

# EE512A – Advanced Inference in Graphical Models

— Fall Quarter, Lecture 8 —

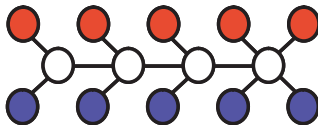
[http://j.ee.washington.edu/~bilmes/classes/ee512a\\_fall\\_2014/](http://j.ee.washington.edu/~bilmes/classes/ee512a_fall_2014/)

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University of Washington, Seattle  
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Oct 22nd, 2014



# Announcements

- Reading assignments, posted to our canvas announcements page (<https://canvas.uw.edu/courses/914697/announcements>): `intro.pdf`, `ugms.pdf` on undirected graphical models, and `tree_inference.pdf` on trees.

# Class Road Map - EE512a

- L1 (9/29): Introduction, Families, Semantics
- L2 (10/1): MRFs, elimination, Inference on Trees
- L3 (10/6): Tree inference, message passing, more general queries, non-tree)
- L4 (10/8): Non-trees, perfect elimination, triangulated graphs
- L5 (10/13): triangulated graphs,  $k$ -trees, the triangulation process/heuristics
- L6 (10/15): multiple queries, decomposable models, junction trees
- L7 (10/20): junction trees, begin intersection graphs
- L8 (10/22): intersection graphs, inference on junction trees, semirings
- L9 (10/27):
- L10 (10/29):
- L11 (11/3):
- L12 (11/5):
- L13 (11/10):
- L14 (11/12):
- L15 (11/17):
- L16 (11/19):
- L17 (11/24):
- L18 (11/26):
- L19 (12/1):
- L20 (12/3):
- Final Presentations: (12/10):

Finals Week: Dec 8th-12th, 2014.

# Today

*JT is the tree that all graphs can be transformed up into. Once we have the tree, we have a variety of options of message passing that generalize the message passing on trees we've already seen. Moreover, we can reduce that down to a 1-tree again if we wish.*

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+ EAGOR

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- Equivalence of triangulated graphs, decomposable graphs, perfect elimination graphs, JT of cliques exists, and (soon) sub-tree graphs.



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- Equivalence of triangulated graphs, decomposable graphs, perfect elimination graphs, JT of cliques exists, and (soon) sub-tree graphs.
- Inference on JTs: goal, clusters as marginals  $p(x_C)$

# Intersection Graphs

## Definition 8.3.1 (Intersection Graph)

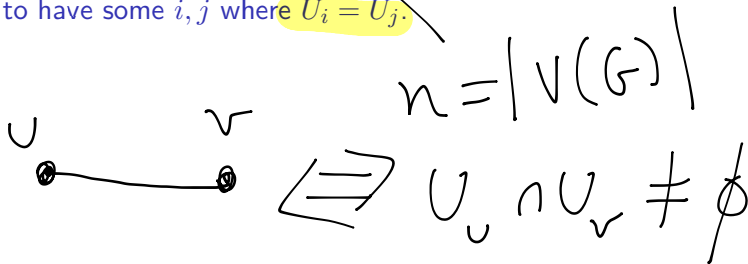
An intersection graph is a graph  $G = (V, E)$  where each vertex  $v \in V(G)$  corresponds to a set  $U_v$  and each edge  $(u, v) \in E(G)$  exists only if  $U_u \cap U_v \neq \emptyset$ .

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- some underlying set of objects  $U$  and a multiset of subsets of  $U$  of the form  $\mathcal{U} = \{U_1, U_2, \dots, U_n\}$  with  $U_i \subseteq U$  — multiset, so allowed to have some  $i, j$  where  $U_i = U_j$ .



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$$U = \bigcup_{i \in [n]} U_i$$

## Theorem 8.3.2

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This can be seen informally by consider an arbitrary graph, create a  $U_i$  for every node, and construct the subsets so that the edges will exist when taking intersection.

# Interval Graphs (a type of intersection graph)

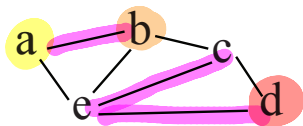
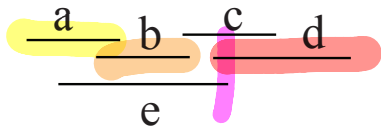
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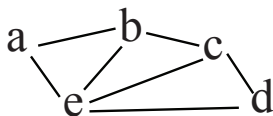
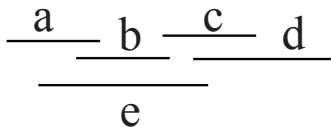
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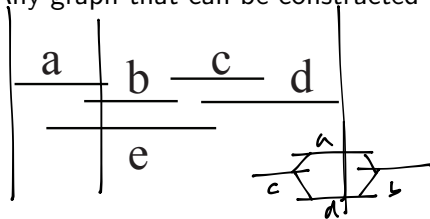
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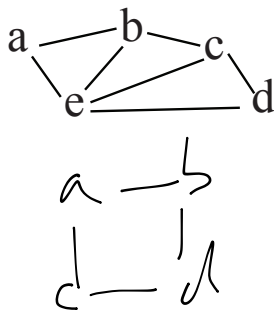
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- Are all graphs interval graphs? **4-cycle**



# Interval Graphs

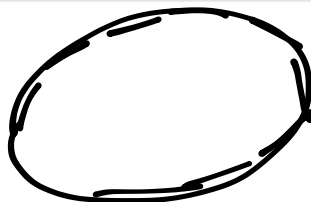
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*All Interval Graphs are triangulated.*

proof sketch.

Given interval graph  $G = (V, E)$ , consider any cycle  $u, w_1, w_2, \dots, w_k, v, u \in V(G)$ . Cycle must go (w.l.o.g.) forward and then backwards along the line in order to connect back to  $u$ , so there must be a chord between some non-adjacent nodes (since they will overlap).  $\square$

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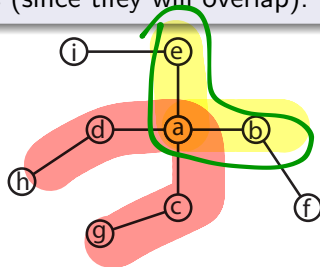
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# Sub-tree intersection Graphs

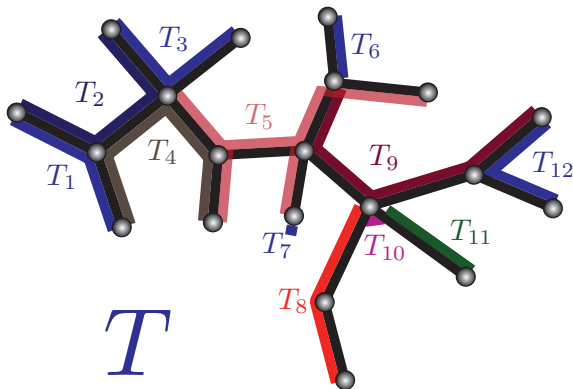
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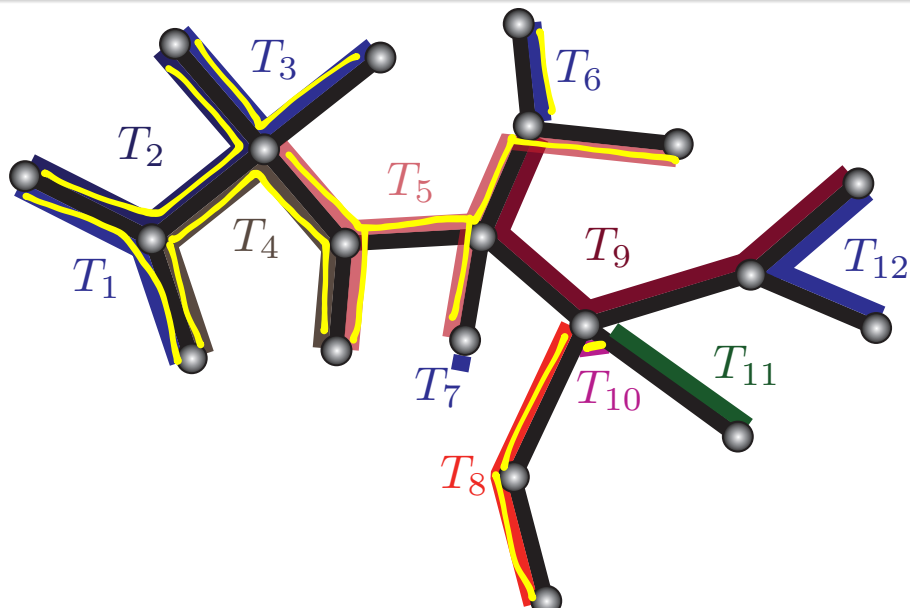
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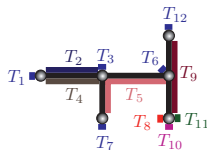
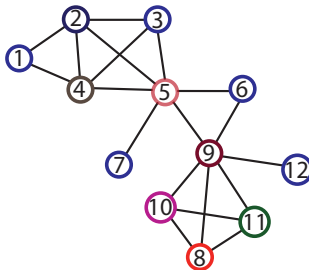
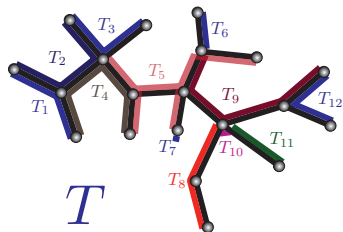
Lets zoom in a little on this



# Ex: Sub-tree intersection Graph

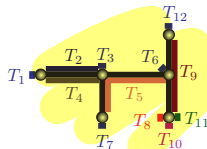
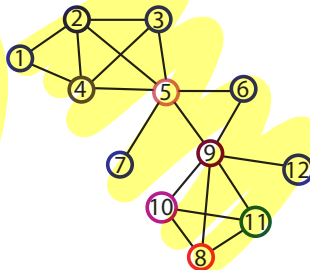
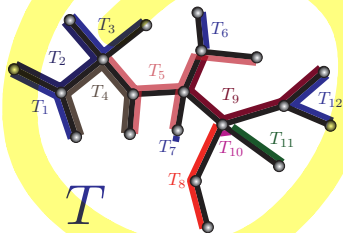


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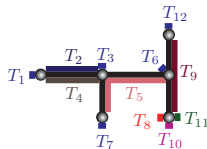
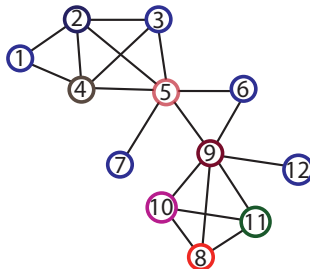
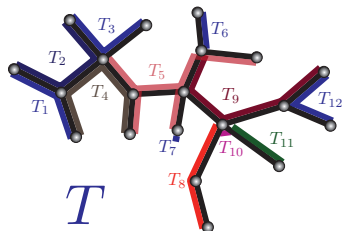
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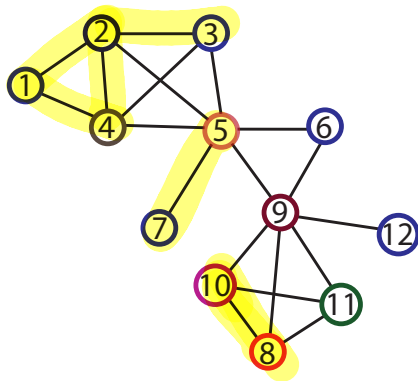
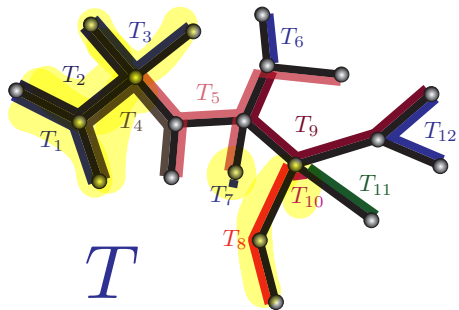


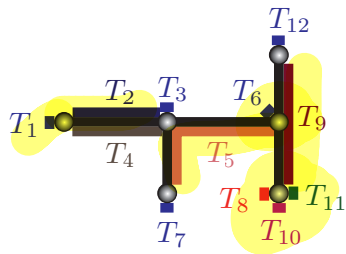
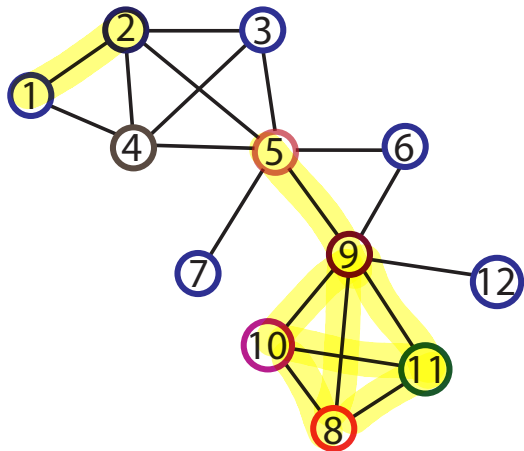
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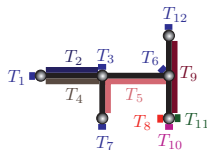
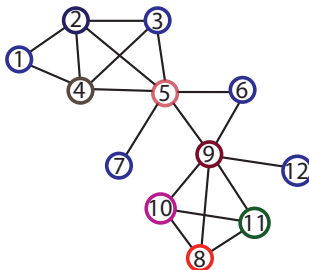
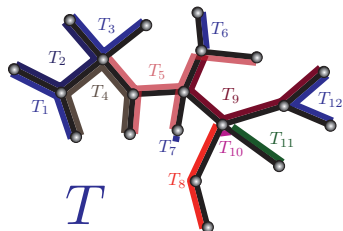


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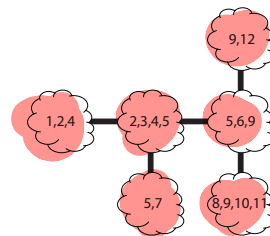
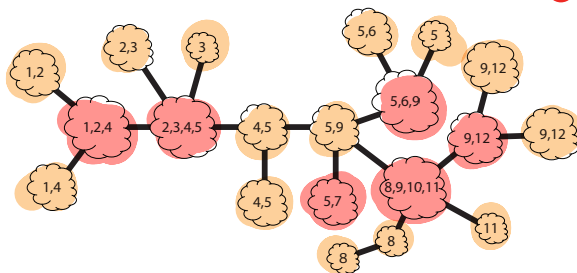
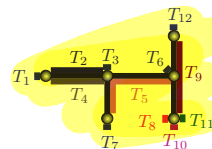
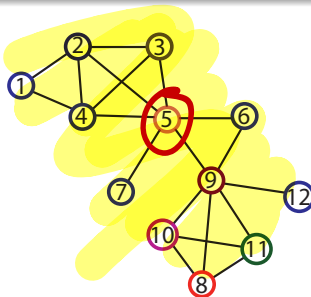
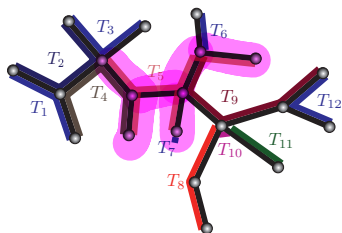


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- What is the difference between left and right trees?
- Junction tree of cliques and maxcliques (left) vs. junction tree of just maxcliques (right).

# Sub-tree intersection Graphs w. Junction Trees





# Sub-tree intersection graphs

## Theorem 8.3.4

*A graph  $G = (V, E)$  is triangulated iff it corresponds to a sub-tree graph (i.e., an intersection graph on subtrees of some tree).*

## proof sketch.

We see that any sub-tree graph is such that nodes in the tree correspond to cliques in  $G$ , and by the nature of how the graph is constructed (subtrees of some underlying tree), the tree corresponds to a cluster tree that satisfies the induced subtree property. Therefore, any sub-tree graph corresponds to a junction tree, and any corresponding graph  $G$  is triangulated. □

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- Are all sub-tree intersection graphs interval graphs?
- So sub-tree intersection graphs capture the “tree-like” nature of triangulated graphs.
- Triangulated graphs are also called hyper-trees (specific type of hyper-graph, where edges are generalized to be clusters of nodes rather than 2 nodes in a normal graph). In hyper-tree, the unique “max-edge” path between any two nodes property is generalized.

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- Let  $G$  be the original graph with cliques  $\mathcal{C}(G)$ , and let  $\mathcal{C}(G')$  be the cliques of the triangulated graph.
- We know we have factorization:

$$\forall c \in \mathcal{C}(G)$$

$$p(x_c) = \sum_{x_{V \setminus c}} p(x)$$

$$p(x) = \prod_{C \in \mathcal{C}(G)} \psi_C(x_C)$$

(8.1)

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- We need to know how to initialize these separators.

# Inference on JTs - table initialization

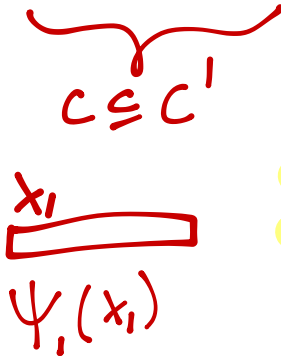
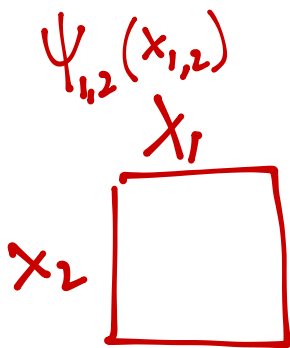
- Initialization Step: For each  $C' \in \mathcal{C}(G')$ , assign  $\psi_{C'}(x_{C'}) = 1$ .

$$\forall x_{C'}$$

# Inference on JT's - table initialization

- Initialization Step: For each  $C' \in \mathcal{C}(G')$ , assign  $\psi_{C'}(x_{C'}) = 1$ .
- For each clique  $C \in \mathcal{C}(G)$ , find one  $C' \in \mathcal{C}(G')$  such that  $C \subseteq C'$ , and update  $\psi_{C'}(x_{C'})$  as follows:

$$\psi_{C'}(x_{C'}) \leftarrow \underbrace{\psi_{C'}(x_{C'})}_{C \subseteq C'} \psi_C(x_C) \quad (8.2)$$



$$\begin{aligned} & \downarrow \downarrow \downarrow \\ & \psi_{1,2}(x_1, x_2) \cdot \psi_1(x_1) \\ & = \psi'_{1,2}(x_1, x_2) \end{aligned}$$



# Inference on JT's - table initialization

- Initialization Step: For each  $C' \in \mathcal{C}(G')$ , assign  $\psi_{C'}(x_{C'}) = 1$ .
- For each clique  $C \in \mathcal{C}(G)$ , find one  $C' \in \mathcal{C}(G')$  such that  $C \subseteq C'$ , and update  $\psi_{C'}(x_{C'})$  as follows:

$$\psi_{C'}(x_{C'}) \leftarrow \psi_{C'}(x_{C'}) \psi_C(x_C) \quad (8.2)$$

- Crucial: Only do this once, otherwise, we'll be double counting the clique  $\psi_C(x_C)$  (i.e., a  $C \in \mathcal{C}(G)$  gets assigned only one  $C' \in \mathcal{C}(G')$ )

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- Once this is done, we have

$$p(x) = \frac{\prod_{C' \in \mathcal{C}(G')} \psi_{C'}(x_{C'})}{\prod_{S \in \mathcal{S}(G')} \phi_S(x_S)^{d(S)-1}} \quad (8.4)$$

# Maxclique marginals as the goal

- Since  $G'$  is triangulated, and is decomposable, we know it is possible to represent  $p$  as:

$$p(x) = \prod_{C' \in \mathcal{C}(G')} \psi_{C'}(x_{C'}) = \frac{\prod_{C \in \mathcal{C}'} p(x_{C'})}{\prod_{S \in \mathcal{S}(G')} p(x_S)^{d(S)-1}} \quad (8.5)$$

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- If we set  $\phi_S(x_S) = 1$  for all  $S$ , then

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- In Equation (8.5), we have the functions at each maxclique and at each separator equal to the **marginal distribution** over the corresponding nodes.

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# Maxclique marginals as the goal

- With the marginals, we can easily compute any desired original-graph clique marginal for any  $C \in \mathcal{C}(G)$ .
- Our goal is to efficiently go from the representation at Equation (??) to the representation at the right of Equation (8.5).
- Can we do this using a similar message passing procedure to what we've already seen?

# Maxclique marginals as the goal

- Start out (after initialization) with the expression

$$p(x) = \frac{\prod_{C' \in \mathcal{C}(G')} \psi_{C'}(x_{C'})}{\prod_{S \in \mathcal{S}(G')} \phi_S(x_S)^{d(S)-1}} \quad (8.7)$$

where  $\forall S, \phi_S(x_S) = 1$ , and  $\psi_{C'}(x_{C'})$  is initialized as described earlier.

- Do message passing, so that we end up with

$$p(x) = \frac{\prod_{C' \in \mathcal{C}(G')} \psi_{C'}(x_{C'})}{\prod_{S \in \mathcal{S}(G')} \phi_S(x_S)^{d(S)-1}} = \frac{\prod_{C \in \mathcal{C}} p(x_{C'})}{\prod_{S \in \mathcal{S}(G)} p(x_S)^{d(S)-1}} \quad (8.8)$$

- Meaning,  $\psi_{C'}(x_{C'}) = p(x_{C'})$  for all  $C'$  and  $\phi_S(x_S) = p(x_S)$  for all  $S$ , marginals.

# Marginal Agreement for Agreeable Marginals

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$$\sum_{x_{C'_1 \setminus S}} \psi_{C'_1}(x_{C'_1}) = \sum_{x_{C'_2 \setminus S}} \psi_{C'_2}(x_{C'_2}) \quad (8.9)$$




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- Such marginal agreement is a critical idea that also lies at the heart of the approximate inference methods we'll be later covering.

# Local Marginal Aggrement

- This is a necessary condition for the clique/separator functions to be marginals because

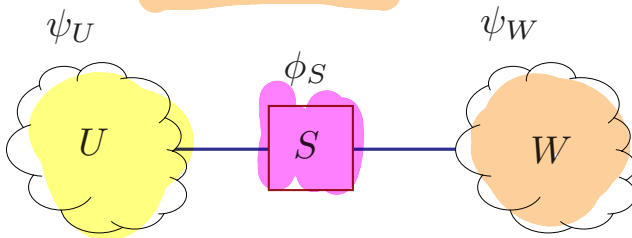
$$\sum_{x_{C'_1 \setminus S}} \psi_{C'_1}(x_{C'_1}) = \sum_{x_{C'_1 \setminus S}} p(x_{C'_1}) = \sum_{x_{C'_2 \setminus S}} p(x_{C'_2}) = \sum_{x_{C'_2 \setminus S}} \psi_{C'_2}(x_{C'_2}) \quad (8.10)$$

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- Given two maxcliques  $U$  and  $W$  with separator  $S = U \cap W$ , and potential functions  $\psi_U$ ,  $\psi_W$ , and  $\phi_S$ , arranged in small JT as follows:



# Maxclique marginals as the goal

- Shorthand notation:  $\phi_S^* = \sum_{U \setminus S} \psi_U$  — represents new potential over separator  $S$  obtained from  $\psi_U$  where all but  $S$  has been marginalized away.

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- Thus,

$$\sum_{U \setminus S} \psi_U \triangleq \sum_{x_{U \setminus S}} \psi_U(x_U) = \sum_{x_{U \setminus S}} \psi_U(x_{U \setminus S}, x_S) = \phi_S^*(x_S)$$

which is a function only of  $x_S$ .

# Maxclique marginals as the goal: shorthand notation

- More shorthand notation: **table multiplication**

$$\psi_W^* = \frac{\phi_S^*}{\phi_S} \psi_W \quad (8.11)$$

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so to expand everything out, we get

$$\frac{\phi_S^*}{\phi_S} \psi_W = \psi_W^* = \psi_W^*(x_S, x_{W_S}) = \frac{\phi_S^*(x_S)}{\phi_S(x_S)} \psi_W(x_S, x_{W_S}) \quad (8.14)$$

$\forall x_W$

# Towards Marginal Aggrement

- Suppose, JT potentials start out inconsistent. i.e.,

$$\sum_{U \setminus S} \psi_U \neq \sum_{W \setminus S} \psi_W \quad \text{and} \quad \phi_S = 1 \quad (8.15)$$

but we still have that  $p(x_U, x_W) = p(x_H, \bar{x}_E) = \psi_U \psi_W / \phi_S$ .

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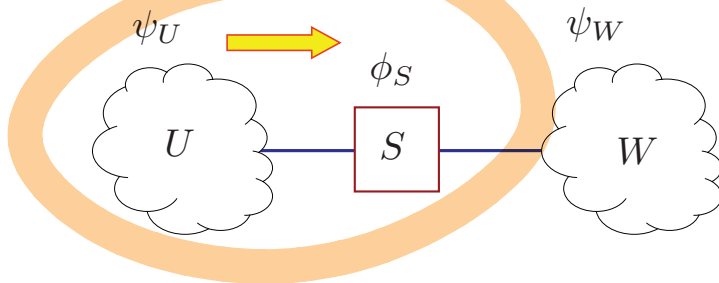
- Note (again) that we may treat evidence  $\bar{x}_E$  as additional factors contained within a clique and that any summation would only sum over corresponding evidence value, so we can avoid mentioning evidence for now.
- What we'll do: exchange information between cliques via separators to achieve consistency.

# New separator potential to obtain new marginal

- **Marginalize  $U$ :**

$$\phi_S^* = \sum_{U \setminus S} \psi_U \quad (8.16)$$

which leads to a new separator potential  $\phi_S^*$  and can be seen as a partial message, as shown in the following figure

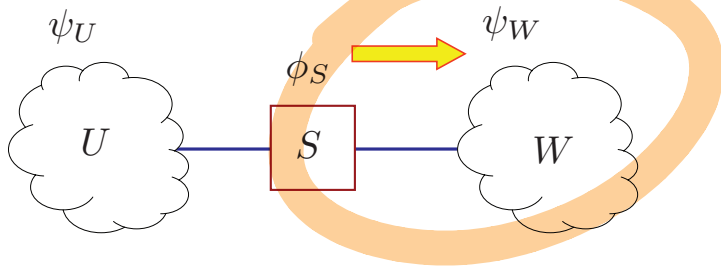


# Updated $W$ marginal based on separator

- Rescale  $W$ :

$$\psi_W^* = \frac{\phi_S^*}{\phi_S} \psi_W \quad (8.17)$$

This produces a new potential on  $W$  based on the updated separator potential at  $S$ . This can also be seen as a partial message.



# Updated distribution unchanged

- After these operations, joint has not changed: define  $\psi_U^* = \psi_U$  for convenience, we get:

alias

$$\frac{\psi_U^* \psi_W^*}{\phi_S^*} = \frac{\psi_U \psi_W \cancel{\phi_S^*}}{\phi_S \cancel{\phi_S^*}} = \frac{\psi_U \psi_W}{\phi_S} \quad (8.18)$$

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- Don't yet (nec.) have consistency since could have

$$\sum_{U \setminus S} \psi_U^* = \sum_{U \setminus S} \psi_U = \phi_S^* \neq \sum_{W \setminus S} \psi_W^* = \frac{\phi_S^*}{\phi_S} \sum_{W \setminus S} \psi_W \quad (8.19)$$

which follows because we still could have that

$$\psi = \phi_S \neq \sum_{W \setminus S} \psi_W \quad (8.20)$$



# Progress towards marginals

$$\Rightarrow P(X) \cdot \delta(x_E = \bar{x}_E) = P(X) \cdot \prod_{e \in E} \delta(x_e = \bar{x}_e)$$

- We do at least have one marginal at  $\psi_W^*$ . This is because we started with:

$$p(x_H, \bar{x}_E) = p(x) = p(x_U, x_W) = \frac{\psi_U \psi_W}{\phi_S} \quad (8.21)$$

and

$$\psi_W^* = \frac{\phi_S^*}{\phi_S} \psi_W = \psi_W \sum_{U \setminus S} \psi_U = \sum_{x_{U \setminus S}} p(x_H, \bar{x}_E) = p(x_W) \quad (8.22)$$

is one of the marginals that we desire.

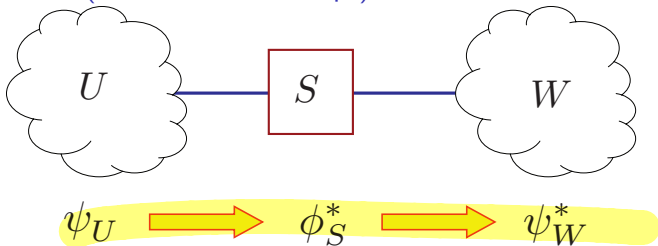
$$\sum_{x_{U \setminus S}} g(x_{U \setminus S}, x_S, x_{W \setminus S}) = \bar{g}(x_S, x_{W \setminus S}) = \bar{g}(x_W)$$

# Message in a junction tree

- We see this as a message passing procedure, passing a message between two nodes in a cluster (or junction) tree.

# Message in a junction tree

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- Message from cluster  $U$  through  $S$  and to  $W$  is the message directly from  $U$  to  $W$  (but done in two steps).



# Send message back

- What if we were to do the same set of operations in reverse, i.e., send a message from  $W$  back to  $U$  using the new state of the potential functions. I.e., we first
- **Marginalize  $W$ :**

$$\phi_S^{**} = \sum_{W \setminus S} \psi_W^* \quad (8.23)$$

resulting in still another separator potential. And then

# Update initial marginal at $U$

- Rescale  $U$ :

$$\psi_U^{**} = \frac{\phi_S^{**}}{\phi_S^*} \psi_U^* \quad \parallel \quad \psi_U \quad (8.24)$$

resulting in a new potential on  $U$ .

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- Intuition:  $\phi_S^{**}$  and  $\psi_U^*$  both “contain”  $\phi_S^*$  so we divide it out in the computation of  $\psi_U^{**}$  so that  $\psi_U^{**}$  doesn't end up double counting  $\phi_S^*$ .

# Maxclique marginals as the goal

alias

- The new joint  $p(x_U, x_W)$  has again not changed. Define  $\psi_W^{**} = \psi_W^*$  for convenience, we get:

$$p(x) = \frac{\psi_U^{**} \psi_W^{**}}{\phi_S^{**}} = \frac{\psi_U \cancel{\phi_S^{**}} \psi_W \cancel{\phi_S^{**}}}{\cancel{\phi_S^{**}} \phi_S \cancel{\phi_S^{**}}} = \frac{\psi_U \psi_W}{\phi_S} \quad (8.25)$$

# Maxclique marginals as the goal

- More importantly, after backwards message, we indeed have consistency guaranteed.
- In particular,  $\psi_U^{**}$  and  $\psi_W^{**}$  are now consistent since:

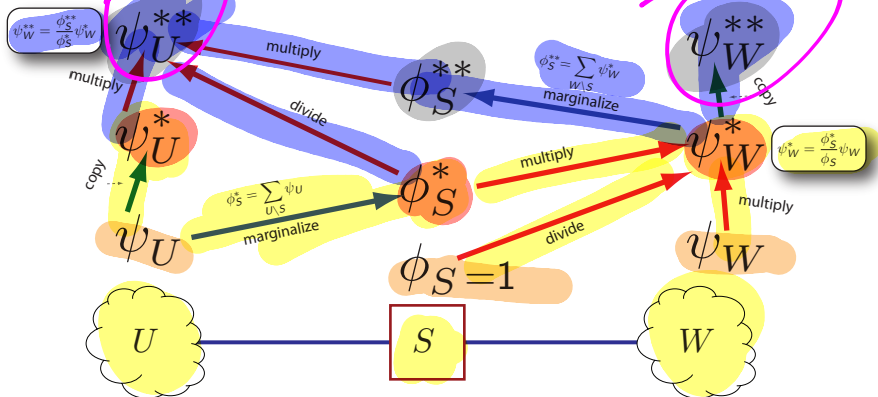
$$\begin{aligned}
 \sum_{U \setminus S} \psi_U^{**} &= \sum_{U \setminus S} \frac{\phi_S^{**}}{\phi_S^*} \psi_U^* = \frac{\phi_S^{**}}{\phi_S^*} \sum_{U \setminus S} \psi_U^* = \frac{\phi_S^{**}}{\phi_S^*} \cancel{\phi_S^*} = \phi_S^{**} = \sum_{W \setminus S} \psi_W^{**}
 \end{aligned}
 \tag{8.26}$$

Diagrammatic annotations: A blue box encloses the sum  $\sum_{U \setminus S} \psi_U^*$  in the third term. A blue arrow labeled  $\psi_U$  points from this box to the  $\phi_S^*$  term in the fourth term. Another blue arrow points from the boxed  $\phi_S^*$  term to the boxed  $\phi_S^{**}$  term in the fifth term. The final sum  $\sum_{W \setminus S} \psi_W^{**}$  is enclosed in a blue bracket.



# Forward/Backward Messages Along Cluster Tree Edge

Summarizing, forward and backwards messages proceed as follows:



Recall:  $S = U \cap W$ , and we initialize  $\psi_U$  and  $\psi_W$  with factors that are contained in  $U$  or  $W$ .

# Marginal at $U$ achieved

We moreover have the other marginal we want at  $\psi_U^{**}$  since:

$$\psi_U^{**} = \frac{\phi_S^{**}}{\phi_S^*} \psi_U = \psi_U \frac{\sum_{W \setminus S} \psi_W^*}{\sum_{U \setminus S} \psi_U}$$

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 &= \psi_U \frac{\sum_{W \setminus S} \psi_W \sum_{U \setminus S} \psi_U}{\sum_{U \setminus S} \psi_U}
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$$= \sum_{W \setminus S} \psi_U \psi_W =$$

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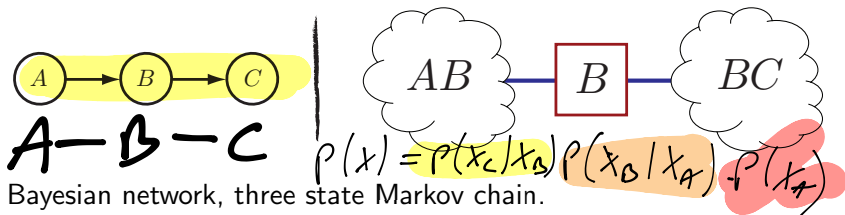
$$\begin{aligned}
 \psi_U^{**} &= \frac{\phi_S^{**}}{\phi_S^*} \psi_U = \psi_U \frac{\sum_{W \setminus S} \psi_W^*}{\sum_{U \setminus S} \psi_U} = \psi_U \frac{\sum_{W \setminus S} \frac{\phi_S^*}{\phi_S} \psi_W}{\sum_{U \setminus S} \psi_U} \\
 &= \psi_U \frac{\sum_{W \setminus S} \psi_W \sum_{U \setminus S} \psi_U}{\sum_{U \setminus S} \psi_U} = \psi_U \sum_{W \setminus S} \psi_W = \sum_{W \setminus S} p(x_U, x_W)
 \end{aligned}$$

# Marginal at $U$ achieved

We moreover have the other marginal we want at  $\psi_U^{**}$  since:

$$\begin{aligned}
 \psi_U^{**} &= \frac{\phi_S^{**}}{\phi_S^*} \psi_U = \psi_U \frac{\sum_{W \setminus S} \psi_W^*}{\sum_{U \setminus S} \psi_U} = \psi_U \frac{\sum_{W \setminus S} \frac{\phi_S^*}{\phi_S} \psi_W}{\sum_{U \setminus S} \psi_U} \\
 &= \psi_U \frac{\sum_{W \setminus S} \psi_W \sum_{U \setminus S} \psi_U}{\sum_{U \setminus S} \psi_U} = \psi_U \sum_{W \setminus S} \psi_W = \sum_{W \setminus S} p(x_U, x_W) \\
 &= p(x_U)
 \end{aligned}$$

# BN Example: $A \rightarrow B \rightarrow C$ with evidence



- Bayesian network, three state Markov chain.
- After moralization and triangulation (which is vacuous), we get maxclique functions  $\psi_{AB}(x_A, x_B)$  and  $\psi_{BC}(x_B, x_C)$ .
- With evidence, we have  $x_C = 1$ . We initialize clique and separator functions as follows:

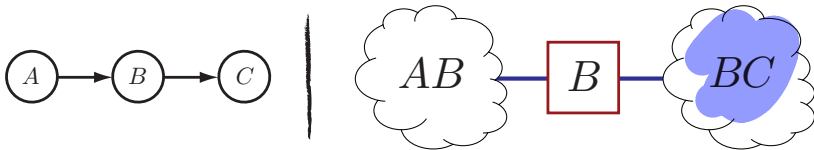
$$\psi_{AB}(x_A, x_B) = p(x_B | x_A) p(x_A) = p(x_A, x_B) \quad (8.27)$$

$$\psi_{BC}(x_B, x_C) = p(x_C | x_B) \delta(x_C, 1) \quad (8.28)$$

$$\phi_B(x_B) = 1 \quad (8.29)$$



# BN Example: $A \rightarrow B \rightarrow C$ with evidence



- Forward (left-to-right) message:

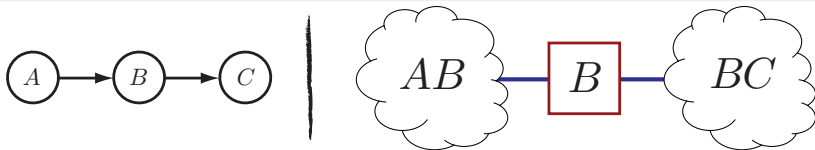
$$\phi_B^*(x_B) = \sum_{x_A} p(x_A, x_B) = p(x_B) \quad (8.30)$$

$$\psi_{BC}^*(x_B, x_C) = \frac{p(x_B)}{1} p(x_C | x_B) \delta(x_C, 1) \quad (8.31)$$

$$= p(x_B, x_C) \delta(x_C, 1) \quad (8.32)$$

$$= p(x_B, x_C = 1) \quad (8.33)$$

# BN Example: $A \rightarrow B \rightarrow C$ with evidence



- Backwards (right-to-left) message

$$\phi_B^{**}(x_B) = \sum_{x_C} p(x_B, x_C) \delta(x_C, 1) = p(x_B, x_C = 1) \quad (8.34)$$

$$\psi_{AB}^{**}(x_A, x_B) = \frac{\phi_B^{**}}{\phi_B^*} \psi_{AB}^* \quad (8.35)$$

$$= \frac{p(B, C = 1)}{p(B)} p(A, B) = p(A|B) \frac{p(B)}{p(B)} p(B, C = 1) \quad (8.36)$$

$$= p(A|B, C = 1) p(B, C = 1) = p(A, B, C = 1) \quad (8.37)$$

# BN Example: $A \rightarrow B \rightarrow C$ with evidence



- We are left with the maxclique functions as marginals, i.e., we have:

$$\psi_{BC}^*(x_B, x_C) = p(x_B, x_C = 1) \quad (8.38)$$

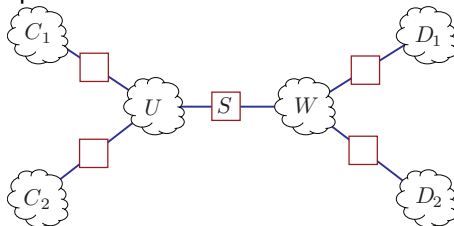
$$\psi_{AB}^{**}(x_A, x_B) = p(x_A, x_B, x_C = 1) \quad (8.39)$$

- ... from which it is easy to construct, say, maxclique conditionals, e.g.,  $p(x_B | x_C = 1)$ ,  $p(x_A, x_B | C = 1)$ , etc.

$$\psi(x_C) = p(x_C | E, \bar{x}_E)$$

## Less simple example: general tree

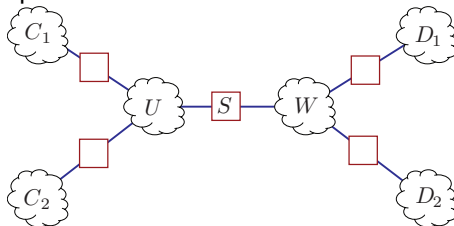
How to ensure any local consistency we achieved not ruined by later message passing steps?



E.g. once we send message  $U \rightarrow W$  and then  $W \rightarrow U$ , we know  $W$  and  $U$  are consistent. If we next send messages  $W \rightarrow D_1$  and  $D_1 \rightarrow W$ , then  $W$  &  $D_1$  are consistent, but  $U$  &  $W$  might no longer be consistent.

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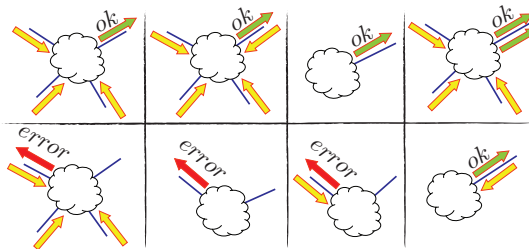
Basic problem, **future messages might mess up achieved local marginal consistency**.

# Ensuring consistency over all marginals

We use same scheme we saw for 1-trees. I.e., recall from earlier lectures:

## Definition 8.4.1 (Message passing protocol)

A clique can send a message to a neighboring cluster in a JT **only** after it has received messages from all of its *other* neighbors.



We already know collect/distribute evidence is a simple algorithm that obeys MPP (designate root, and do bottom up messages and then top-down messages). Does this achieve consistency?

# Maxclique marginals as the goal

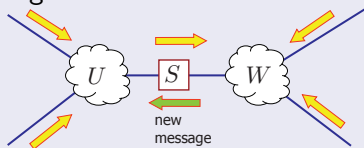
## general trees

### Theorem 8.4.2

*The message passing protocol renders the cliques locally consistent between all pairs of connected cliques in the tree.*

### Proof.

Suppose  $W$  has received a message from all other neighbors, and is sending a message to  $U$ . There are two possible cases: Case A:  $U$  already sent a message to  $W$  before, so  $U$  already received message from all other neighbors, & message renders the two consistent since neither receives any more messages.

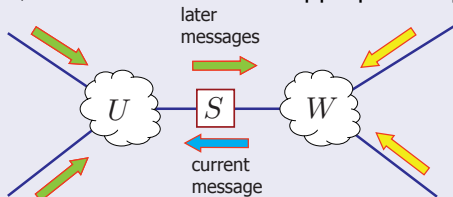


# Maxclique marginals as the goal

## general trees

proof continued.

Case B:  $U$  has not yet sent a message to  $W$ , so  $W$  sends to  $U$  & waits. Later,  $U$  will have received message from all other neighbors & will send message back to  $W$ , but this will contain appropriate update from  $W$ .



Another way we can see it: If we abide by the message passing protocol, the potential functions will just be scaled by a constant, and we'll get back to the same case that we were before with two cliques.



# Maxclique marginals as the goal

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- Note, we need only that it is a cluster tree. Result holds even if r.i.p. not satisfied.
- But we want more than this, we want to ensure that potentials over any two clusters, with common variables, agree on their common variables.

# Local implies global consistency

## Theorem 8.4.4

*In any JT of clusters, any configuration of cluster functions that are locally (neighbor) consistent will be globally consistent. I.e., for any clusters pair  $C_1, C_2$  with  $C_1 \cap C_2 \neq \emptyset$  we have:*

$$\psi_{C_1}(x_{C_1 \cap C_2}) = \psi_{C_2}(x_{C_1 \cap C_2}) \quad (8.40)$$

*for all values  $x_{C_1 \cap C_2}$ .*

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*for all values  $x_{C_1 \cap C_2}$ .*

## Proof.

Local consistency implies that for neighboring  $C_1, C_2$ , the above equality holds. For non-neighboring  $C_1, C_2$ , cluster intersection property (r.i.p.) ensures that intersection  $C_1 \cap C_2$  exists along unique path between  $C_1$  and  $C_2$ . Each edge along that path is locally consistent. By transitivity, each distance-2 pair is consistent. Repeating this argument for any path length gives the result. □

# Consistency gives Marginals

## Theorem 8.4.5

*Given junction tree of clusters  $\mathcal{C}$  and separators  $\mathcal{S}$ , and given above initialization, after all messages are sent and obey MPP, cluster and separator potentials will reach the marginal state:*

$$\psi_C(x_C) = p(x_C) \text{ and } \phi_S(x_S) = p(x_S) \quad (8.41)$$



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## Proof.

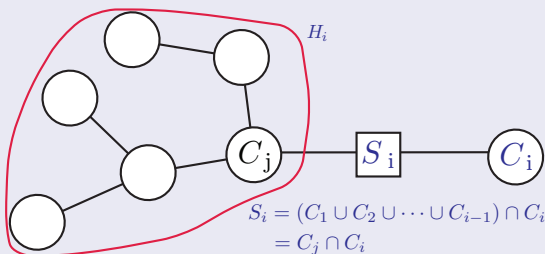
Separators are marginalizations of clusters, so ensuring clusters are marginals is sufficient for separators as marginals.

Induction: base case: One cluster is a marginal. Two clusters reach marginals (we verified above).

Assume true for  $i - 1$  clusters marginals, and show for  $i$ . Given JT with clusters  $C_1, \dots, C_{i-1}$  and add new cluster  $C_i$  connecting to  $C_j$  and obeying r.i.p. We have separator  $S_i = C_i \cap C_j$ .

# Consistency gives Marginals

... proof continued.



We have (as always)  $p(x) = p(x_V)$  and that

$$p(x_V) = p(x_{C_i \setminus S_i}, x_{S_i}, x_{V \setminus C_i}) = p(x_{C_i \setminus S_i} | x_{S_i}) p(x_{S_i \cup (V \setminus C_i)}) \quad (8.42)$$

due to conditional independence property of separator  $S$

$$X_{C_i \setminus S_i} \perp\!\!\!\perp X_{V \setminus C_i} | X_S \quad (8.43)$$

# Consistency gives Marginals

... proof continued.

We have:

$$p(x_{S_i \cup (V \setminus C_i)}) = \sum_{x_{C_i \setminus S_i}} p(x_V) = \sum_{x_{C_i \setminus S_i}} \frac{\prod_{C \in \mathcal{C}} \psi_C(x_C)}{\prod_{S \in \mathcal{S}} \phi_S(x_S)^{d(S)-1}} \quad (8.44)$$

$$= \sum_{x_{C_i \setminus S_i}} \frac{\psi_{C_i}(x_{C_i}) \prod_{C \neq C_i} \psi_C(x_C)}{\phi_{S_i}(x_{S_i}) \prod_{S \in \mathcal{S}} \phi_S(x_S)^{d'(S)-1}} \quad (8.45)$$

$$= \frac{\sum_{x_{C_i \setminus S_i}} \psi_{C_i}(x_{C_i})}{\phi_{S_i}(x_{S_i})} \frac{\prod_{C \neq C_i} \psi_C(x_C)}{\prod_{S \in \mathcal{S}} \phi_S(x_S)^{d'(S)-1}} \quad (8.46)$$

$$= \frac{\prod_{C \neq C_i} \psi_C(x_C)}{\prod_{S \in \mathcal{S}} \phi_S(x_S)^{d'(S)-1}} \quad (8.47)$$

since  $\sum_{x_{C_i \setminus S_i}} \psi_{C_i}(x_{C_i}) = \phi_{S_i}(x_{S_i})$  and since the only cluster containing  $C_i \setminus S_i$  is  $C_i$ .  $d'(S) = d(S)$  except at  $S_i$  where one less.

# Consistency gives Marginals

... proof continued.

With only  $i - 1$  cliques, after message passing is performed, JT will have cluster functions as marginals (by induction). We need to show that  $\psi_{C_i}(x_{C_i})$  is also a valid marginal. After MP, we have local and global consistency, so

$$\phi_{S_i}(x_{S_i}) = \sum_{x_{C_j \setminus S_i}} \psi_{C_j}(x_{C_j}) \quad (8.48)$$

and by induction we have that  $\psi_{C_j}(x_{C_j}) = p(x_{C_j})$  giving:

$$p(x_{C_i \setminus S_i} | x_{S_i}) = \frac{p(x)}{p(x_{S_i \cup (V \setminus C_i)})} = \frac{\frac{\prod_{C \in \mathcal{C}} \psi_C(x_C)}{\prod_{S \in \mathcal{S}} \phi_S(x_S)^{d(S)-1}}}{\frac{\prod_{C \neq C_i} \psi_C(x_C)}{\prod_{S \in \mathcal{S}} \phi_S(x_S)^{d'(S)-1}}}, \quad (8.49)$$

where the first equality follows from Equation (8.42).

# Consistency gives Marginals

... proof continued.

which yields

$$p(x_{C_i \setminus S_i} | x_{S_i}) = \frac{\psi_{C_i}(x_{C_i})}{\phi_{S_i}(x_{S_i})} = \frac{\psi_{C_i}(x_{C_i})}{p(x_{S_i})} \quad (8.50)$$

this then gives that:

$$\psi_{C_i}(x_{C_i}) = p(x_{C_i \setminus S_i} | x_{S_i}) p(x_{S_i}) = p(x_{C_i}) \quad (8.51)$$

a marginal as desired. □

# Redundant Messages

- Once all messages have been sent according to MPP, what would happen if we send more messages?
- 1-tree formulation:

$$\mu_{i \rightarrow j}(x_j) = \sum_{x_i} \psi_{i,j}(x_i, x_j) \prod_{k \in \delta(i) \setminus \{j\}} \mu_{k \rightarrow i}(x_i) \quad (8.52)$$

- Junction-tree formulation: marginalize and rescale

$$\phi_S^{\text{new}} = \sum_{U \setminus S} \psi_U \text{ and then } \psi_W^{\text{new}} = \frac{\phi_S^{\text{new}}}{\phi_S^{\text{old}}} \psi_W \quad (8.53)$$

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- In either case, extra messages would not change functions - they're redundant, joint "state" has "converged" since  $\phi_S^{\text{new}} = \phi_S^{\text{old}}$ .
- all messages could run in parallel, convergence achieved once we've done  $D$  parallel steps where  $D$  is tree diameter.

# Distributive Law and Other Objects

- Only one property needed for this algorithm to work, namely distributive law  $ab + ac = a(b + c)$  along with factorization.
- Distributive law allows sending sums inside of factors.
- Other objects have distribute law, and in general any set of objects that is a commutative semiring will work as well



# Commutative Semirings

## Definition 8.5.1

A *commutative semiring* is a set  $K$  with two binary operators “+” and “.” having three axioms, for all  $a, b, c \in K$ .

S1: “+” is commutative  $(a + b) = (b + a)$  and associative  $(a + b) + c = a + (b + c)$ , and  $\exists$  additive identity called “0” such that  $k + 0 = k$  for all  $k \in K$ . I.e.,  $(K, +)$  is a commutative monoid.

S2: “.” is also associative, commutative, and  $\exists$  multiplicative identity called “1” s.t.  $k \cdot 1 = k$  for all  $k \in K$  ( $(K, \cdot)$  is also a comm. monoid).

S3: distributive law holds:  $(a \cdot b) + (a \cdot c) = a(b + c)$  for all  $a, b, c \in K$ .

This, and factorization w.r.t. a graph  $G$  is all that is necessary for the above message passing algorithms to work. There are many commutative semirings.

# Commutative Semirings

- Additive inverse need not exist. If additive inverse exists, then we get a commutative ring ("semi-ring" since we need not have additive inverse). Note, in algebra texts, a ring often doesn't require multiplicative identity, but we assume it exists here.

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- Above definition does not mention  $0 \cdot k = 0$ , but this follows from above properties since  $k \cdot k = k(k + 0) = k \cdot k + k \cdot 0$  so that  $k \cdot 0$  must also be an additive identity, meaning that  $k \cdot 0 = 0$ . This is useful with evidence with delta functions, where the delta functions multiplies by zero anything that does not obide by the evidence value.

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- Same message passing protocol and message passing scheme on a junction tree will work to ensure that all clusters reach a state where they are the appropriate "marginals"
- Marginals in this case dependent on ring.

# Other Semi-Rings

Here,  $A$  denotes arbitrary commutative semiring,  $S$  is arbitrary finite set,  $\Lambda$  is arbitrary distributed lattice.

	$K$	$“(+, 0)”$	$“(., 1)”$	short name
1	$A$	$(+, 0)$	$(., 1)$	semiring
2	$A[x]$	$(+, 0)$	$(., 1)$	polynomial
3	$A[x, y, \dots]$	$(+, 0)$	$(., 1)$	polynomial
4	$[0, \infty)$	$(+, 0)$	$(., 1)$	sum-product
5	$(0, \infty]$	$(\min, \infty)$	$(., 1)$	min-product
6	$[0, \infty)$	$(\max, 0)$	$(., 1)$	max-product
7	$[0, \infty)+$	$(k\max, 0)$	$(., 1)$	$k$ -max-product
8	$(-\infty, \infty]$	$(\min, \infty)$	$(+, 0)$	min-sum
9	$[-\infty, \infty)$	$(\max, -\infty)$	$(+, 0)$	max-sum
10	$\{0, 1\}$	$(\text{OR}, 0)$	$(\text{AND}, 1)$	Boolean
11	$2^S$	$(\cup, \emptyset)$	$(\cap, S)$	Set
12	$\Lambda$	$(\vee, 0)$	$(\wedge, 1)$	Lattice
13	$\Lambda$	$(\wedge, 1)$	$(\vee, 0)$	Lattice

# Example: Viterbi/MPE

- Most-probable explanation (e.g., Viterbi assignment) is just the max-product ring.
- Here, we wish to compute

$$\operatorname{argmax}_{x_{V \setminus E}} p(x_{V \setminus E}, \bar{x}_E) \quad (8.54)$$

- After message passing with the max-product ring on a junction tree, cluster functions will reach the “max-marginal” state, where we have:

$$\psi_C(x_C) = \max_{x_{V \setminus C}} p(x_C, x_{V \setminus C}) \quad (8.55)$$

- What about a “ $k$ -max” operation (i.e., finding the  $k$  highest scoring assignments to the variables?) How would we define the operators “ $+$ ” and “ $\cdot$ ”?

# Recap

- Message passing on junction tree nodes, definition of messages, divide out old, multiply in new.

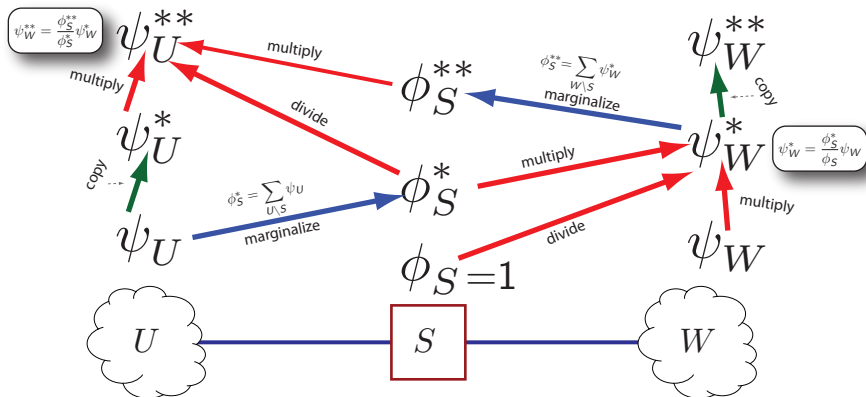


# Recap

- Message passing on junction tree nodes, definition of messages, divide out old, multiply in new.
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# Forward/Backward Messages Along Cluster Tree Edge

Summarizing, forward and backwards messages proceed as follows:



Recall:  $S = U \cap W$ , and we initialize  $\psi_U$  and  $\psi_W$  with factors that are contained in  $U$  or  $W$ .

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- In JT (r.i.p.), running MPP gives marginals.
- Commutative semiring - other algebraic objects can be used.
- Time and memory complexity is  $O(Nr^{\omega+1})$  where  $\omega$  is the tree-width.

# Sources for Today's Lecture

- Most of this material comes from the reading handout `tree_inference.pdf`