  is a set of possible properties of each data object (e.g., objects in images, or words in documents).

- each data object (e.g., objects in images, or words in documents). Neighbor function  $\Gamma(X) \subseteq U$  are the objects in  $X \subseteq V$  and  $f(\Gamma(X))$  is submodular for submodular  $f : 2^U \rightarrow \mathbb{R}_+$ .



- Given modular  $w : 2^V \rightarrow \mathbb{R}_+$  scores for objects  $v \in V$ . Then  $h(X) = w(V \setminus X) + f(\Gamma(X))$  is submodular, the minimization (SFM) of which produces are desirable ( $w(X)$  big, large if  $w(X) = |X|$ ) subset that is low complexity relative to  $f(\Gamma(X))$ .  $\lambda \cdot f(\Gamma(X)) - w(X) = h(X)$

# Ellipsoid algorithm, and polynomial time SFM

- For a long time, it was not known if general purpose submodular function minimization was possible in polynomial time.

# Ellipsoid algorithm, and polynomial time SFM

- For a long time, it was not known if general purpose submodular function minimization was possible in polynomial time.
- This was answered in the early 1980s via the help of Edmonds's greedy algorithm from 1970.

# Ellipsoid algorithm, and polynomial time SFM

- For a long time, it was not known if general purpose submodular function minimization was possible in polynomial time.
- This was answered in the early 1980s via the help of Edmonds's greedy algorithm from 1970. Let  $C \subseteq \mathbb{R}^V$  be a non-empty convex compact set.

# Ellipsoid algorithm, and polynomial time SFM

- For a long time, it was not known if general purpose submodular function minimization was possible in polynomial time.
- This was answered in the early 1980s via the help of Edmonds's greedy algorithm from 1970. Let  $C \subseteq \mathbb{R}^V$  be a non-empty convex compact set.

## Definition 19.4.1 ((strong) optimization problem)

Given  $c \in \mathbb{R}^V$ , find a vector  $x \in C$  that maximizes  $c^\top x$  on  $C$ . I.e., solve

$$\max_{x \in C} c^\top x \quad (19.25)$$

# Ellipsoid algorithm, and polynomial time SFM

- For a long time, it was not known if general purpose submodular function minimization was possible in polynomial time.
- This was answered in the early 1980s via the help of Edmonds's greedy algorithm from 1970. Let  $C \subseteq \mathbb{R}^V$  be a non-empty convex compact set.

## Definition 19.4.1 ((strong) optimization problem)

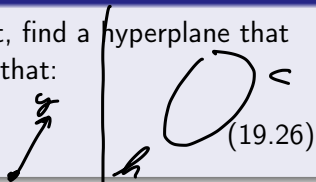
Given  $c \in \mathbb{R}^V$ , find a vector  $x \in C$  that maximizes  $c^\top x$  on  $C$ . I.e., solve

$$\max_{x \in C} c^\top x \quad (19.25)$$

## Definition 19.4.2 ((strong) separation problem)

Given a vector  $y \in \mathbb{R}^V$ , decide if  $y \in C$ , and if not, find a hyperplane that separates  $y$  from  $C$ . I.e., find vector  $c \in \mathbb{R}^V$  such that:

$$c^\top y > \max_{x \in C} c^\top x$$



# Ellipsoid algorithm, and polynomial time SFM

- We have the following important theorem:

# Ellipsoid algorithm, and polynomial time SFM

- We have the following important theorem:

## Theorem 19.4.3 (Grötschel, Lovász, and Schrijver, 1981)

*Let  $\mathcal{C}$  be set of convex sets. Then there is a polynomial-time algorithm to solve the separation problem for the members of  $\mathcal{C}$  iff there is a polynomial-time algorithm to solve the optimization problem for the members of  $\mathcal{C}$ .*



# Ellipsoid algorithm, and polynomial time SFM

- We have the following important theorem:

## Theorem 19.4.3 (Grötschel, Lovász, and Schrijver, 1981)

*Let  $\mathcal{C}$  be set of convex sets. Then there is a polynomial-time algorithm to solve the separation problem for the members of  $\mathcal{C}$  iff there is a polynomial-time algorithm to solve the optimization problem for the members of  $\mathcal{C}$ .*

- We saw already that the Edmonds greedy algorithm solves the strong optimization problem for polymatroidal polytopes, e.g.,  $\max_{x \in B_f} c^T x$ .

# Ellipsoid algorithm, and polynomial time SFM

- We have the following important theorem:

## Theorem 19.4.3 (Grötschel, Lovász, and Schrijver, 1981)

*Let  $\mathcal{C}$  be set of convex sets. Then there is a polynomial-time algorithm to solve the separation problem for the members of  $\mathcal{C}$  iff there is a polynomial-time algorithm to solve the optimization problem for the members of  $\mathcal{C}$ .*

- We saw already that the Edmonds greedy algorithm solves the strong optimization problem for polymatroidal polytopes, e.g.,  $\max_{x \in B_f} c^T x$ .
- The ellipsoid algorithm first bounds a polytope  $P$  with an ellipsoid, and then creates a sequence of ellipsoids of exponentially decreasing volume which are used to address a  $P$  membership problem.

# Ellipsoid algorithm, and polynomial time SFM

- We have the following important theorem:

## Theorem 19.4.3 (Grötschel, Lovász, and Schrijver, 1981)

*Let  $\mathcal{C}$  be set of convex sets. Then there is a polynomial-time algorithm to solve the separation problem for the members of  $\mathcal{C}$  iff there is a polynomial-time algorithm to solve the optimization problem for the members of  $\mathcal{C}$ .*

- We saw already that the Edmonds greedy algorithm solves the strong optimization problem for polymatroidal polytopes, e.g.,  $\max_{x \in B_f} c^T x$ .
- The ellipsoid algorithm first bounds a polytope  $P$  with an ellipsoid, and then creates a sequence of ellipsoids of exponentially decreasing volume which are used to address a  $P$  membership problem.
- This is sufficient to show that we can solve SFM in polynomial time! See the book: Grötschel, Lovász, and Schrijver, "Geometric Algorithms and Combinatorial Optimization" for details.

# Ellipsoid algorithm, and polynomial time SFM

- We have the following important theorem:

## Theorem 19.4.3 (Grötschel, Lovász, and Schrijver, 1981)

*Let  $\mathcal{C}$  be set of convex sets. Then there is a polynomial-time algorithm to solve the separation problem for the members of  $\mathcal{C}$  iff there is a polynomial-time algorithm to solve the optimization problem for the members of  $\mathcal{C}$ .*

- We saw already that the Edmonds greedy algorithm solves the strong optimization problem for polymatroidal polytopes, e.g.,  $\max_{x \in B_f} c^T x$ .
- The ellipsoid algorithm first bounds a polytope  $P$  with an ellipsoid, and then creates a sequence of ellipsoids of exponentially decreasing volume which are used to address a  $P$  membership problem.
- This is sufficient to show that we can solve SFM in polynomial time! See the book: Grötschel, Lovász, and Schrijver, "Geometric Algorithms and Combinatorial Optimization" for details.
- Unfortunately, it does not lead to a practical algorithm.

# Lovász extension, convex minimization, and SFM

- SFM is also related to the convexity of the Lovász extension, the ease of minimizing convex functions.

# Lovász extension, convex minimization, and SFM

- SFM is also related to the convexity of the Lovász extension, the ease of minimizing convex functions.
- We can recover  $f$  from  $\check{f}$  via  $f(A) = \check{f}(\mathbf{1}_A)$ . We can also minimize  $\check{f}$  since it is convex.

# Lovász extension, convex minimization, and SFM

- SFM is also related to the convexity of the Lovász extension, the ease of minimizing convex functions.
- We can recover  $f$  from  $\check{f}$  via  $f(A) = \check{f}(\mathbf{1}_A)$ . We can also minimize  $\check{f}$  since it is convex.
- We will now show that we can get discrete solutions to the minimization of  $f$  from the continuous solution to the minimization of  $\check{f}$ .

# Review from lecture 17

- The next slide comes from lecture 17.



# One slide review of convex closure/L.E./CI

- convex closure  $\check{f}(x) = \min_{p \in \Delta^n(x)} E_{S \sim p}[f(S)]$ , where  $\Delta^n(x) = \left\{ p \in \mathbb{R}^{2^n} : \sum_{S \subseteq V} p_S = 1, p_S \geq 0 \forall S \subseteq V, \& \sum_{S \subseteq V} p_S \mathbf{1}_S = x \right\}$
- “Edmonds” extension  $\check{f}(w) = \max(w x : x \in B_f)$  *quality.*
- Lovász extension  $f_{LE}(w) = \sum_{i=1}^m \lambda_i f(E_i)$ , with  $\lambda_i$  such that  $w = \sum_{i=1}^m \lambda_i \mathbf{1}_{E_i}$
- $f_{\sigma^*}(w) = \max_{\sigma \in \Pi_{[m]}} w^\top c^\sigma$ ,  $\Pi_{[m]}$  set of  $m!$  permutations of  $[m]$ ,  $\sigma \in \Pi_{[m]}$  a permutation,  $c^\sigma$  vector with  $c_i^\sigma = f(E_{\sigma_i}) - f(E_{\sigma_{i-1}})$ ,  $E_{\sigma_i} = \{e_{\sigma_1}, e_{\sigma_2}, \dots, e_{\sigma_i}\}$ .
- Choquet integral  $C_f(w) = \sum_{i=1}^m (w_{e_i} - w_{e_{i+1}}) f(E_i)$
- $f(w) = \int_{-\infty}^{+\infty} \hat{f}(\alpha) d\alpha$ ,  $\hat{f}(\alpha) = \begin{cases} f(\{w \geq \alpha\}) & \text{if } \alpha \geq 0 \\ f(\{w \geq \alpha\}) - f(E) & \text{if } \alpha < 0 \end{cases}$
- All the same when  $f$  is submodular. We'll use  $\check{f}(w)$  for the Lovász extension.

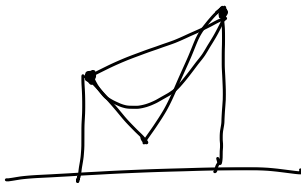
# Minimizing $\check{f}$ vs. minimizing $f$

In fact, we have:

## Theorem 19.5.1

Let  $f$  be submodular and  $\check{f}$  be its Lovász extension. Then

$$\min \{f(A) \mid A \subseteq E\} = \min_{w \in \{0,1\}^E} \check{f}(w) = \min_{w \in [0,1]^E} \check{f}(w).$$



# Minimizing $\check{f}$ vs. minimizing $f$

In fact, we have:

## Theorem 19.5.1

Let  $f$  be submodular and  $\check{f}$  be its Lovász extension. Then

$$\min \{f(A) \mid A \subseteq E\} = \min_{w \in \{0,1\}^E} \check{f}(w) = \min_{w \in [0,1]^E} \check{f}(w).$$

## Proof.

- First, since  $\check{f}(\mathbf{1}_A) = f(A), \forall A \subseteq V$ , we clearly have
 
$$\min \{f(A) \mid A \subseteq V\} = \min_{w \in \{0,1\}^E} \check{f}(w) \geq \min_{w \in [0,1]^E} \check{f}(w).$$

# Minimizing $\check{f}$ vs. minimizing $f$

In fact, we have:

## Theorem 19.5.1

Let  $f$  be submodular and  $\check{f}$  be its Lovász extension. Then

$$\min \{f(A) \mid A \subseteq E\} = \min_{w \in \{0,1\}^E} \check{f}(w) = \min_{w \in [0,1]^E} \check{f}(w).$$

## Proof.

- First, since  $\check{f}(\mathbf{1}_A) = f(A), \forall A \subseteq V$ , we clearly have
 
$$\min \{f(A) \mid A \subseteq V\} = \min_{w \in \{0,1\}^E} \check{f}(w) \geq \min_{w \in [0,1]^E} \check{f}(w).$$
- Next, consider any  $w \in [0,1]^E$ , sort elements  $E = \{e_1, \dots, e_m\}$  as  $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$ , define  $E_i = \{e_1, \dots, e_i\}$ , and define  $\lambda_m = w(e_m)$  and  $\lambda_i = w(e_i) - w(e_{i+1})$  for  $i \in \{1, \dots, m-1\}$ .

# Minimizing $\check{f}$ vs. minimizing $f$

In fact, we have:

## Theorem 19.5.1

Let  $f$  be submodular and  $\check{f}$  be its Lovász extension. Then

$$\min \{f(A) \mid A \subseteq E\} = \min_{w \in \{0,1\}^E} \check{f}(w) = \min_{w \in [0,1]^E} \check{f}(w).$$

## Proof.

- First, since  $\check{f}(\mathbf{1}_A) = f(A), \forall A \subseteq V$ , we clearly have
 
$$\min \{f(A) \mid A \subseteq V\} = \min_{w \in \{0,1\}^E} \check{f}(w) \geq \min_{w \in [0,1]^E} \check{f}(w).$$
- Next, consider any  $w \in [0,1]^E$ , sort elements  $E = \{e_1, \dots, e_m\}$  as  $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$ , define  $E_i = \{e_1, \dots, e_i\}$ , and define  $\lambda_m = w(e_m)$  and  $\lambda_i = w(e_i) - w(e_{i+1})$  for  $i \in \{1, \dots, m-1\}$ .
- Then, as we have seen,  $w = \sum_i \lambda_i \mathbf{1}_{E_i}$  and  $\lambda_i \geq 0$ .

# Minimizing $\check{f}$ vs. minimizing $f$

In fact, we have:

## Theorem 19.5.1

Let  $f$  be submodular and  $\check{f}$  be its Lovász extension. Then

$$\min \{f(A) \mid A \subseteq E\} = \min_{w \in \{0,1\}^E} \check{f}(w) = \min_{w \in [0,1]^E} \check{f}(w).$$

## Proof.

- First, since  $\check{f}(\mathbf{1}_A) = f(A), \forall A \subseteq V$ , we clearly have
 
$$\min \{f(A) \mid A \subseteq V\} = \min_{w \in \{0,1\}^E} \check{f}(w) \geq \min_{w \in [0,1]^E} \check{f}(w).$$
- Next, consider any  $w \in [0,1]^E$ , sort elements  $E = \{e_1, \dots, e_m\}$  as  $w(e_1) \geq w(e_2) \geq \dots \geq w(e_m)$ , define  $E_i = \{e_1, \dots, e_i\}$ , and define  $\lambda_m = w(e_m)$  and  $\lambda_i = w(e_i) - w(e_{i+1})$  for  $i \in \{1, \dots, m-1\}$ .
- Then, as we have seen,  $w = \sum_i \lambda_i \mathbf{1}_{E_i}$  and  $\lambda_i \geq 0$ .
- Also,  $\sum_i \lambda_i = w(e_1) \leq 1$ .

# Minimizing $f$ vs. minimizing $f$

... cont. proof of Thm. 19.5.1.

- Note that since  $f(\emptyset) = 0$ ,  $\min \{f(A) \mid A \subseteq E\} \leq 0$ .



# Minimizing $\check{f}$ vs. minimizing $f$

... cont. proof of Thm. 19.5.1.

- Note that since  $f(\emptyset) = 0$ ,  $\min \{f(A) | A \subseteq E\} \leq 0$ .
- Then we have for all  $w \in [0, 1]^E$ ,

$$\check{f}(w) = \int_0^1 f(\{w \geq \alpha\}) d\alpha = \sum_{i=1}^m \lambda_i f(E_i) \quad (19.27)$$

$$\geq \sum_{i=1}^m \lambda_i \min_{A \subseteq E} f(A) \quad (19.28)$$

$$\geq \min_{A \subseteq E} f(A) \quad \sum_{i=1}^m \lambda_i \leq 1 \quad (19.29)$$





# Minimizing $\check{f}$ vs. minimizing $f$

... cont. proof of Thm. 19.5.1.

- Note that since  $f(\emptyset) = 0$ ,  $\min \{f(A) | A \subseteq E\} \leq 0$ .
- Then we have for all  $w \in [0, 1]^E$ ,

$$\check{f}(w) = \int_0^1 f(\{w \geq \alpha\}) d\alpha = \sum_{i=1}^m \lambda_i f(E_i) \quad (19.27)$$

$$\geq \sum_{i=1}^m \lambda_i \min_{A \subseteq E} f(A) \quad (19.28)$$

$$\geq \min_{A \subseteq E} f(A) \quad (19.29)$$

- Thus,  $\min \{f(A) | A \subseteq E\} = \min_{w \in [0, 1]^E} \check{f}(w)$ .



## Other minimizers based on min of $f$

- Let  $w^* \in \operatorname{argmin} \{ \check{f}(w) \mid w \in [0, 1]^E \}$  and let  $A^* \in \operatorname{argmin} \{ f(A) \mid A \subseteq V \}$ .

  
a lattice.

## Other minimizers based on min of $\check{f}$

- Let  $w^* \in \operatorname{argmin} \left\{ \check{f}(w) \mid w \in [0, 1]^E \right\}$  and let  $A^* \in \operatorname{argmin} \{ f(A) \mid A \subseteq V \}$ .
- Previous theorem states that  $\check{f}(w^*) = f(A^*)$ .

## Other minimizers based on $\check{f}$

- Let  $w^* \in \operatorname{argmin} \{ \check{f}(w) | w \in [0, 1]^E \}$  and let  $A^* \in \operatorname{argmin} \{ f(A) | A \subseteq V \}$ .
- Previous theorem states that  $\check{f}(w^*) = f(A^*)$ .
- Let  $\lambda_i^*$  be the Lovász extension weights and  $E_i^*$  be the chain of sets associated with optimal  $w^*$ . From previous theorem, we have

$$\check{f}(w^*) = \sum_i \lambda_i^* f(E_i^*) = f(A^*) = \min \{ f(A) | A \subseteq E \} \quad (19.30)$$

## Other minimizers based on min of $\check{f}$

- Let  $w^* \in \operatorname{argmin} \{ \check{f}(w) | w \in [0, 1]^E \}$  and let  $A^* \in \operatorname{argmin} \{ f(A) | A \subseteq V \}$ .
- Previous theorem states that  $\check{f}(w^*) = f(A^*)$ .
- Let  $\lambda_i^*$  be the Lovász extension weights and  $E_i^*$  be the chain of sets associated with optimal  $w^*$ . From previous theorem, we have

$$\check{f}(w^*) = \sum_i \lambda_i^* f(E_i^*) = f(A^*) = \min \{ f(A) | A \subseteq E \} \quad (19.30)$$

and that  $f(A^*) \leq f(E_i^*), \forall i$ ,

## Other minimizers based on min of $\check{f}$

- Let  $w^* \in \operatorname{argmin} \{ \check{f}(w) | w \in [0, 1]^E \}$  and let  $A^* \in \operatorname{argmin} \{ f(A) | A \subseteq V \}$ .
- Previous theorem states that  $\check{f}(w^*) = f(A^*)$ .
- Let  $\lambda_i^*$  be the Lovász extension weights and  $E_i^*$  be the chain of sets associated with optimal  $w^*$ . From previous theorem, we have

$$\check{f}(w^*) = \sum_i \lambda_i^* f(E_i^*) = f(A^*) = \min \{ f(A) | A \subseteq E \} \quad (19.30)$$

and that  $f(A^*) \leq f(E_i^*), \forall i$ , and that  $f(A^*) \leq 0$ ,

## Other minimizers based on min of $\check{f}$

- Let  $w^* \in \operatorname{argmin} \{ \check{f}(w) | w \in [0, 1]^E \}$  and let  $A^* \in \operatorname{argmin} \{ f(A) | A \subseteq V \}$ .
- Previous theorem states that  $\check{f}(w^*) = f(A^*)$ .
- Let  $\lambda_i^*$  be the Lovász extension weights and  $E_i^*$  be the chain of sets associated with optimal  $w^*$ . From previous theorem, we have

$$\check{f}(w^*) = \sum_i \lambda_i^* f(E_i^*) = f(A^*) = \min \{ f(A) | A \subseteq E \} \quad (19.30)$$

and that  $f(A^*) \leq f(E_i^*), \forall i$ , and that  $f(A^*) \leq 0$ , and  $\sum_i \lambda_i \leq 1$ .

## Other minimizers based on min of $\check{f}$

- Let  $w^* \in \operatorname{argmin} \{ \check{f}(w) | w \in [0, 1]^E \}$  and let  $A^* \in \operatorname{argmin} \{ f(A) | A \subseteq V \}$ .
- Previous theorem states that  $\check{f}(w^*) = f(A^*)$ .
- Let  $\lambda_i^*$  be the Lovász extension weights and  $E_i^*$  be the chain of sets associated with optimal  $w^*$ . From previous theorem, we have

$$\check{f}(w^*) = \sum_i \lambda_i^* f(E_i^*) = f(A^*) = \min \{ f(A) | A \subseteq E \} \quad (19.30)$$

and that  $f(A^*) \leq f(E_i^*), \forall i$ , and that  $f(A^*) \leq 0$ , and  $\sum_i \lambda_i \leq 1$ .

- Thus, since  $w^* \in [0, 1]^E$ , each  $0 \leq \lambda_i^* \leq 1$ , we have for all  $i$  such that  $\lambda_i^* > 0$ ,

$$f(E_i^*) = f(A^*) \quad (19.31)$$

meaning such  $E_i^*$  are also minimizers of  $f$ , and  $\sum_i \lambda_i = 1$ .



## Other minimizers based on min of $\check{f}$

- Let  $w^* \in \operatorname{argmin} \{ \check{f}(w) | w \in [0, 1]^E \}$  and let  $A^* \in \operatorname{argmin} \{ f(A) | A \subseteq V \}$ .
- Previous theorem states that  $\check{f}(w^*) = f(A^*)$ .
- Let  $\lambda_i^*$  be the Lovász extension weights and  $E_i^*$  be the chain of sets associated with optimal  $w^*$ . From previous theorem, we have

$$\check{f}(w^*) = \sum_i \lambda_i^* f(E_i^*) = f(A^*) = \min \{ f(A) | A \subseteq E \} \quad (19.30)$$

and that  $f(A^*) \leq f(E_i^*), \forall i$ , and that  $f(A^*) \leq 0$ , and  $\sum_i \lambda_i \leq 1$ .

- Thus, since  $w^* \in [0, 1]^E$ , each  $0 \leq \lambda_i^* \leq 1$ , we have for all  $i$  such that  $\lambda_i^* > 0$ ,

$$f(E_i^*) = f(A^*) \quad (19.31)$$

meaning such  $E_i^*$  are also minimizers of  $f$ , and  $\sum_i \lambda_i = 1$ .

- Note that the negative of  $f(A^*)$  is crucial here (see next slides).

## Other minimizers based on min of $\check{f}$

- Let  $w^* \in \operatorname{argmin} \{ \check{f}(w) | w \in [0, 1]^E \}$  and let  $A^* \in \operatorname{argmin} \{ f(A) | A \subseteq V \}$ .
- Previous theorem states that  $\check{f}(w^*) = f(A^*)$ .
- Let  $\lambda_i^*$  be the Lovász extension weights and  $E_i^*$  be the chain of sets associated with optimal  $w^*$ . From previous theorem, we have

$$\check{f}(w^*) = \sum_i \lambda_i^* f(E_i^*) = f(A^*) = \min \{ f(A) | A \subseteq E \} \quad (19.30)$$

and that  $f(A^*) \leq f(E_i^*), \forall i$ , and that  $f(A^*) \leq 0$ , and  $\sum_i \lambda_i \leq 1$ .

- Thus, since  $w^* \in [0, 1]^E$ , each  $0 \leq \lambda_i^* \leq 1$ , we have for all  $i$  such that  $\lambda_i^* > 0$ ,

$$f(E_i^*) = f(A^*) \quad (19.31)$$

meaning such  $E_i^*$  are also minimizers of  $f$ , and  $\sum_i \lambda_i^* = 1$ .

- Note that the negative of  $f(A^*)$  is crucial here (see next slides).
- By the L.E. properties,  $w^* = \sum_i \lambda_i^* \mathbf{1}_{E_i^*}$ , we have that  $w^*$  is in the convex hull of incidence vectors of minimizers of  $f$ .

show next slides

# A bit more on level sets being minimizers

- $f$  is normalized  $f(\emptyset) = 0$ , so minimizer is  $\leq 0$ .
- We know that  $f(E_i^*) \geq f(A^*)$  for all  $i$ , and  $f(A^*) = \sum_i \lambda_i f(E_i^*)$ .
- If  $f(A^*) = 0$ , then we must have  $f(E_i^*) = 0$  for any  $i$  such that  $\lambda_i > 0$ . Otherwise, assume  $f(A^*) < 0$ .
- Suppose there exists an  $i$  such that  $f(E_i^*) > f(A^*)$ .
- Then we have

$$f(A^*) = \sum_i \lambda_i f(E_i^*) > \sum_i \lambda_i f(A^*) = f(A^*) \sum_i \lambda_i \quad (19.32)$$

and since  $f(A^*) < 0$ , this means that  $\sum_i \lambda_i > 1$  which is a contradiction.

- Hence, must have  $f(E_i^*) = f(A^*)$  for all  $i$ . *wrt  $\lambda_i > 0$*
- Hence,  $\sum_i \lambda_i = 1$  since  $f(A^*) = \sum_i \lambda_i f(A^*)$ .

# Yet another way to see Equation 19.31

- We know  $f(A^*) \leq 0$ . Consider two cases in Equation 19.31.
- Case 1:  $f(A^*) = 0$ . Then for any  $i$  with  $\lambda_i > 0$  we must have  $f(E_i) = 0$  as well for all  $i$  since  $f(A^*) \leq f(E_i)$ .
- Case 2 is where  $f(A^*) < 0$ . In this second case, we have

$$0 > f(A^*) = \sum_i \lambda_i f(E_i) \geq \sum_i \lambda_i f(A^*) \quad (19.33)$$

$$\stackrel{(a)}{\geq} \sum_i \lambda_i f(A^*) + (1 - \bar{\lambda})f(A^*) = f(A^*) \quad (19.34)$$

where  $\bar{\lambda} = \sum_i \lambda_i$  and  $(1 - \bar{\lambda}) \geq 0$  and where (a) follows since  $f(A^*) < 0$ .

- Hence, all inequalities must be equalities, which means that we must have that  $\bar{\lambda} = 1$ .

## $\theta$ -rounding the L.E. minimum

We can also view the above as a form of rounding a continuous convex relaxation to the problem.

### Definition 19.5.2 ( $\theta$ -rounding)

Given vector  $\hat{x} \in [0, 1]^E$ , choose  $\theta \in (0, 1)$  and define a set corresponding to elements above  $\theta$ , i.e.,

$$\hat{X}_\theta = \{i : \hat{x}(i) \geq \theta\} \triangleq \{\hat{x} \geq \theta\} \quad (19.35)$$

### Lemma 19.5.3 (Fujishige-2005)

Given a continuous minimizer  $x^* \in \operatorname{argmin}_{x \in [0, 1]^n} \check{f}(x)$ , the discrete minimizers are exactly the maximal chain of sets  $\emptyset \subseteq X_{\theta_1} \subset \dots \subset X_{\theta_k}$  obtained by  $\theta$ -rounding  $x^*$ , for  $\theta_j \in (0, 1)$ .

- gradient of L.E. is easy to get. (Wednesday)

# Min-Norm Point: Definition

- Consider the optimization:

$$\text{minimize} \quad \|x\|_2^2 \quad (19.36a)$$

$$\text{subject to} \quad x \in B_f \quad (19.36b)$$

where  $B_f$  is the base polytope of submodular  $f$ , and  $\|x\|_2^2 = \sum_{e \in E} x(e)^2$  is the squared 2-norm. Let  $x^*$  be the optimal solution.

# Min-Norm Point: Definition

- Consider the optimization:

$$\text{minimize} \quad \|x\|_2^2 \quad (19.36a)$$

$$\text{subject to} \quad x \in B_f \quad (19.36b)$$

where  $B_f$  is the base polytope of submodular  $f$ , and  $\|x\|_2^2 = \sum_{e \in E} x(e)^2$  is the squared 2-norm. Let  $x^*$  be the optimal solution.

- Note,  $x^*$  is the unique optimal solution since we have a strictly convex objective over a set of convex constraints.

# Min-Norm Point: Definition

- Consider the optimization:

$$\text{minimize} \quad \|x\|_2^2 \quad (19.36a)$$

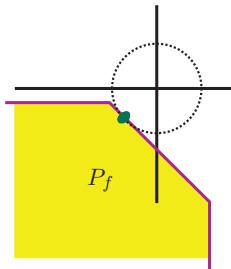
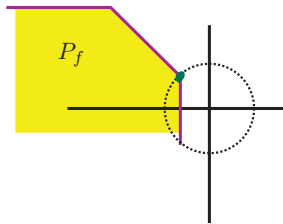
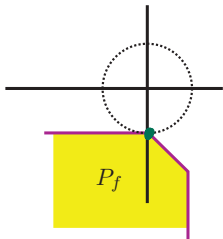
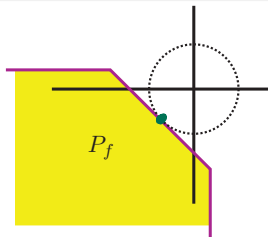
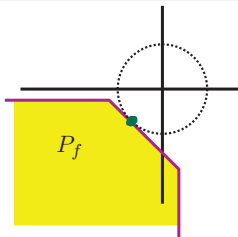
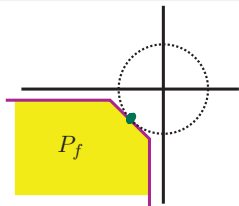
$$\text{subject to} \quad x \in B_f \quad (19.36b)$$

where  $B_f$  is the base polytope of submodular  $f$ , and  $\|x\|_2^2 = \sum_{e \in E} x(e)^2$  is the squared 2-norm. Let  $x^*$  be the optimal solution.

- Note,  $x^*$  is **the** unique optimal solution since we have a strictly convex objective over a set of convex constraints.
- $x^*$  is called **the minimum norm point** of the base polytope.



# Min-Norm Point: Examples

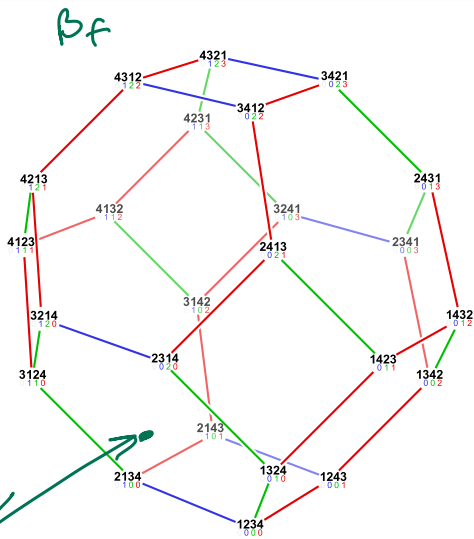


# Ex: 3D base $B_f$ : permutahedron

- Consider submodular function  $f : 2^V \rightarrow \mathbb{R}$  with  $n = |V| = 4$ , and for  $X \subseteq V$ , concave  $g$ ,

$$f(X) = g(|X|) = \sum_{i=1}^{|X|} (n - i + 1) \\ = |X| \left( n - \frac{|X| - 1}{2} \right)$$

- Then  $B_f$  is a 3D polytope, and in this particular case gives us a permutahedron with 24 distinct extreme points, on the right (from wikipedia).



# Min-Norm Point and Submodular Function Minimization

- Given optimal solution  $x^*$  to  $[\min \|x\|_2^2 \text{ s.t. } x \in B_f]$ , and consider:

$$y^* = x^* \wedge 0 = (\min(x^*(e), 0) | e \in E), \quad (19.37)$$

$$A_- = \{e : x^*(e) < 0\}, \quad A_0 = \{e : x^*(e) \leq 0\}. \quad (19.38)$$

*negative elements at min-norm point*

*non-positive elements at min-norm point.*

# Min-Norm Point and Submodular Function Minimization

- Given optimal solution  $x^*$  to  $[\min \|x\|_2^2 \text{ s.t. } x \in B_f]$ , and consider:

$$y^* = x^* \wedge 0 = (\min(x^*(e), 0) | e \in E), \quad (19.37)$$

$$A_- = \{e : x^*(e) < 0\}, \quad A_0 = \{e : x^*(e) \leq 0\}. \quad (19.38)$$

- Thus, we immediately have that:

$$A_- \subseteq A_0 \quad (19.39)$$

and that

$$x^*(A_-) = x^*(A_0) = y^*(A_-) = y^*(A_0). \quad (19.40)$$

# Min-Norm Point and Submodular Function Minimization

- Given optimal solution  $x^*$  to  $[\min \|x\|_2^2 \text{ s.t. } x \in B_f]$ , and consider:

$$y^* = x^* \wedge 0 = (\min(x^*(e), 0) | e \in E), \quad (19.37)$$

$$A_- = \{e : x^*(e) < 0\}, \quad A_0 = \{e : x^*(e) \leq 0\}. \quad (19.38)$$

- Thus, we immediately have that:

$$A_- \subseteq A_0 \quad (19.39)$$

and that

$$x^*(A_-) = x^*(A_0) = y^*(A_-) = y^*(A_0). \quad (19.40)$$

- These quantities will solve the SFM problem: we will see that  $f(A_-) = f(A_0) = \min_{A \subseteq V} f(A)$  and that  $A_-$  is the unique minimal minimizer and  $A_0$  is the unique maximal minimizer.

# Min-Norm Point and Submodular Function Minimization

- Given optimal solution  $x^*$  to  $[\min \|x\|_2^2 \text{ s.t. } x \in B_f]$ , and consider:

$$y^* = x^* \wedge 0 = (\min(x^*(e), 0) | e \in E), \quad (19.37)$$

$$A_- = \{e : x^*(e) < 0\}, \quad A_0 = \{e : x^*(e) \leq 0\}. \quad (19.38)$$

- Thus, we immediately have that:

$$A_- \subseteq A_0 \quad (19.39)$$

and that

$$x^*(A_-) = x^*(A_0) = y^*(A_-) = y^*(A_0). \quad (19.40)$$

- These quantities will solve the SFM problem: we will see that  $f(A_-) = f(A_0) = \min_{A \subseteq V} f(A)$  and that  $A_-$  is the unique minimal minimizer and  $A_0$  is the unique maximal minimizer.
- The proof is nice since it uses recently developed tools (e.g., dep, sat).

# Min-Norm Point and Submodular Function Minimization

- Given optimal solution  $x^*$  to  $[\min \|x\|_2^2 \text{ s.t. } x \in B_f]$ , and consider:

$$y^* = x^* \wedge 0 = (\min(x^*(e), 0) | e \in E), \quad (19.37)$$

$$A_- = \{e : x^*(e) < 0\}, \quad A_0 = \{e : x^*(e) \leq 0\}. \quad (19.38)$$

- Thus, we immediately have that:

$$A_- \subseteq A_0 \quad (19.39)$$

and that

$$x^*(A_-) = x^*(A_0) = y^*(A_-) = y^*(A_0). \quad (19.40)$$

- These quantities will solve the SFM problem: we will see that  $f(A_-) = f(A_0) = \min_{A \subseteq V} f(A)$  and that  $A_-$  is the unique minimal minimizer and  $A_0$  is the unique maximal minimizer.
- The proof is nice since it uses recently developed tools (e.g., dep, sat).
- We'll also show both the Fujishige-Wolfe algorithm and the Frank-Wolfe algorithm (which are quite different from each other) can find the min-norm point relatively efficiently.

# Base Polytope $B_f$ Existence

- Given polymatroid function  $f$ , the base polytope  $B_f = \{x \in \mathbb{R}_+^E : x(A) \leq f(A) \forall A \subseteq E, \text{ and } x(E) = f(E)\}$  always exists.



# Base Polytope $B_f$ Existence

- Given polymatroid function  $f$ , the base polytope  $B_f = \{x \in \mathbb{R}_+^E : x(A) \leq f(A) \forall A \subseteq E, \text{ and } x(E) = f(E)\}$  always exists.
- Consider **any** order of  $E$  and generate a vector  $x$  by this order (i.e.,  $x(e_1) = f(\{e_1\})$ ,  $x(e_2) = f(\{e_1, e_2\}) - f(\{e_1\})$ , and so on).

# Base Polytope $B_f$ Existence

- Given polymatroid function  $f$ , the base polytope  $B_f = \{x \in \mathbb{R}_+^E : x(A) \leq f(A) \forall A \subseteq E, \text{ and } x(E) = f(E)\}$  always exists.
- Consider **any** order of  $E$  and generate a vector  $x$  by this order (i.e.,  $x(e_1) = f(\{e_1\})$ ,  $x(e_2) = f(\{e_1, e_2\}) - f(\{e_1\})$ , and so on).
- From past lectures, we now know that:

# Base Polytope $B_f$ Existence

- Given polymatroid function  $f$ , the base polytope  $B_f = \{x \in \mathbb{R}_+^E : x(A) \leq f(A) \forall A \subseteq E, \text{ and } x(E) = f(E)\}$  always exists.
- Consider **any** order of  $E$  and generate a vector  $x$  by this order (i.e.,  $x(e_1) = f(\{e_1\})$ ,  $x(e_2) = f(\{e_1, e_2\}) - f(\{e_1\})$ , and so on).
- From past lectures, we now know that:
  - (1)  $x \in P_f$

# Base Polytope $B_f$ Existence

- Given polymatroid function  $f$ , the base polytope  $B_f = \{x \in \mathbb{R}_+^E : x(A) \leq f(A) \forall A \subseteq E, \text{ and } x(E) = f(E)\}$  always exists.
- Consider **any** order of  $E$  and generate a vector  $x$  by this order (i.e.,  $x(e_1) = f(\{e_1\})$ ,  $x(e_2) = f(\{e_1, e_2\}) - f(\{e_1\})$ , and so on).
- From past lectures, we now know that:
  - (1)  $x \in P_f$
  - (2)  $x$  is an extreme point in  $P_f$

# Base Polytope $B_f$ Existence

- Given polymatroid function  $f$ , the base polytope  $B_f = \{x \in \mathbb{R}_+^E : x(A) \leq f(A) \forall A \subseteq E, \text{ and } x(E) = f(E)\}$  always exists.
- Consider **any** order of  $E$  and generate a vector  $x$  by this order (i.e.,  $x(e_1) = f(\{e_1\})$ ,  $x(e_2) = f(\{e_1, e_2\}) - f(\{e_1\})$ , and so on).
- From past lectures, we now know that:
  - $x \in P_f$
  - $x$  is an extreme point in  $P_f$
  - Since  $x$  is generated using an ordering of all of  $E$ , we have that  $x(E) = f(E)$ .

$$x(E_i) = f(E_i) \quad \forall i$$

$$E_n = E.$$

# Base Polytope $B_f$ Existence

- Given polymatroid function  $f$ , the base polytope  $B_f = \{x \in \mathbb{R}_+^E : x(A) \leq f(A) \forall A \subseteq E, \text{ and } x(E) = f(E)\}$  always exists.
- Consider **any** order of  $E$  and generate a vector  $x$  by this order (i.e.,  $x(e_1) = f(\{e_1\})$ ,  $x(e_2) = f(\{e_1, e_2\}) - f(\{e_1\})$ , and so on).
- From past lectures, we now know that:
  - (1)  $x \in P_f$
  - (2)  $x$  is an extreme point in  $P_f$
  - (3) Since  $x$  is generated using an ordering of all of  $E$ , we have that  $x(E) = f(E)$ .
- Thus  $x \in B_f$ , and  $B_f$  is never empty.

# Base Polytope $B_f$ Existence

- Given polymatroid function  $f$ , the base polytope  $B_f = \{x \in \mathbb{R}_+^E : x(A) \leq f(A) \forall A \subseteq E, \text{ and } x(E) = f(E)\}$  always exists.
- Consider **any** order of  $E$  and generate a vector  $x$  by this order (i.e.,  $x(e_1) = f(\{e_1\})$ ,  $x(e_2) = f(\{e_1, e_2\}) - f(\{e_1\})$ , and so on).
- From past lectures, we now know that:
  - $x \in P_f$
  - $x$  is an extreme point in  $P_f$
  - Since  $x$  is generated using an ordering of all of  $E$ , we have that  $x(E) = f(E)$ .
- Thus  $x \in B_f$ , and  $B_f$  is never empty.
- Moreover, in this case,  $x$  is a vertex of  $B_f$  since it is extremal.

# Base Polytope $B_f$ Dominance

- Now, for any  $A \subseteq E$ , we can generate a particular point in  $B_f$

$$\text{s.t. } \chi(A) = f(A).$$



## Base Polytope $B_f$ Dominance

- Now, for any  $A \subseteq E$ , we can generate a particular point in  $B_f$
- That is, choose the ordering of  $E = (e_1, e_2, \dots, e_n)$  where  $n = |E|$ , and where  $E_i = (e_1, e_2, \dots, e_i)$ , so that we have  $E_k = A$  with  $k = |A|$ .

# Base Polytope $B_f$ Dominance

- Now, for any  $A \subseteq E$ , we can generate a particular point in  $B_f$
- That is, choose the ordering of  $E = (e_1, e_2, \dots, e_n)$  where  $n = |E|$ , and where  $E_i = (e_1, e_2, \dots, e_i)$ , so that we have  $E_k = A$  with  $k = |A|$ .
- Note there are  $k!(n - k)! < n!$  such orderings.

# Base Polytope $B_f$ Dominance

- Now, for any  $A \subseteq E$ , we can generate a particular point in  $B_f$
- That is, choose the ordering of  $E = (e_1, e_2, \dots, e_n)$  where  $n = |E|$ , and where  $E_i = (e_1, e_2, \dots, e_i)$ , so that we have  $E_k = A$  with  $k = |A|$ .
- Note there are  $k!(n - k)! < n!$  such orderings.
- Generate  $x$  via greedy using this order,  $\forall i, x(e_i) = f(e_i | E_{i-1})$ .

## Base Polytope $B_f$ Dominance

- Now, for any  $A \subseteq E$ , we can generate a particular point in  $B_f$
- That is, choose the ordering of  $E = (e_1, e_2, \dots, e_n)$  where  $n = |E|$ , and where  $E_i = (e_1, e_2, \dots, e_i)$ , so that we have  $E_k = A$  with  $k = |A|$ .
- Note there are  $k!(n-k)! < n!$  such orderings.
- Generate  $x$  via greedy using this order,  $\forall i, x(e_i) = f(e_i | E_{i-1})$ .
- We have generated a point (a vertex)  $x$  in  $B_f$  such that  $x(A) = f(A)$ .

$$\text{Since } x(E_i) = f(E_i) \quad \forall i$$

$$\text{and } E_k = A.$$

## Base Polytope $B_f$ Dominance

- Now, for any  $A \subseteq E$ , we can generate a particular point in  $B_f$
- That is, choose the ordering of  $E = (e_1, e_2, \dots, e_n)$  where  $n = |E|$ , and where  $E_i = (e_1, e_2, \dots, e_i)$ , so that we have  $E_k = A$  with  $k = |A|$ .
- Note there are  $k!(n - k)! < n!$  such orderings.
- Generate  $x$  via greedy using this order,  $\forall i, x(e_i) = f(e_i|E_{i-1})$ .
- We have generated a point (a vertex)  $x$  in  $B_f$  such that  $x(A) = f(A)$ .
- Thus, for any  $A$ , we have

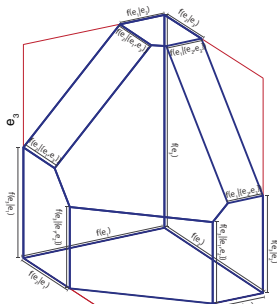
$$B_f \cap \{x \in \mathbb{R}^E : x(A) = f(A)\} \neq \emptyset \quad (19.41)$$

# Base Polytope $B_f$ Dominance

- Now, for any  $A \subseteq E$ , we can generate a particular point in  $B_f$
- That is, choose the ordering of  $E = (e_1, e_2, \dots, e_n)$  where  $n = |E|$ , and where  $E_i = (e_1, e_2, \dots, e_i)$ , so that we have  $E_k = A$  with  $k = |A|$ .
- Note there are  $k!(n-k)! < n!$  such orderings.
- Generate  $x$  via greedy using this order,  $\forall i, x(e_i) = f(e_i | E_{i-1})$ .
- We have generated a point (a vertex)  $x$  in  $B_f$  such that  $x(A) = f(A)$ .
- Thus, for any  $A$ , we have

$$B_f \cap \{x \in \mathbb{R}^E : x(A) = f(A)\} \neq \emptyset \quad (19.41)$$

In words,  $B_f$  intersects all “multi-axis congruent” hyperplanes within  $\mathbb{R}^E$  of the form  $\{x \in \mathbb{R}^E : x(A) = f(A)\}$  for all  $A \subseteq E$ .



# $B_f$ dominates $P_f$

- In fact, every  $x \in P_f$  is dominated by  $x \leq y \in B_f$ .

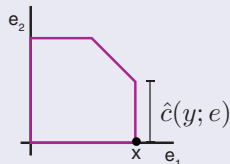
## Theorem 19.7.1

If  $x \in P_f$  and  $T$  is tight for  $x$  (meaning  $x(T) = f(T)$ ), then there exists  $y \in B_f$  with  $x \leq y$  and  $y(e) = x(e)$  for  $e \in T$ .

## Proof.

- We construct the  $y$  algorithmically: initially set  $y \leftarrow x$ .
- $y \in P_f$ ,  $T$  is tight for  $y$  so  $y(T) = f(T)$ .
- Recall saturation capacity: for  $y \in P_f$ ,  $\hat{c}(y; e) = \min \{f(A) - y(A) \mid \forall A \ni e\} = \max \{\alpha : \alpha \in \mathbb{R}, y + \alpha \mathbf{1}_e \in P_f\}$
- Consider following algorithm:

- 
- 
- $T' \leftarrow T$  ;
  - for**  $e \in E \setminus T$  **do**
  - $y \leftarrow y + \hat{c}(y; e) \mathbf{1}_e$  ;  $T' \leftarrow T' \cup \{e\}$  ;
- 



# $B_f$ dominates $P_f$

... proof of Thm. 19.7.1 cont.

- Each step maintains feasibility: consider one step adding  $e$  to  $T'$  — for  $e \notin T'$ , feasibility requires  $y(T' + e) = y(T') + y(e) \leq f(T' + e)$ , or  $y(e) \leq f(T' + e) - y(T') = y(e) + f(T' + e) - y(T' + e)$ .
- We set  $y(e) \leftarrow y(e) + \hat{c}(y; e) \leq y(e) + f(T' + e) - y(T' + e)$ . Hence, after each step,  $y \in P_f$  and  $\hat{c}(y; e) \geq 0$ . (also, consider r.h. version of  $\hat{c}(y; e)$ ).
- Also, only  $y(e)$  for  $e \notin T$  changed, final  $y$  has  $y(e) = x(e)$  for  $e \in T$ .
- Let  $S_e \ni e$  be a set that achieves  $c(y; e) = f(S_e) - y(S_e)$ .

- At iteration  $e$ , let  $y'(e)$  (resp.  $y(e)$ ) be new (resp. old) entry for  $e$ , then

$$\begin{aligned} y'(S_e) &= y(S_e \setminus \{e\}) + y'(e) & (19.42) \\ &= y(S_e \setminus \{e\}) + [y(e) + f(S_e) - y(S_e)] = f(S_e) \end{aligned}$$

So,  $S_e$  is tight for  $y'$ . It remains tight in further iterations since  $y$  doesn't decrease and it stays within  $P_f$ .

- Also,  $E = T \cup \bigcup_{e \notin T} S_e$  is also tight, meaning the final  $y$  has  $y \in B_f$ .  $\square$



# Review from Lecture 12

The following slide repeats Theorem 13.4.2 from lecture 12 and is one of the most important theorems in submodular theory.

# A polymatroid function's polyhedron is a polymatroid.

## Theorem 19.7.1

Let  $f$  be a submodular function defined on subsets of  $E$ . For any  $x \in \mathbb{R}^E$ , we have:

$$\text{rank}(x) = \max(y(E) : y \leq x, y \in P_f) = \min(x(A) + f(E \setminus A) : A \subseteq E) \quad (19.1)$$

Essentially the same theorem as Theorem ??, but note  $P_f$  rather than  $P_f^+$ . Taking  $x = 0$  we get:

## Corollary 19.7.2

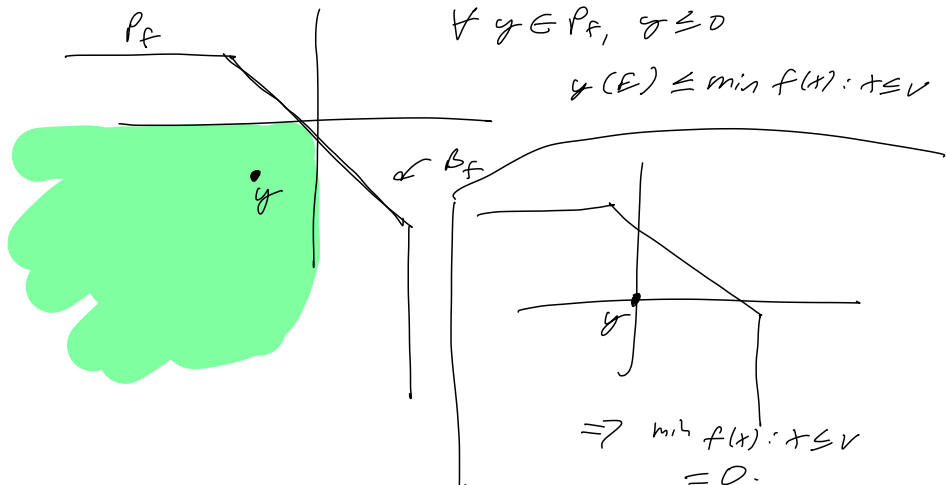
Let  $f$  be a submodular function defined on subsets of  $E$ . We have:

$$\text{rank}(0) = \max(y(E) : y \leq 0, y \in P_f) = \min(f(A) : A \subseteq E) \quad (19.2)$$

# Modified max-min theorem

- Min-max theorem (Thm 13.4.2) restated for  $x = 0$ .

$$\max \{y(E) \mid y \in P_f, y \leq 0\} = \min \{f(X) \mid X \subseteq V\} \quad (19.43)$$



# Modified max-min theorem

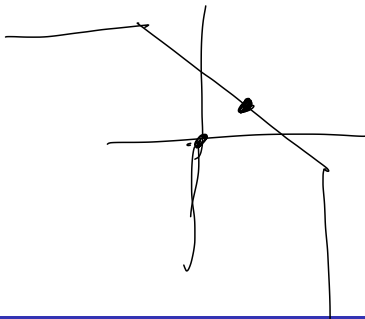
- Min-max theorem (Thm 13.4.2) restated for  $x = 0$ .

$$\max \{y(E) | y \in P_f, y \leq 0\} = \min \{f(X) | X \subseteq V\} \quad (19.43)$$

## Theorem 19.7.2 (Edmonds-1970)

$$\min \{f(X) | X \subseteq E\} = \max \{x^-(E) | x \in B_f\} \quad (19.44)$$

where  $x^-(e) = \min \{x(e), 0\}$  for  $e \in E$ .



# Modified max-min theorem

- Min-max theorem (Thm 13.4.2) restated for  $x = 0$ .

$$\max \{y(E) | y \in P_f, y \leq 0\} = \min \{f(X) | X \subseteq V\} \quad (19.43)$$

## Theorem 19.7.2 (Edmonds-1970)

$$\min \{f(X) | X \subseteq E\} = \max \{x^-(E) | x \in B_f\} \quad (19.44)$$

where  $x^-(e) = \min \{x(e), 0\}$  for  $e \in E$ .

## Proof via the Lovász ext.

$$\min \{f(X) | X \subseteq E\} = \min_{w \in [0,1]^E} \check{f}(w) = \min_{w \in [0,1]^E} \max_{x \in P_f} w^\top x \quad (19.45)$$

$$= \min_{w \in [0,1]^E} \max_{x \in B_f} w^\top x \quad (19.46)$$

$$= \max_{x \in B_f} \min_{w \in [0,1]^E} w^\top x \quad (19.47)$$

$$= \max_{x \in B_f} x^-(E) \quad (19.48)$$



# Alternate proof of modified max-min theorem

We start directly from Theorem 13.4.2.

$$\max (y(E) : y \leq 0, y \in P_f) = \min (f(A) : A \subseteq E) \quad (19.52)$$

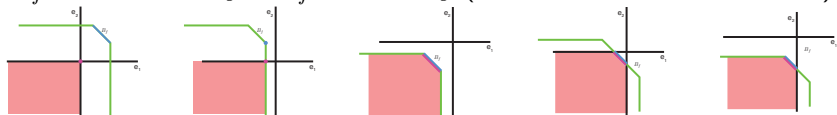
Given  $y \in \mathbb{R}^E$ , define  $y^- \in \mathbb{R}^E$  with  $y^-(e) = \min \{y(e), 0\}$  for  $e \in E$ .

$$\max (y(E) : y \leq 0, y \in P_f) = \max (y^-(E) : y \leq 0, y \in P_f) \quad (19.53)$$

$$= \max (y^-(E) : y \in P_f) \quad (19.54)$$

$$= \max (y^-(E) : y \in B_f) \quad (19.55)$$

The first equality follows since  $y \leq 0$ . The second equality (together with the first) shown on following slide. The third equality follows since for any  $x \in P_f$  there exists a  $y \in B_f$  with  $x \leq y$  (follows from Theorem 19.7.1).



# Alternate proof of modified max-min theorem

Consider the following two problems for down-closed polyhedron  $P$ :

$$\max \sum_{e \in E} y(e) \quad (19.56a)$$

$$\text{s.t. } y \leq x \quad (19.56b)$$

$$y \in P \quad (19.56c)$$

$$\max \sum_{e \in E} \min(y(e), x(e)) \quad (19.57a)$$

$$\text{s.t. } y \in P \quad (19.57b)$$

- Solutions identical cost. Let  $y_1^*$  be l.h.s. OPT and  $y_2^*$  be r.h.s. OPT.
- Consider l.h.s. OPT  $y_1^*$  in r.h.s. evaluation and suppose it is worse (lower) than r.h.s. OPT:

$$\sum_{e \in E} \min(y_1^*(e), x(e)) < \sum_{e \in E} \min(y_2^*(e), x(e)) \quad (19.58)$$

# Alternate proof of modified max-min theorem

Consider the following two problems for down-closed polyhedron  $P$ :

$$\max \sum_{e \in E} y(e) \quad (19.56a)$$

$$\text{s.t. } y \leq x \quad (19.56b)$$

$$y \in P \quad (19.56c)$$

$$\max \sum_{e \in E} \min(y(e), x(e)) \quad (19.57a)$$

$$\text{s.t. } y \in P \quad (19.57b)$$

- Solutions identical cost. Let  $y_1^*$  be l.h.s. OPT and  $y_2^*$  be r.h.s. OPT.
- Consider l.h.s. OPT  $y_1^*$  in r.h.s. evaluation and suppose it is worse (lower) than r.h.s. OPT:

$$\sum_{e \in E} \min(y_1^*(e), x(e)) < \sum_{e \in E} \min(y_2^*(e), x(e)) \quad (19.58)$$

- But the vector  $\bar{y}_1^*$  with entries  $\bar{y}_1^*(e) = \min(y_2^*(e), x(e))$  has  $\bar{y}_1^*(e) \leq x(e)$  and  $\bar{y}_1^* \in P$  since  $y_2^* \in P$ ,  $\bar{y}_1^* \leq y_2^*$ , and  $P$  is down-closed.



# Alternate proof of modified max-min theorem

Consider the following two problems for down-closed polyhedron  $P$ :

$$\max \sum_{e \in E} y(e) \quad (19.56a)$$

$$\text{s.t. } y \leq x \quad (19.56b)$$

$$y \in P \quad (19.56c)$$

$$\max \sum_{e \in E} \min(y(e), x(e)) \quad (19.57a)$$

$$\text{s.t. } y \in P \quad (19.57b)$$

- Solutions identical cost. Let  $y_1^*$  be l.h.s. OPT and  $y_2^*$  be r.h.s. OPT.
- Consider l.h.s. OPT  $y_1^*$  in r.h.s. evaluation and suppose it is worse (lower) than r.h.s. OPT:

$$\sum_{e \in E} \min(y_1^*(e), x(e)) < \sum_{e \in E} \min(y_2^*(e), x(e)) \quad (19.58)$$

- But the vector  $\bar{y}_1^*$  with entries  $\bar{y}_1^*(e) = \min(y_2^*(e), x(e))$  has  $\bar{y}_1^*(e) \leq x(e)$  and  $\bar{y}_1^* \in P$  since  $y_2^* \in P$ ,  $\bar{y}_1^* \leq y_2^*$ , and  $P$  is down-closed.
- Thus,  $\bar{y}_1^*$  is l.h.s. feasible but a better l.h.s. evaluation, a contradiction of the optimality of  $y_1^*$  for l.h.s.

# Alternate proof of modified max-min theorem

Consider the following two problems for down-closed polyhedron  $P$ :

$$\max \sum_{e \in E} y(e) \quad (19.56a)$$

$$\text{s.t. } y \leq x \quad (19.56b)$$

$$y \in P \quad (19.56c)$$

$$\max \sum_{e \in E} \min(y(e), x(e)) \quad (19.57a)$$

$$\text{s.t. } y \in P \quad (19.57b)$$

- Solutions identical cost. Let  $y_1^*$  be l.h.s. OPT and  $y_2^*$  be r.h.s. OPT.
- Similarly, consider r.h.s. OPT  $y_2^*$  in l.h.s. evaluation and suppose it is worse (lower) than l.h.s. OPT

$$\sum_{e \in E} y_2^*(e) < \sum_{e \in E} y_1^*(e) \quad (19.58)$$

# Alternate proof of modified max-min theorem

Consider the following two problems for down-closed polyhedron  $P$ :

$$\max \sum_{e \in E} y(e) \quad (19.56a)$$

$$\text{s.t. } y \leq x \quad (19.56b)$$

$$y \in P \quad (19.56c)$$

$$\max \sum_{e \in E} \min(y(e), x(e)) \quad (19.57a)$$

$$\text{s.t. } y \in P \quad (19.57b)$$

- Solutions identical cost. Let  $y_1^*$  be l.h.s. OPT and  $y_2^*$  be r.h.s. OPT.
- Similarly, consider r.h.s. OPT  $y_2^*$  in l.h.s. evaluation and suppose it is worse (lower) than l.h.s. OPT

$$\sum_{e \in E} y_2^*(e) < \sum_{e \in E} y_1^*(e) \quad (19.58)$$

- But the vector  $\bar{y}_2^*$  with entries  $\bar{y}_2^*(e) = y_1^*(e)$  has  $\bar{y}_2^* \in P$  and since  $\bar{y}_2^*(e) \leq x(e)$  for all  $e$ , we have

$$\sum_{e \in E} y_2^*(e) < \sum_{e \in E} y_1^*(e) = \sum_{e \in E} \bar{y}_2^*(e) = \sum_{e \in E} \min(\bar{y}_2^*(e), x(e)) \quad (19.59)$$

# Alternate proof of modified max-min theorem

Consider the following two problems for down-closed polyhedron  $P$ :

$$\max \sum_{e \in E} y(e) \quad (19.56a)$$

$$\text{s.t. } y \leq x \quad (19.56b)$$

$$y \in P \quad (19.56c)$$

$$\max \sum_{e \in E} \min(y(e), x(e)) \quad (19.57a)$$

$$\text{s.t. } y \in P \quad (19.57b)$$

- Solutions identical cost. Let  $y_1^*$  be l.h.s. OPT and  $y_2^*$  be r.h.s. OPT.
- Similarly, consider r.h.s. OPT  $y_2^*$  in l.h.s. evaluation and suppose it is worse (lower) than l.h.s. OPT

$$\sum_{e \in E} y_2^*(e) < \sum_{e \in E} y_1^*(e) \quad (19.58)$$

- But the vector  $\bar{y}_2^*$  with entries  $\bar{y}_2^*(e) = y_1^*(e)$  has  $\bar{y}_2^* \in P$  and since  $\bar{y}_2^*(e) \leq x(e)$  for all  $e$ , we have

$$\sum_{e \in E} y_2^*(e) < \sum_{e \in E} y_1^*(e) = \sum_{e \in E} \bar{y}_2^*(e) = \sum_{e \in E} \min(\bar{y}_2^*(e), x(e)) \quad (19.59)$$

- Thus, we have r.h.s. feasible vector  $\bar{y}_2^*$  strictly better than r.h.s. OPT contradicting the optimality of  $y_2^*$ .

# Alternate proof of modified max-min theorem

Consider the following two problems for down-closed polyhedron  $P$ :

$$\max \sum_{e \in E} y(e) \quad (19.56a)$$

$$\text{s.t. } y \leq x \quad (19.56b)$$

$$y \in P \quad (19.56c)$$

$$\max \sum_{e \in E} \min(y(e), x(e)) \quad (19.57a)$$

$$\text{s.t. } y \in P \quad (19.57b)$$

- Solutions identical cost. Let  $y_1^*$  be l.h.s. OPT and  $y_2^*$  be r.h.s. OPT.
- Thus, l.h.s. and r.h.s. have identically valued solutions.

# Alternate proof of modified max-min theorem

Consider the following two problems for down-closed polyhedron  $P$ :

$$\max \sum_{e \in E} y(e) \quad (19.56a)$$

$$\text{s.t. } y \leq x \quad (19.56b)$$

$$y \in P \quad (19.56c)$$

$$\max \sum_{e \in E} \min(y(e), x(e)) \quad (19.57a)$$

$$\text{s.t. } y \in P \quad (19.57b)$$

- Solutions identical cost. Let  $y_1^*$  be l.h.s. OPT and  $y_2^*$  be r.h.s. OPT.
- Thus, l.h.s. and r.h.s. have identically valued solutions.
- Hence, from previous slide, taking  $x = 0$ ,  $\max(y(E) : y \leq 0, y \in P_f) = \max(y^-(E) : y \in P_f) = \max(y^-(E) : y \in B_f)$

$$\min \{w^\top x : x \in B_f\}$$

- Recall that the greedy algorithm solves, for  $w \in \mathbb{R}_+^E$

$$\max \{w^\top x | x \in P_f\} = \max \{w^\top x | x \in B_f\} \quad (19.58)$$

since for all  $x \in P_f$ , there exists  $y \geq x$  with  $y \in B_f$ .

$$\min \{w^\top x : x \in B_f\}$$

- Recall that the greedy algorithm solves, for  $w \in \mathbb{R}_+^E$

$$\max \{w^\top x | x \in P_f\} = \max \{w^\top x | x \in B_f\} \quad (19.58)$$

since for all  $x \in P_f$ , there exists  $y \geq x$  with  $y \in B_f$ .

- For arbitrary  $w \in \mathbb{R}^E$ , we saw in Lecture 16 that the greedy algorithm will also solve:

$$\max \{w^\top x | x \in B_f\} \quad (19.59)$$



$$\min \{w^\top x : x \in B_f\}$$

- Recall that the greedy algorithm solves, for  $w \in \mathbb{R}_+^E$

$$\max \{w^\top x | x \in P_f\} = \max \{w^\top x | x \in B_f\} \quad (19.58)$$

since for all  $x \in P_f$ , there exists  $y \geq x$  with  $y \in B_f$ .

- For arbitrary  $w \in \mathbb{R}^E$ , we saw in Lecture 16 that the greedy algorithm will also solve:

$$\max \{w^\top x | x \in B_f\} \quad (19.59)$$

- Also, since  $w \in \mathbb{R}^E$  is arbitrary, and since

$$\min \{w^\top x | x \in B_f\} = -\max \{-w^\top x | x \in B_f\} \quad (19.60)$$

the greedy algorithm using ordering  $(e_1, e_2, \dots, e_m)$  such that

$$w(e_1) \leq w(e_2) \leq \dots \leq w(e_m) \quad (19.61)$$

will solve l.h.s. of Equation (19.60).

# Greedy solves $\max \{w^\top x \mid x \in B_f\}$ for arbitrary $w \in \mathbb{R}^E$

Let  $f(A)$  be arbitrary submodular function, and  $f(A) = f'(A) - m(A)$  where  $f'$  is polymatroidal, and  $w \in \mathbb{R}^E$ .

$$\begin{aligned}
 \max \{w^\top x \mid x \in B_f\} &= \max \{w^\top x \mid x(A) \leq f(A) \forall A, x(E) = f(E)\} \\
 &= \max \{w^\top x \mid x(A) \leq f'(A) - m(A) \forall A, x(E) = f'(E) - m(E)\} \\
 &= \max \{w^\top x \mid x(A) + m(A) \leq f'(A) \forall A, x(E) + m(E) = f'(E)\} \\
 &= \max \{w^\top x + w^\top m \mid \\
 &\quad x(A) + m(A) \leq f'(A) \forall A, x(E) + m(E) = f'(E)\} - w^\top m \\
 &= \max \{w^\top y \mid y \in B_{f'}\} - w^\top m \\
 &= w^\top y^* - w^\top m = w^\top (y^* - m)
 \end{aligned}$$

where  $y = x + m$ , so that  $x^* = y^* - m$ .

So  $y^*$  uses greedy algorithm with positive orthant  $B_{f'}$ . To show, we use Theorem ?? in Lecture 11, but we don't require  $y \geq 0$ , and don't stop when  $w$  goes negative to ensure  $y^* \in B_{f'}$ . Then when we subtract off  $m$  from  $y^*$ , we get solution to the original problem.