EE512A – Advanced Inference in Graphical Models

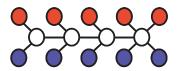
— Fall Quarter, Lecture 16 —

http://j.ee.washington.edu/~bilmes/classes/ee512a_fall_2014/

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Nov 24th, 2014



Announcements

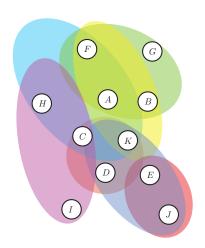
- Wainwright and Jordan Graphical Models, Exponential Families, and Variational Inference http://www.nowpublishers.com/product. aspx?product=MAL&doi=2200000001
- Should have read chapters 1,2, 3, 4 in this book. Read chapter 5.
- Also should read "Divergence measures and message passing" by Thomas Minka, and "Structured Region Graphs: Morphing EP into GBP", by Welling, Minka, and Teh.
- Assignment due Wednesday (Nov 26th) night, 11:45pm. Final project proposal updates and progress report (one page max).

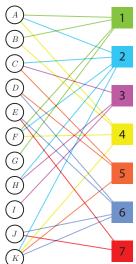
- L1 (9/29): Introduction, Families, Semantics
- L2 (10/1): MRFs, elimination, Inference on Trees
- L3 (10/6): Tree inference, message passing, more general queries, non-tree)
- L4 (10/8): Non-trees, perfect elimination, triangulated graphs
- \bullet L5 (10/13): triangulated graphs, k-trees, the triangulation process/heuristics
- L6 (10/15): multiple queries, decomposable models, junction trees
- L7 (10/20): junction trees, begin intersection graphs
- L8 (10/22): intersection graphs, inference on junction trees
- L9 (10/27): inference on junction trees, semirings,
- L10 (11/3): conditioning, hardness, LBP

- L11 (11/5): LBP, exponential models,
- L12 (11/10): exponential models, mean params and polytopes,
- L13 (11/12): polytopes, tree outer bound, Bethe entropy approx.
- L14 (11/17): Bethe entropy approx, loop series correction
- L15 (11/19): Hypergraphs, posets, Mobius, Kikuchi
- L16 (11/24): Kikuchi, Expectation Propagation
- L17 (11/26): Expectation Propagation, Mean Field
- L18 (12/1):
- L19 (12/3):
- Final Presentations: (12/10):

Drawing/Visualizing Hypergraphs as Bipartite Graphs

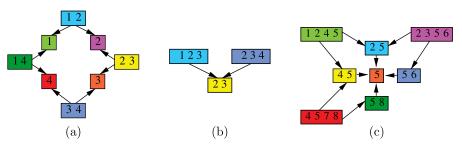
• Hypergraph (shaded regions) on left, while bipartite graph representation on the right.





Hypergraph, edge representations

- It is possible to represent hypergraphs by only showing their hyperedges.
- Here, we see graphical representations of three hypergraphs. Subsets of nodes corresponding to hyperedges are shown in rectangles, whereas the arrows represent inclusion relations among hyperedges.



• Which ones, if any, are in reduced representation?

Möbius Inversion Lemma and Inclusion-Exclusion

- For any $A \subseteq V$, define two functions $\Omega : 2^V \to \mathbb{R}$ and $\Upsilon : 2^V \to \mathbb{R}$.
- Then the above inclusion-exclusion principle is one instance of the more general Möbius Inversion lemma, namely that each of the below two equations implies the other.

$$\forall A \subseteq V : \Upsilon(A) = \sum_{B:B \subseteq A} \Omega(B)$$
 (16.13)

$$\forall A \subseteq V : \Omega(A) = \sum_{B:B \subseteq A} (-1)^{|A \setminus B|} \Upsilon(B)$$
 (16.14)

- Möbius Inversion lemma is also used to prove the Hammersley-Clifford theorem (that factorization and Markov property definitions of families are identical for positive distributions).
- We use it here to come up with alternative expressions for the entropy and for the marginal polytope.

Möbius Inversion Lemma for posets

- Let \mathcal{P} be a partially ordered set with binary relation \leq .
- A zeta function of a poset is a mapping $\zeta: \mathcal{P} \times \mathcal{P} \to \mathbb{R}$ defined by

$$\zeta(g,h) = \begin{cases} 1 & \text{if } g \leq h, \\ 0 & \text{otherwise.} \end{cases}$$
 (16.23)

- The Möbius function $\omega : \mathcal{P} \times \mathcal{P} \to \mathbb{R}$ is the multiplicative inverse of this function. It is defined recursively:
- $\omega(g,g) = 1$ for all $g \in \mathcal{P}$
- $\omega(g,h) = 0$ for all $h: h \npreceq g$.
- Given $\omega(g,f)$ defined for f such that $g \leq f \prec h$, we define

$$\omega(g,h) = -\sum_{\{f|g \le f \prec h\}} \omega(g,f) \tag{16.24}$$

• Then, ω and ζ are multiplicative inverses, in that

$$\sum_{f \in \mathcal{P}} \omega(g, f) \zeta(f, h) = \sum_{\{f \mid g \preceq f \preceq h\}} \omega(g, f) = \delta(g, h)$$
 (16.25)

General Möbius Inversion Lemma for Posets

Lemma 16.2.8 (General Möbius Inversion Lemma)

Given real valued functions Υ and Ω defined on poset $\mathcal P$, then $\Omega(h)$ may be expressed via $\Upsilon(\cdot)$ via

$$\Omega(h) = \sum_{g \leq h} \Upsilon(g) \quad \text{for all } h \in \mathcal{P}$$
 (16.23)

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$$\Upsilon(h) = \sum_{g \leq h} \Omega(g)\omega(g, h)$$
 for all $h \in \mathcal{P}$ (16.24)

When $\mathcal{P}=2^V$ for some set V (so this means that the poset consists of sets and all subsets of an underlying set V) this can be simplified, where \preceq becomes \subseteq ; and \succeq becomes \supseteq , like we saw above. (see Stanley, "Enumerative Combinatorics" for more info.)

Back to Kikuchi: Möbius and expressions of factorization

• Suppose we are given marginals that factor w.r.t. a hypergraph G=(V,E), so we have $\mu=(\mu_h,h\in E)$, then we can define new functions $\varphi=(\varphi_h,h\in E)$ via Möbius inversion lemma as follows

$$\log \varphi_h(x_h) \triangleq \sum_{g \leq h} \omega(g, h) \log \mu_g(x_g)$$
 (16.23)

 From Möbius inversion lemma, this then gives us a new way to write the log marginals, i.e., as

$$\log \mu_h(x_h) = \sum_{g \le h} \log \varphi_g(x_g) \tag{16.24}$$

ullet Key, when $arphi_h$ is defined as above, and G is a hypertree we have

$$p_{\mu}(x) = \prod_{h \in E} \varphi_h(x_h) \tag{16.25}$$

⇒ general way to factorize a distribution that factors w.r.t. a hypergraph.

multi-information decomposition

• Using Möbius, and Eqn. (??) we can write

$$I_h(\mu_h) = \sum_{x_h} \mu_h(x_h) \log \varphi_h(x_h) = \sum_{x_h} \mu_h(x_h) \left(\sum_{g \leq h} \omega(g, h) \log \mu_g(x_g) \right)$$

$$= \sum_{g \leq h} \omega(g, h) \left\{ \sum_{x_h} \mu_h(x_h) \log \mu_g(x_g) \right\}$$

$$= \sum_{f \leq h} \sum_{e \succeq f} \omega(f, e) \left\{ \sum_{x_f} \mu_f(x_f) \log \mu_f(x_f) \right\} = -\sum_{f \leq h} c(f) H_f(\mu_f)$$

where we define overcounting numbers (\sim shattering coefficient)

$$c(f) \triangleq \sum_{e \succeq f} \omega(f, e) \tag{16.31}$$

• This gives us a new expression for the hypertree entropy

$$H_{\mathsf{hyper}}(\mu) = \sum_{h \in E} c(h) H_h(\mu_h) \tag{16.32}$$

Usable to get Kikuchi variational approximation

• Sum to one constraint:

$$\sum_{x_h} \tau_h(x_h) = 1 \tag{16.33}$$

• Local agreement via the hypergraph constraint. For any $g \leq h$ must have marginalization condition

$$\sum_{x_{h\backslash g}} \tau_h(x_h) = \tau_g(x_g) \tag{16.34}$$

• Define new polyhedral constraint set $\mathbb{L}_t(G)$

$$\mathbb{L}_t(G) = \{ \tau \ge 0 | \text{ Equations (\ref{eq:total_tot$$

Kikuchi variational approximation, entropy approx

• Generalized approximate (app) entropy for the hypergraph:

$$H_{\mathsf{app}} = \sum_{g \in E} c(g) H_g(\tau_g) \tag{16.33}$$

where H_g is hyperedge entropy and overcounting number defined by:

$$c(g) = \sum_{f \succeq g} \omega(g, f) \tag{16.34}$$

Variational Approach Amenable to Approximation

Original variational representation of log partition function

$$A(\theta) = \sup_{\mu \in \mathcal{M}} \left\{ \langle \theta, \mu \rangle - A^*(\mu) \right\}$$
 (16.1)

where dual takes form:

$$A^{*}(\mu) = \sup_{\theta \in \Omega} (\langle \theta, \mu \rangle - A(\theta)) = \begin{cases} -H(p_{\theta(\mu)}) & \text{if } \mu \in \mathcal{M}^{\circ} \\ +\infty & \text{if } \mu \notin \overline{\mathcal{M}} \end{cases}$$
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- Given efficient expression for $A(\theta)$, we can compute marginals of interest.
- Above expression (dual of the dual) offers strategies to approximate or (upper or lower) bound $A(\theta)$. We either approximate \mathcal{M} or $-A^*(\mu)$ or (most likely) both.

Variational Approximations we cover

• Set $\mathcal{M} \leftarrow \mathbb{L}$ and $-A^*(\mu) \leftarrow H_{\mathsf{Bethe}}(\tau)$ to get Bethe variational approximation, LBP fixed point.

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- Set $\mathcal{M} \leftarrow \mathbb{L}$ and $-A^*(\mu) \leftarrow H_{\mathsf{Bethe}}(\tau)$ to get Bethe variational approximation, LBP fixed point.
- ② Set $\mathcal{M} \leftarrow \mathbb{L}_t(G)$ (hypergraph marginal polytope), $-A^*(\mu) \leftarrow H_{\mathsf{app}}(\tau)$ where $H_{\mathsf{app}} = \sum_{g \in E} c(g) H_g(\tau_g)$ (via Möbius) to get Kikuchi variational approximation, message passing on hypergraphs.

• This at last gets the Kikuchi variational approximation

$$A_{\mathsf{Kikuchi}}(\theta) = \max_{\tau \in \mathbb{L}_t(G)} \left\{ \langle \theta, \tau \rangle + H_{\mathsf{app}}(\tau) \right\} \tag{16.1}$$

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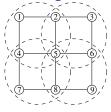
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- Also, if hypergraph is junction tree (r.i.p. holds, tree-local consistency implies global consistency), then also exact (although expensive, exponential in the tree-width to compute H_{app}).

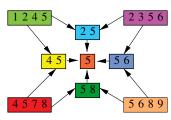
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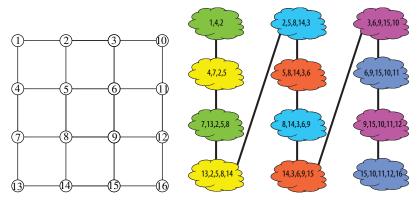
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- Also, if hypergraph is junction tree (r.i.p. holds, tree-local consistency implies global consistency), then also exact (although expensive, exponential in the tree-width to compute $H_{\rm app}$).
- We can define message passing algorithms on the hypertree, and show that if it converges, it is a fixed point of the associated Lagrangian.

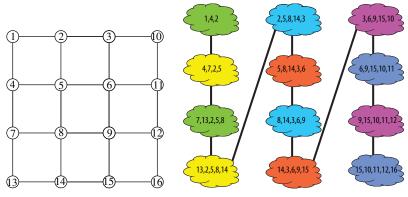




• Example, left is 3x3 grid, right is optimal junction tree cover.

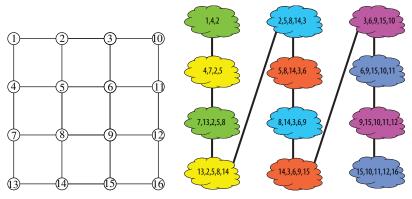


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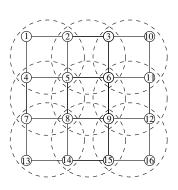
ullet Treewidth is 4, so complexity is $O(r^5)$.

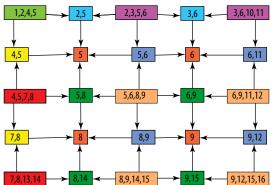
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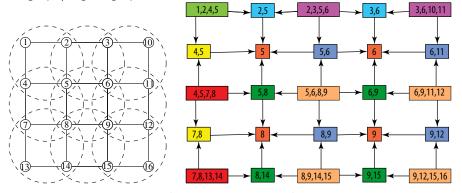
- Treewidth is 4, so complexity is $O(r^5)$.
- In general, for $n \times n$ grid strutured graph, treewidth is O(n) (grows as the square root of the number of nodes).

• Left is clustering of vertices in 3x3 grid, and right is hyperedge graph/region graph.





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• Complexity is only $O(r^4)$ and will stay $O(r^4)$ even as n gets bigger (since clusters are at most size four).

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- This gives the user a gradual tradeoff between the most expensive, intractable, and accurate junction tree algorithm, and the least expensive but possibly quite inaccurate LBP algorithm.

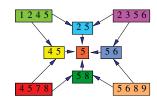
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- Allows a trade-off between complexity for accuracy!
- In many cases, convergence of GBP will be at fixed points of the Lagrangian for the generalized variational approximation

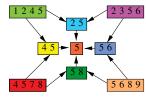
$$A_{\mathsf{Kikuchi}}(\theta) = \max_{\tau \in \mathbb{L}_t(G)} \left\{ \langle \theta, \tau \rangle + H_{\mathsf{app}}(\tau) \right\} \tag{16.2}$$

GBP examples: parent-to-child

In hypergraph Hasse-like diagram, arrows point from parent (superset) to child (subset). Ex: on the right, set $\{1,2,4,5\}$ is the parent of both $\{2,5\}$ and $\{4,5\}$.



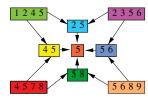
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• For $h \in E$, let Par(h) be the set of parents. Also define descendants as $\mathcal{D}(h) = \{g \in E | g \prec h\}$ and ancestors as $\mathcal{A}(h) = \{g \in E | g \succ h\}$.

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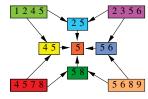
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- Also define $\mathcal{D}^+(h) = \mathcal{D}(h) \cup \{h\}$ and $\mathcal{A}^+(h) = \mathcal{A}(h) \cup \{h\}$

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- Also define $\mathcal{D}^+(h) = \mathcal{D}(h) \cup \{h\}$ and $\mathcal{A}^+(h) = \mathcal{A}(h) \cup \{h\}$
- If $f\succ g$ then x_f has more variables than x_g and one can perform a message of the form $M_{f\to g}(x_g)=\sum_{f\setminus g}\tau(x_f)=\sum_{f\setminus g}\tau(x_g,x_{f\setminus g})$

GBP examples: parent-to-child message

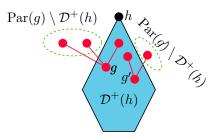
• Then parent-to-child message passing takes the form:

$$\tau_h(x_h) \propto \left[\prod_{g \in \mathcal{D}^+(h)} \exp(\theta(x_g)) \right] \left[\prod_{g \in \mathcal{D}^+(h)} \prod_{f \in \mathsf{Par}(g) \setminus \mathcal{D}^+(h)} M_{f \to g}(x_g) \right]$$
(16.3)

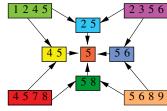
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We form marginal at h from the factors associated with each hyperedge, namely $\exp(\theta(x_g))$, and by the messages sent to h and h's descendants from other parents.

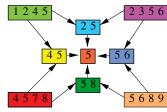




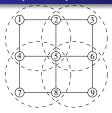


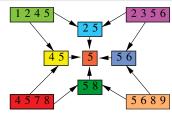
• Consider message for hyperedge $h=\{1,2,4,5\}$, which has factors ψ' associated with (regular graph) edges $\{1,2\}$, $\{2,5\}$, $\{4,5\}$, and $\{1,4\}$ and also unary factors for each of the nodes 1, 2, 4, and 5 (eg., to associate evidence into the model).





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- Then $\mathcal{D}^+(h) = \{\{1, 2, 4, 5\}, \{4, 5\}, \{2, 5\}, \{5\}\}.$

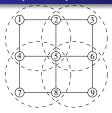


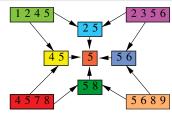


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- ullet We get and expression for the marginal at h using the above formula.

$$\tau_{1,2,4,5} \propto \psi'_{1,2} \psi'_{1,4} \psi'_{2,5} \psi'_{4,5} \psi'_{1} \psi'_{2} \psi'_{4} \psi'_{5}$$

$$\times M_{\{2,3,5,6\} \to \{2,5\}} M_{\{4,5,7,8\} \to \{4,5\}} M_{\{5,6\} \to \{5\}} M_{\{5,8\} \to \{5\}}$$
(16.4)





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$$\times M_{\{2,3,5,6\} \to \{2,5\}} M_{\{4,5,7,8\} \to \{4,5\}} M_{\{5,6\} \to \{5\}} M_{\{5,8\} \to \{5\}}$$

• This could repeat for each of the largest clusters, until convergence.

Theorem 16.4.3 (Relationship between A and A^*)

(a) For any $\mu \in \mathcal{M}^{\circ}$, $\theta(\mu)$ unique canonical parameter sat. matching condition, then conj. dual takes form:

$$A^{*}(\mu) = \sup_{\theta \in \Omega} (\langle \theta, \mu \rangle - A(\theta)) = \begin{cases} -H(p_{\theta(\mu)}) & \text{if } \mu \in \mathcal{M}^{\circ} \\ +\infty & \text{if } \mu \notin \overline{\mathcal{M}} \end{cases}$$
(16.3)

(b) Partition function has variational representation (dual of dual)

$$A(\theta) = \sup_{\mu \in \mathcal{M}} \left\{ \langle \theta, \mu \rangle - A^*(\mu) \right\}$$
 (16.4)

(c) For $\theta \in \Omega$, sup occurs at $\mu \in \mathcal{M}^{\circ}$ of moment matching conditions

$$\mu = \int_{D_X} \phi(x) p_{\theta}(x) \nu(dx) = \mathbb{E}_{\theta}[\phi(X)] = \nabla A(\theta)$$
 (16.5)

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- Interestingly, EP is instance of our variational framework, Equation

Term Decoupling in EP

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- So $\phi: \mathcal{X}^m \to \mathbb{R}^{d_T}$ with vector of parameters $\theta \in \mathbb{R}^{d_T}$.
- Could instantiate model based only on this subcomponent, called the base model

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- \bullet $\Phi: \mathcal{X}^m \to \mathbb{R}^{b \times d_I}$.
- Parameters $\tilde{\theta} \in \mathbb{R}^{b \times d_I}$.

• The associated exponential family

$$p(x; \theta, \tilde{\theta}) \propto \exp(\langle \theta, \phi(x) \rangle) \exp(\langle \tilde{\theta}, \Phi(x) \rangle)$$
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$$= \exp\left(\langle \theta, \phi(x) \rangle\right) \prod_{i=1}^{d_I} \exp\left(\left\langle \tilde{\theta}^i, \Phi^i(x) \right\rangle\right) \tag{16.10}$$

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Associated Distributions: key points

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- Intractable to perform exact computations with the full (ϕ, Φ) -exponential family.

Example: Mixture models

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• Assume we have obtained n i.i.d. samples y^1, \ldots, y^n from mixture density, and goal is to produce posterior $p(x|y^1, \ldots, y^n)$, similar to Bayes-rule inverting a Naive-Bayes model.

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- Using Bayes rule, we get mixture model with 2^n components!

$$p(x|y^1, \dots, y^n) \propto \exp\left(-\frac{1}{2}x^{\mathsf{T}}\Sigma^{-1}x\right) \prod_{i=1}^n p(y^i|X=x)$$

$$= \exp\left(-\frac{1}{2}x^{\mathsf{T}}\Sigma^{-1}x\right) \exp\left\{\sum_{i=1}^n \log p(y^i|X=x)\right\}$$
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- Computing marginals is easy (mixture of only 2 components)
- If we multiply in all Φ^i , becomes intractable $(2^n$ potentially distinct components each of which requires marginalization).

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ullet Recall thm: any mean in the interior is realizable via an exponential family model, and associated entropy $H(\mu)$ is tractable.

ullet For each $i=1\dots d_I$ we have a Φ^i -augmented exp. model and polytope

$$\mathcal{M}(\phi, \Phi^i) = \left\{ (\mu, \tilde{\mu}^i) \in \mathbb{R}^{d_T + b} | (\mu, \tilde{\mu}^i) = \mathbb{E}_p[(\phi(X), \Phi^i(X))] \text{ for some } p \right\}$$
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- Goal, variational approximation: Need outer bounds on $\mathcal{M}(\phi, \Phi)$ and expression for entropy (as is now normal).
- Turns out we can do this, and an iterative algorithm to find fixed points of associated Lagrangian, that correspond to EP.

• For any mean parms $(\tau, \tilde{\tau})$ where $\tilde{\tau} = (\tilde{\tau}^1, \tilde{\tau}^2, \dots, \tilde{\tau}^{d_I})$, define coordinate "projection operation"

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This operator simply removes all but $\tilde{\tau}^i$ from $\tilde{\tau}$.

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$$\mathcal{L}(\phi, \Phi) = \left\{ (\tau, \tilde{\tau}) \middle| \tau \in \mathcal{M}(\phi), \Pi^{i}(\tau, \tilde{\tau}) \in \mathcal{M}(\phi, \Phi^{i}), \ \forall i \right\}$$
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- ullet Note, based on a set of projections onto $\mathcal{M}(\phi,\Phi^i)$.
- Outer bound, i.e., $\mathcal{M}(\phi, \Phi) \subseteq \mathcal{L}(\phi, \Phi)$, since:

$$\tau \in \mathcal{M}(\phi) \Leftrightarrow \exists p \text{ s.t. } \tau = E_p[\phi(X)]$$
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$$(\tau, \tilde{\tau}) \in \mathcal{L}(\phi, \Phi) \Leftrightarrow \tau \in \mathcal{M}(\phi) \& \exists p \text{ s.t. } (\tau, \tilde{\tau}^i) = E_p[\phi(X), \Phi^i(X)]$$

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• For any mean parms $(\tau, \tilde{\tau})$ where $\tilde{\tau} = (\tilde{\tau}^1, \tilde{\tau}^2, \dots, \tilde{\tau}^{d_I})$, define coordinate "projection operation"

$$\Pi^{i}(\tau,\tilde{\tau}) \to (\tau,\tilde{\tau}^{i})$$
(16.20)

This operator simply removes all but $\tilde{\tau}^i$ from $\tilde{\tau}$.

ullet Define outer bound on true means $\mathcal{M}(\phi,\Phi)$ (which is still convex)

$$\mathcal{L}(\phi, \Phi) = \left\{ (\tau, \tilde{\tau}) | \tau \in \mathcal{M}(\phi), \Pi^{i}(\tau, \tilde{\tau}) \in \mathcal{M}(\phi, \Phi^{i}), \forall i \right\}$$
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ullet If Φ^i are edges of a graph (i.e. local consistency) then we get standard ${\mathbb L}$ outer bound we saw before with Bethe approximation

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- Both entropy forms are easy to compute, and so is a new entropy approximation:

$$H(\tau, \tilde{\tau}) \approx H_{\mathsf{ep}}(\tau, \tilde{\tau}) \triangleq H(\tau) + \sum_{\ell=1}^{d_I} \left[H(\tau, \tilde{\tau}^l) - H(\tau) \right]$$
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With outer bound and entropy expression, we get new variational form

$$\max_{(\tau,\tilde{\tau})\in\mathcal{L}(\phi,\Phi)} \left\{ \langle \tau,\theta \rangle + \left\langle \tilde{\tau},\tilde{\theta} \right\rangle + H_{\mathsf{ep}}(\tau,\tilde{\tau}) \right\} \tag{16.26}$$

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- This characterizes the EP algorithms.
- Given graph G=(V,E) when we take ϕ to be unaries V and Φ to be edges E, we exactly recover Bethe approximation.

Lagrangian optimization setup

• Make d_I duplicates of vector $\tau \in \mathbb{R}^{d_T}$, call them $\eta^i \in \mathbb{R}^{d_T}$ for $i \in [d_T]$.

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- This gives large set of pseudo-mean parameters

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• We arrive at the optimization:

$$\max_{\left\{\tau, \left\{(\eta^{i}, \tilde{\tau}^{i})\right\}_{i}\right\}} \left\{ \left\langle \tau, \theta \right\rangle + \sum_{i=1}^{d_{I}} \left\langle \tilde{\tau}^{i}, \tilde{\theta}^{i} \right\rangle + H(\tau) + \sum_{i=1}^{d_{I}} \left[H(\eta^{i}, \tilde{\tau}^{i}) - H(\eta^{i}) \right] \right\}$$
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subject to $\tau \in \mathcal{M}(\phi)$, and for all i that $\tau = \eta^i$ and that $(\eta^i, \tilde{\tau}^i) \in \mathcal{M}(\phi, \Phi^i)$.

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subject to $\tau \in \mathcal{M}(\phi)$, and for all i that $\tau = \eta^i$ and that $(\eta^i, \tilde{\tau}^i) \in \mathcal{M}(\phi, \Phi^i)$.

• Use Lagrange multipliers to impose constraint $\eta^i = \tau$ for all i, and for the rest of the constraints too.

To Lagrangian optimization

• We get a Lagrangian version of the objective

$$L(\tau;\lambda) = \langle \tau, \theta \rangle + \sum_{i=1}^{d_I} \left\langle \tilde{\tau}^i, \tilde{\theta}^i \right\rangle + F(\tau; (\eta^i, \tilde{\tau}^i)) + \sum_{i=1}^{d_I} \left\langle \lambda^i, \tau - \eta^i \right\rangle + \dots$$
(16.29)

where

$$F(\tau; (\eta^{i}, \tilde{\tau}^{i})) = H(\tau) + \sum_{i=1}^{d_{I}} \left[H(\eta^{i}, \tilde{\tau}^{i}) - H(\eta^{i}) \right]$$
 (16.30)

and where λ^i are the Lagrange multipliers assocaited with the constraint $\eta^i=\tau$ for all i (other multipliers not shown).

To Lagrangian optimization to Moment Matching

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- First condition means we're a member of the ϕ -exponential family, and (it can be shown) has form:

$$q(x; \theta, \lambda) \propto \exp\left\{\left\langle \theta + \sum_{i=1}^{d_I} \lambda^i, \phi(x)\right\rangle\right\}$$
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 \bullet Second condition means we're a member of the (ϕ,Φ^i) -exponential family, and (it can be shown) has form:

$$q^{i}(x, \theta, \tilde{\theta}^{i}, \lambda) \propto \exp\left(\left\langle \theta + \sum_{\ell \neq i} \lambda^{\ell}, \phi(x) \right\rangle + \left\langle \tilde{\theta}^{i}, \Phi^{i}(x) \right\rangle\right)$$
 (16.32)

• Thid condiiton is a form of moment-matching. I.e., we have $\tau = E_q[\phi(X)]$ and $\eta^i = E_{\sigma^i}[\phi(X)]$, so equating these gives:

$$\int q(x;\theta,\lambda)\phi(x)\nu(dx) = \int q^{i}(x;\theta,\tilde{\theta}^{i})\phi(x)\nu(dx)$$
 (16.33)

fro $i \in [d_I]$.

$\mathsf{Moment}\ \mathsf{Matching} o \mathsf{Expectation}\ \mathsf{Propagation}\ \mathsf{Updates}$

1 At iteration n=0, initialize the Lagrange multiplier vectors $(\lambda^1,\ldots,\lambda^{d_I})$

Moment Matching o Expectation Propagation Updates

- **4** At iteration n=0, initialize the Lagrange multiplier vectors $(\lambda^1,\ldots,\lambda^{d_I})$
- **2** At each iteration $n = 1, 2, \ldots$ choose some index $i(n) \in \{1, \ldots, d_I\}$.

${\color{red}\mathsf{Moment}}\ {\color{blue}\mathsf{Matching}}\ {\color{blue}\to}\ {\color{blue}\mathsf{Expectation}}\ {\color{blue}\mathsf{Propagation}}\ {\color{blue}\mathsf{Updates}}$

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compute the mean parameters η^i as follows:

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 \blacksquare Form base distribution q using Equation 16.31 and adjust $\lambda^{i(n)}$ to satisfy the moment-matching condition

$$\mathbb{E}_q[\phi(X)] = \eta^{i(n)} \tag{16.36}$$

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This is a KL-divergence minimization step, but done w. exponential family models which thus corresponds to moment-matching.

Sources for Today's Lecture

 Wainwright and Jordan Graphical Models, Exponential Families, and Variational Inference http://www.nowpublishers.com/product. aspx?product=MAL&doi=2200000001